

A Multisensory SAR-based approach for melt ponds retrievals

Summary of methodology performed and first main results using PolarTEP

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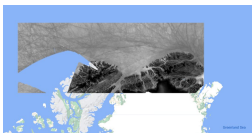
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Methodology 1: Preparation preparation of training datasets

1) Acquisition

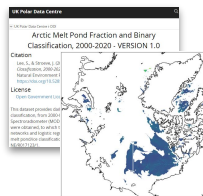
Sentinel-1

- Through EE
- Selected angles between 31 and 45 degrees
- Selected only HH band
- Daily average
- Over same area:



MPF (Lee et al.)

- Data acquired at ramadda.data.bas.ac.uk



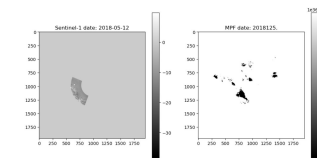
2) Processing

Reprojected to 'EPSG:6931'

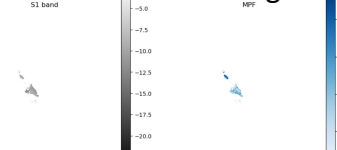
NetCDFs converted into GeoTIFFs using a Lambert Azimuthal Equal-Area Projection (EPSG 6931)

3) Stacking & Masking

- Aligning and stacking MPF file and S1 reprojected using GDAL commands for warping, followed by creating a VRT to combine them into a single entity
- Translating them into a GeoTIFF (COG) format

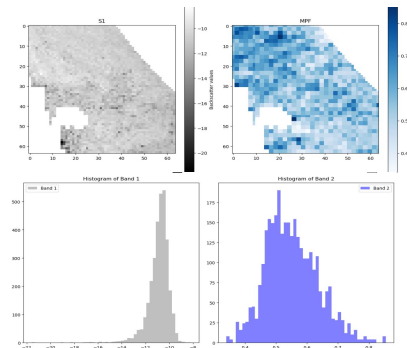


- Masking invalid values ($9.969e+36$) (NaN) in each band, creating a new binary band indicating where the S1 is valid
- Stack masked bands together



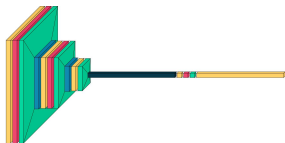
4) Cropping into patches

- Every COG is divided into tiles of 64 by 64 and saved as a separate TIFF. If all pixels in a tile are either all NaN or all Zero, that tile/patch is not save.



Methodology 2: Preparation 3 different AI workflows: CNN, UNET and SegNET

CNN



Consists of convolutional layers followed by pooling layers and fully connected layers.

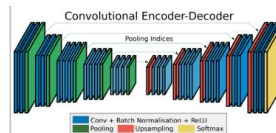
Pros:

- Effective in capturing spatial hierarchies in data due to the use of convolutional layers.
- Automatically learns hierarchical patterns from the input data.
- Suitable for a variety of tasks such as image classification, object detection, and segmentation.

Cons:

- Requires a large amount of data for training, which can be computationally expensive.
- Prone to overfitting, especially with complex architectures and insufficient data augmentation.
- Interpretability might be challenging due to the complexity of the learned features.

SegNET



Employs an encoder-decoder architecture with skip connections. Utilizes skip connections to retain spatial information during decoding.

Pros:

- Utilizes a hierarchical encoder-decoder architecture which enables capturing fine details.
- Incorporates skip connections to retain spatial information during the decoding process.
- Effective for tasks like image segmentation where preserving spatial information is crucial.

Cons:

- May suffer from vanishing gradients during training, especially in deeper architectures.
- Requires careful tuning of hyperparameters and architecture design to prevent overfitting.
- Computationally intensive due to the use of multiple convolutional layers and upsampling operations.

U-NET



Features a U-shaped architecture with symmetric encoder and decoder paths. Incorporates skip connections to facilitate feature propagation and precise localization.

Pros:

- Incorporates a U-shaped architecture with symmetric encoder-decoder paths, facilitating better feature propagation.
- Enables precise localization of objects due to skip connections that preserve spatial information.
- Widely used and proven effective for medical image segmentation and other tasks requiring precise delineation.

Cons:

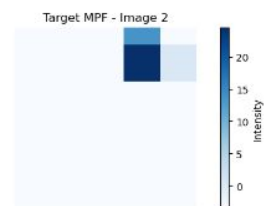
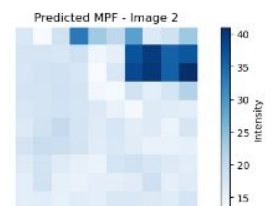
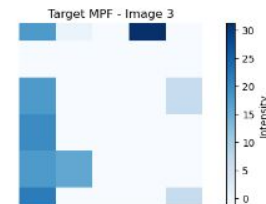
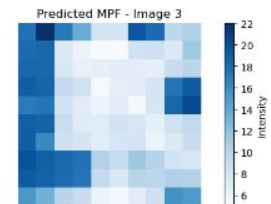
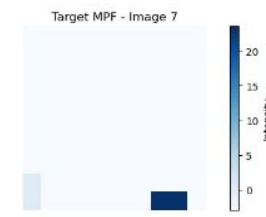
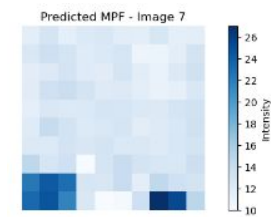
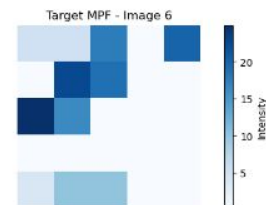
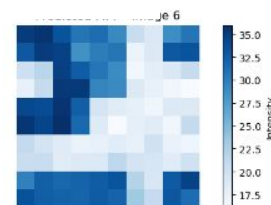
- Can be memory-intensive, especially for larger input sizes and deeper architectures.
- Training can be slow due to the large number of parameters, especially in the bottleneck layers.
- May struggle with class imbalance if not properly addressed during training.

Results 1: OLCI ISTOMINA-dataset

10 x 10 input image
38054 instances



CNN

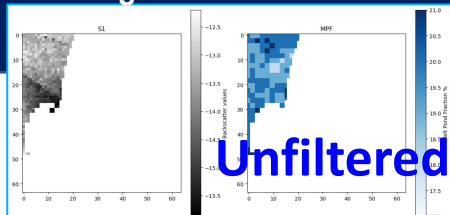


Loss and metrics	Loss: MSE Metric: MAE
NaN handling	X =0
CNN	Model A
Epochs	25
Normalization	no data normalization
Results	<p>Model evaluation is [38.27766418457031, 4.0326619148254395]</p> <p>The graph shows the training and validation loss and MAE over 25 epochs. The x-axis represents the epoch number from 0 to 25. The y-axis represents the loss and MAE values from 0 to 50. The training loss (blue line) starts at approximately 48 and decreases to about 34. The validation loss (green line) starts at approximately 45 and fluctuates between 40 and 45. The training MAE (orange line) starts at approximately 5 and remains relatively stable around 5. The validation MAE (red line) starts at approximately 4 and remains relatively stable around 4.</p>

Results 2: OLCI ISTOMINA-dataset

First trials with UNET

64 x 64 input image
2862 instances



Loss and metrics	Loss: MSE Metric: MAE
NaN handling	X[nan] = 0 images with NaNs
CNN	SegNet 1
Epochs	15
Normalization	without normalization
Results	loss: 10.1952

