

Landslide identification using deep learning-based change detection and the DeepESDL collaborative cloud platform

Master Thesis developed at the Politecnico di Milano by Julia Leonardi under the supervision of Prof. Maria Antonia Brovelli and co-supervision of Dr. Vasil Yordanov and Dr. Valerio Marsocci *Objectives of the project*

- Investigate the possibilities of deep learningbased change detection workflows for landslide identification
 - Create a global landslide change detection training dataset with optical Sentinel-2 data
 - Apply different **change detection workflows** to compare their performances and explore the capabilities of **Deep Learning-based** workflows
- Assess the **usefulness of the DeepESDL** cloud collaborative platform for **machine** and **deep learning** applied to **earth observation research** use cases.

What tools were critical to the project

- The Sentinel Hub xcube data store cloud API. Retrieving the relevant patches of Sentinel-2 imagery by subsetting using the intuitive Python API request syntax was a great advantage when creating the dataset.
- The possibility of storage of the retrieved data. Thanks to which there was no need of downloading the heavy files to the PC, speeding up and easing the research process.
- Jupyter Lab environment with dependencies. Providing an intuitive data manipulation platform with all the important tools in place.

The outputs of the project

 Training dataset created within the DeepESDL platform and using the SH xcube data store cloud API (code snippet on the next slide). The dataset is published on Zenodo: https://zenodo.org/records/10800338

 Master Thesis with the result of the assessment of three change detection workflows
 (Differential Thresholding, Bitemporal Image Transformer Change Detection [BIT-CD], and Change Detection based on image Reconstruction

Loss [CDRL]). The text of the thesis is publicly available:

https://www.politesi.polimi.it/handle/10589/2180 42

• Code repository with the Notebooks developed on GitHub: <u>https://github.com/leonardijulia/MSc</u>

| | [3]: 1 | andslide_: | inventor | rу | | | | | | | |
|---|---------|---|--|---|---|---|--|---|---|---|---|
| | [3]: | event_ | _date a | ccuracy | category | latitude | e longitude | source | pre1 | prež | 2 post1 |
| | | 0 2022-1 | 11-26 | exact | mudslide | 40.737080 | 13.901270 | EMS | 2022-04-05 | 2022-04-12 | 2 2023-03-28 |
| landslide list = [] | | 1 2017-0 | 04-22 | exact | landslide | 3.055990 | 101.781120 | GLC | 2017-01-14 | 2017-02-03 | 3 2018-02-13 |
| ident = 0 | | 2 2017-0 | 05-20 | exact | landslide | 35.864314 | -121.430499 | GLC | 2017-04-20 | 2017-05-17 | 2017-05-27 |
| x = 0.01 | | 3 2017-0 | 05-26 | exact | landslide | 6.514224 | 80.169071 | GLC | 2017-01-31 | 2017-03-02 | 2 2017-07-15 |
| | | 4 2017-0 | 06-19 | exact | mudslide | 51.976862 | 2 -122.279271 | GLC | 2017-05-29 | 2017-06-0 | 5 2017-06-25 |
| <pre>for index, row in landslide_inventory.iterrows():</pre> | | | | | | | | | | - | |
| event_date = row.event_date | 1 | 69 2023-0 | 02-06 | exact | landslide | 36.750054 | 36.297924 | Tukey | 2022-09-07 | 2022-09-17 | 7 2023-05-25 |
| bbox = [row.longitude - x, row.latitude - x, row.longitude + x, row.latitude + x] | 1 | 70 2023-0 | 02-06 | exact | landslide | 36.842000 | 36.323500 | Tukey | 2022-09-07 | 2022-09-17 | 7 2023-05-25 |
| <pre>poly = box(bbox[0], bbox[1], bbox[2], bbox[3])</pre> | 1 | 71 2023-0 | 02-06 | exact | landslide | 37.004370 | 36.590910 | Tukey | 2022-09-07 | 2022-09-17 | 7 2023-02-24 |
| <pre>time_range_pre = (row.pre2, row.pre2)</pre> | 1 | 72 2017-0 | 05-11 | exact | landslide | 5.851690 | -75.921240 | UT | 2017-02-16 | 2017-03-28 | 3 2017-06-16 |
| <pre>time_range_post = (row.post1, row.post1)</pre> | 1 | 73 2018-0 | 02-15 | exact | landslide | 5.534380 | -75.225990 | UT | 2017-05-24 | 2017-07-13 | 3 2018-08-07 |
| | 17 | ′4 rows × 9 | e column | s | | | | | | | |
| <pre>dataset_pre = store.open_data('S2L2A',</pre> | | | | | | | | | | | |
| variable_names=['B01', 'B02', 'B03', 'B04', 'B05', 'B06', 'B07', 'B08', 'B8A', | ', 'B09 | Э', 'В | 11', | 'B1 | 2', 'C | | | | | | |
| bbox=bbox, | | | | | | | | | | | |
| spatial_res=0.00001, | | | | | | | | | | | |
| time_range=time_range_pre, | [26]. | landsli | de df | - nd D | ataEramo | landsli | de list) | | | | |
| time_period= ID , | [20]. | Tanasti | uc_ur · | - pu.b | | Tanasti | <u>uc_1130</u> / | | | | |
| (IIE_SIZE= [1024, 1024]) | [27]: | landsli | de_df | | | | | | | | |
| dataset nost - store open data('S2L2A' | [27]: | | | | | | T1 | | | | T2 |
| variable names=['B01' 'B02' 'B03' 'B04' 'B05' 'B06' 'B07' 'B08' 'B84' | | 0 (D) | 01 000 | DOD D (| | | 0.000 | 01 000 0 | DD 004 00 | | |
| bbox=bbox. | د | O [B(| 01, ВО2, | B03, BU | и, воз, во | 06, B07, B0 | 8, B09, [B | UT, BUZ, BU | ЈЗ, ВО4, ВО | 15, B06, B07 | , 808, 809, |
| spatial res=0.00001. | | 1 [B(| 01, B02, | B03, B0 |)4, B05, B0 |)6, B07, B0 | 8, B09, [B | 01, B02, B0 | 03, B04, B0 | 5, B06, B07 | , B08, B09, |
| time range=time range post, | | 2 [B0 | 01, B02, | B03, B0 | 04, B05, B0 | 06, <mark>B</mark> 07, B0 | 8, B09, [B | 01, B02, B | 03, B04, B0 | 5, B06, B07 | , B08, B09, |
| | | | 01 B02 | B03, B0 | 04, B05, B0 | 06, <mark>B</mark> 07, B0 | 8, B09, [B | 01, B02, B | 03, B04, B0 | 5, B06, B07 | , B08, B09, |
| time_period='1D', | | 3 [B0 | 01, 002, | |)4, B05, B0 |)6, <mark>B</mark> 07, B0 | 8, B09, [B | 01, B02, B | 03, B04, B0 | 5, B06, B07 | , B08, B09, |
| <pre>time_period='1D', tile_size= [1024, 1024])</pre> | | 3 [B0 | 01, B02, | B03, B0 | | | | | | | |
| time_period='1D', tile_size= [1024, 1024]) | | 3 [B0 4 [B0 | 01, B02, | B03, B0 | | | | | | | |
| <pre>time_period='1D', tile_size= [1024, 1024]) landslide_list.append(</pre> | | 3 [B(4 [B(| 01, B02, | B03, B0 | | | | | | | |
| <pre>time_period='1D', tile_size= [1024, 1024]) landslide_list.append({</pre> | | 3 [B(4 [B(169 [B(| 01, B02, 01, B02, 01, B02, | B03, B0 B03, B0 |)4, B05, B0 | 06, B07, B0 | 8, B09, [B | 01, B02, B | 03, B04, B0 | 5, B06, B07 | , B08, B09, |
| <pre>time_period='1D', tile_size= [1024, 1024]) landslide_list.append({ 'T1':dataset_pre,</pre> | | 3 [80 4 [80 169 [80 170 [80 | 01, B02, 01, B02, 01, B02, 01, B02, | B03, B0 B03, B0 B03, B0 | 04, B05, B0 04, B05, B0 |)6, B07, B0)6, B07, B0 | 8, B09, [B 8, B09, [B | 01, B02, B(01, B02, B(| 03, B04, B0 03, B04, B0 | 5, B06, B07 5, B06, B07 | , B08, B09, , B08, B09, |
| <pre>time_period='1D', tile_size= [1024, 1024]) landslide_list.append({</pre> | | 3 [80 4 [80 169 [80 170 [80 171 [80 | 01, B02, 01, B02, 01, B02, 01, B02, 01, B02, | B03, B0 B03, B0 B03, B0 B03, B0 |)4, B05, BC)4, B05, BC)4, B05, BC | 06, B07, B0 06, B07, B0 06, B07, B0 | 8, B09, [B 8, B09, [B 8, B09, [B | 01, B02, B(01, B02, B(01, B02, B(| 03, B04, B0 03, B04, B0 03, B04, B0 | 5, B06, B07 5, B06, B07 5, B06, B07 | , B08, B09, , B08, B09, , B08, B09, |
| <pre>time_period='1D', tile_size= [1024, 1024]) landslide_list.append({ 'T1':dataset_pre, 'T2':dataset_post, }</pre> | | 3 [80 4 [80 169 [80 170 [80 171 [80 | 01, B02, 01, B02, 01, B02, 01, B02, 01, B02, 01, B02, | B03, B0 B03, B0 B03, B0 B03, B0 B03, B0 |)4, B05, BC)4, B05, BC)4, B05, BC)4, B05, BC |)6, B07, B0)6, B07, B0)6, B07, B0)6, B07, B0 | 8, B09, [B 8, B09, [B 8, B09, [B 8, B09, [B | 01, B02, B(01, B02, B(01, B02, B(01, B02, B(| 03, B04, B0 03, B04, B0 03, B04, B0 03, B04, B0 | 15, B06, B07 15, B06, B07 15, B06, B07 15, B06, B07 | , B08, B09, , B08, B09, , B08, B09, , B08, B09, |
| <pre>time_period='1D', tile_size= [1024, 1024]) landslide_list_append({ 'T1':dataset_pre, 'T2':dataset_post, })</pre> | | 3 [80 4 [80 169 [80 170 [80 171 [80 172 [80 | 01, B02, 01, B02, 01, B02, 01, B02, 01, B02, 01, B02, 01, B02, | 803, 80 803, 80 803, 80 803, 80 803, 80 |)4, B05, B0)4, B05, B0)4, B05, B0)4, B05, B0 | 06, B07, B0 06, B07, B0 06, B07, B0 06, B07, B0 | 8, B09, [B 8, B09, [B 8, B09, [B 8, B09, [B | 01, B02, B0 01, B02, B0 01, B02, B0 01, B02, B0 01, B02, B0 | 03, B04, B0 03, B04, B0 03, B04, B0 03, B04, B0 | 5, B06, B07 5, B06, B07 5, B06, B07 5, B06, B07 | , B08, B09, , B08, B09, , B08, B09, , B08, B09, B08, B09 |
| <pre>time_period='1D', tile_size= [1024, 1024]) landslide_list_append({</pre> | | 3 [B0 4 [B0 169 [B0 170 [B0 171 [B0 172 [B0 173 [B0 | 01, B02, 01, B02, 01, B02, 01, B02, 01, B02, 01, B02, 01, B02, | 803, 80 803, 80 803, 80 803, 80 803, 80 |)4, B05, BC)4, B05, BC)4, B05, BC)4, B05, BC)4, B05, BC | 06, B07, B0 06, B07, B0 06, B07, B0 06, B07, B0 06, B07, B0 | 8, B09, [B 8, B09, [B 8, B09, [B 8, B09, [B | 01, B02, B(01, B02, B(01, B02, B(01, B02, B(01, B02, B(| 03, B04, B0 03, B04, B0 03, B04, B0 03, B04, B0 03, B04, B0 | 5, B06, B07 5, B06, B07 5, B06, B07 5, B06, B07 5, B06, B07 | , B08, B09, , B08, B09, , B08, B09, , B08, B09, , B08, B09, |

Additional Comments

- An issue that I found during the work using the DeepESDL platform was that there was **limited flexibility in terms of customizing the users' dependencies**. I believe that giving more freedom and **simplifying the process of installing and updating libraries** would benefit the research process.
- A more **in depth documentation of examples using the xcube** toolkit would also be a big advantage. I believe that xcube could be a state of the art framework for earth observation data used in machine and deep learning research, however still not much information and examples are available to propagate this technology.