



# From model simulations towards vegetation properties mapping:

# automating, optimizing & expanding



Jochem Verrelst

20/09/2023

### How to quantify vegetation properties?



#### *Today we will learn:* Semi-automated mapping of vegetation properties from optical RS data



### The problem:

Biophysical parameter retrieval is an essential step in modeling the processes occurring on Earth and the interactions with the atmosphere.

The analysis can be done at **local** or **global** scales by looking at bio-geochemical cycles, atmospheric situations, ocean/river/ice states, and vegetation dynamics.

Main parameters: crop yield, biomass, leaf area coverage, chlorophyll content, fraction vegetation cover, GPP,....

Land/vegetation parameters cannot be estimated directly from optical **RS data. A model is required!** 

**The objective:** Transform measurements into biophysical parameter estimates.

#### The data:

- **Input data:** satellite/airborne spectra, in situ (field) radiometers, or • simulated spectra by RTMs
- **Output results:** estimation of a biophysical parameter









eaf Area Index

### **Introduction retrieval biophysical parameters**



Statistical approaches

Retrieval of biophysical parameters from Remote Sensing (RS) data **always occurs through a model**, e.g. through statistical models or through inversion of physically-based radiative transfer models (RTM).

Physically based RTM approaches





### Some retrieval methods....



Verrelst, J et al. (2019). Quantifying vegetation biophysical variables from imaging spectroscopy data: a review on retrieval methods. Surveys in Geophysics, 40(3), 589-629. 6/59

## **Retrieval of (continuous) vegetation properties**

#### Remote sensing image

Map of a vegetation property



### 1. Statistical models

- 1. Parametric regression models
- 2. Nonparametric regression models
  - 1. Linear
  - 2. Nonlinear
- 2. Inversion of physically based radiative transfer models
  - 1. Numerical optimization
  - 2. Lookup-table (LUT)-based inversion

### Taxonomy of retrieval methods, three main families:

- 1. Statistical: parametric and non-parametric:
  - Parametric models rely on some physical knowledge of the problem and build explicit parametrized expressions that relate a few spectral bands with the biophysical parameter(s) of interest.
  - Non-parametric models are *data-driven* models. They are adjusted to predict a variable of interest using a training dataset of input-output data pairs.
- 2. Physical: try to reverse RTMs.
  - Physically based algorithms are applications of physical laws establishing photon interaction *cause–effect relationships*. Model variables are inferred based on specific knowledge, typically obtained with radiative transfer functions.
- 3. Hybrid:
  - A hybrid-method combines elements of nonparametric statistics and physically based methods. Hybrid models rely on the generic properties of physically based methods combined with the flexibility and computational efficiency of nonparametric nonlinear regression methods.









# **Retrieval families**



#### Methods of these different families can be combined: hybrid methods



# **Statistical interpretation of RS**

Remote Sensing Data

**Statistical relationship** 

- Parametric regression
- Non-parametric regression

Variable of Interest



- Simple statistical relationships (VIs) constitute the **BULK of RS analysis**.
- These analyses allow to determine IF there is a relationship, not WHY there is a relationship.
- Linear methods such as VIs are **useful indicators** of biophysical (e.g. structure) or biochemical (e.g. chlorophyll) parameters, however in natural, complex environments indices are **confounded** by additional abiotic and biotic factors.
- VIs lack generality for estimating biophysical parameters.
- Apart from VIs a large number of powerful **alternative statistical retrieval** methods exists (e.g. non-parametric regression methods).

# **Parametric regression**

### Parametric regression assume an explicit model for retrieval

- Discrete band methods(VIs):
  - 2-band: SR, NDVI, PRI, OSAVI
  - 3-band: TVI, MCARI, SIPI
  - 4-band: TCARI/OSAVI



- Shape-based methods (hyperspectral data):
  - Red-edge position (REP)
  - Derivative/Integral indices
  - Continuum removal
  - wavelet



## **Parametric regression:**



#### Strengths 🕲

- Simple and comprehensive regression models; little knowledge of user required.
- Fast in processing
- Computationally inexpensive

#### Weaknesses 🛞

- Makes only poorly use of the available information within the spectral observation; at most a spectral subset is used. Therefore, they tend to be more noisesensitive as compared to full-spectrum methods
- Parametric regression puts boundary conditions at the level of chosen bands, formulations and regression function.
- Statistical function accounts for one variable at a time.
- A limited portability to different measurement conditions or sensor characteristics
- No uncertainty estimates are provided. Hence the quality of the output maps remains unknown.



# **Parametric regression**



## Non-parametric models (1/2):

Data-driven methods: Do not assume explicit feature relations

### Linear nonparametric models:

- Stepwise multiple linear regression (SMLR)
- Principal component regression (PCR)
- Partial least squares regression (PLSR)
- Ridge regression (RR)
- Least Absolute Shrinkage and Selection Operator (LASSO)



# Non-parametric models (2/2):

Data-driven methods: Do not assume explicit feature relations

### Non-linear nonparametric models:

Decision Trees (DT)



Neural networks (NN)



#### Also:

- Elastic Net (ELASTICNET)
- Bagging trees (BAGTREE)
- Boosting trees (BOOST)
- Neural networks (NN)

# Support vector regression (SVR)

Kernel ridge regression (KRR)



 $K(\mathbf{x}_i, \mathbf{x}_j) = \exp(-\|\mathbf{x}_i - \mathbf{x}_j\|^2 / (2\sigma^2)).$ 

- Extreme Learning Machines (ELM)
- Relevance Vector Machine (RVM)
- Gaussian process Regression (GPR)
- Variational Heteroscedastic Gaussian Process Regression (VHGPR)





# **Gaussian Processes Regression (GPR)**

- A **GPR** model is a **probabilistic** (**Bayesian**) model directly in function space, with no intermediate model or model parameters.
- GPR are equivalent to kernel ridge regression, least square suport vector machines (SVM), Kriging, large neural networks (NN) and very closely related to SVM regulazation networks.
- **GPR alleviates** some **shortcomings** of the previous methods, while maintaining very good numerical performance and stability:
  - GPR is far simpler than NN, and needs fewer sample points (2)
  - Not only a mean prediction for each sample (pixel), but also a full distribution over the output values including an uncertainty of the prediction (confidence interval).
  - GPR provide a ranking of features (bands) and samples (spectra), thus partly overcoming the blackbox problem. <sup>(C)</sup>
  - <u>http://www.rainsoft.de/projects/gausspro.html</u>



A regression curve plot by the "Gaussian Process Regression Applet" using 11 data points. One can observe that uncertainty goes down when multiple data points are aggregated together.



# **Non-parametric regression:**

#### Strengths 🙂

- Full-spectrum methods. They make use of the complete spectral information.
- Advanced, adaptive (non-linear) models are built.
- Methodologically, accurate and robust performance is enabled.
- Some MLRAs cope well with datasets showing redundancy and high noise levels.
- Once trained, imagery can be processed time efficient.
- Some of the non-parametric methods (e.g. ANNs, decision trees) can be trained with a high number of samples (typically >1,000,000).
- Some MLRAs provide insight in model development (e.g. GPR: relevant bands; decision trees: model structure).
- Some MLRAs can provide multiple-outputs (e.g. PLRS, ANN, SVR, GPR and KRR)

#### Weaknesses 🛞

- Training can be computational expensive.
- Hypercomplex models can be generated. Their generic potential is limited and hence they do not generalize well, based on the training data (problem of over-fitting).
- Some regression algorithms are difficult (or even impossible) to train with a high number of samples.
- Expert knowledge is required, e.g. for tuning. However, toolboxes exist automating some of the steps in this sub-process.
- Some of the methods can be considered as black boxes.
- Some regression algorithms elicit instability when applied with datasets statistically deviating from the datasets used for training.

• Some MLRAs provide uncertainty intervals (e.g. GPR).

# **Non-parametric regression**

COOKBOOK



# **Physical interpretation of RS**



#### Radiative transfer models:

- Try to predict RS data based on a function of the **RT** state variables
- Two categories of RT models:
  - **Economically invertible models:**



typically designed for simple scenes, have a few number of state variables (e.g. SAIL, RPV)







# Background



# **Radiative transfer models**

#### Leaf RT models





J



#### **Canopy RT models**







### Multiple models exist with diverse complexity.

# Leaf optical models

- A leaf is not opaque but transparent.
- Leaf as composed out of layers and empty spaces







http://rami-benchmark.jrc.ec.europa.eu

Examples of canopy RTMs(1/4)

### SAIL model (Verhoef 1984): a 1-D model



### Examples of canopy RTMs (2/4)

Canopy models can be coupled with leaf, soil and atmospheric models



### *Examples of canopy RTMs (3/4)* Ray tracing models

Drat -the aDvanced Radiometric Ray Tracer.

P. Lewis, 1999; Saich et al., 2001. University College, Dept. Geography, London

Vegetation is built using The Botanical Plant Modelling System (BPMS) BPMS is a form of L-systems - the branches of a tree as geometric primitives

ARARAT - the advanced radiometric ray tracer, reverce ray tracing, a variety of camera models implemented



(Dürer, 1525)







### Examples of canopy RTMs (4/4)

### FLIGHT (North, 1996): A 3-D model

FLIGHT MC ray tracing approach

- Large scale structure by geometric primitives (e.g. cone)
- Foliage within crowns described by volume-averaged parameters
- 3D photon trajectories are simulated, accounting for the probabilities of free path, absorption and scattering
- Individual photon trajectories are traced from a solar source, through successive interactions, to a predetermined sensor view angle.





### **Biophysical parameters retrieval through RTM inversion:**





# **LUT-based RTM inversion**



## LUT-based inversion:

#### Strengths © Weaknesses 🛞 **Full-spectrum methods Computationally demanding** due to the per-pixel Reputation of physically-based (however, note information have been developed). the impact of regularization factors) Generally and globally applicable (e.g. MODIS

- products).
- Capability to provide multiple outputs
- Yields additional information about **uncertainty** of the retrievals (e.g. residuals).

- based approach (however, solutions based on a priori
- Retrieval quality depends on the quality of the RT **mo**dels, prior knowledge and regularization.
- Quite complex approach: requires parameterization and optimization procedures.
- The imposed upper/lower boundaries in the LUT have a logical consequence in that estimated variables cannot go beyond the boundaries imposed. This contradicts somewhat the physical approach as the prior information has an overwhelming influence.
- LUT-based inversion methods are often strongly affected by noise and measurement uncertainty.

# **Hybrid retrieval**

COOKBOOK



# **Non-parametric regression: hybrid**

#### Strengths 🙂

- Full-spectrum methods. They make use of the complete spectral information.
- Advanced, adaptive (non-linear) models are built.
- Methodologically, accurate and robust performance is enabled.
- Some MLRAs cope well with datasets showing redundancy and high noise levels.
- Once trained, imagery can be processed time efficient.
- Some of the non-parametric methods (e.g. ANNs, decision trees) can be trained with a high number of samples (typically >1,000,000).
- Some MLRAs provide insight in model development (e.g. GPR: relevant bands; decision trees: model structure).
- Some MLRAs can provide multiple-outputs (e.g. PLRS, ANN, SVR, GPR and KRR)

#### Weaknesses 🛞

- Training can be computational expensive.
- Hypercomplex models can be generated. Their generic potential is limited and hence they do not generalize well, based on the training data (problem of over-fitting).
- Some regression algorithms are difficult (or even impossible) to train with a high number of samples.
- Expert knowledge is required, e.g. for tuning. However, toolboxes exist automating some of the steps in this sub-process.
- Some of the methods can be considered as black boxes.
- Some regression algorithms elicit instability when applied with datasets statistically deviating from the datasets used for training.

• Some MLRAs provide uncertainty intervals (e.g. GPR).

# Summary mapping methods

Parametric regression

	LAI
Calibration & ValidationVegetation indicesFitting functionShape indices(e.g. linear regression)	
Training & Validation          All bands         Band selection or VIs    Non-parametri regression	

Non-parametric regression



Hybrid

regression



Transformation (e.g. PCA)



Ω

Verrelst, J., Malenovský, Z., Van der Tol, C., Camps-Valls, G., Gastellu-Etchegory, J.P., Lewis, P., Moreno, J. (2018). Quantifying Vegetation Biophysical Variables from Imaging Spectroscopy Data: A Review on Retrieval Methods. Surveys in Geophysics,

# **Taxonomy retrieval methods**



# **Optimizing retrieval**



ARTMO automates retrieval optimization





RTMs are important tools in EO research but for the broader community these models are perceived as complicated. Only very few of them offer user-friendly interfaces (GUIs).



Only very few offer a GUI.

- No interface exists that brings multiple RTMs together in one GUI.
- None of existing (publicly available) GUIs provide post-processing tools.

# To fill up this gap:



### > To develop a GUI toolbox that:

- operates various RTMs in an intuitive interface
- provides a comprehensive visualization of model outputs
- works both for **multispectral and hyperspectral** data
- enables to retrieve biophysical parameters through various retrieval methods
- takes different land cover classes into account.

# **Toolbox for EO applications:**



# Selection RTMs & programming language

#### language

#### Accessibility

Model	Reference	Source code
PROSPECT-4	Feret et al., 2008	Matlab
PROSPECT-5	Feret et al., 2008	Matlab
PROSPECT-D	Feret et al., 2017	Matlab
DLM	Stuckens et al., 2009	Matlab
LIBERTY	Dawson et al., 1998	Matlab
FLUSPECT	Vilfan et al., 2016	Matlab
4SAIL	Verhoef et al., 2007	Matlab
FLIGHT	North, 1996	Executable file
INFORM	Atzberger, 2000	Matlab
SCOPE	Van der Tol et al., 2009	Matlab

### **Software packages:**

Programming language:Matlab®Database:MySQL®Image processing software:ENVI®





# ARTMO v. 3.31



承 ARTMO [v. 3.31]					_	×
File Models Forward Retriev	al Classification	Tools I	Help	Plugins		ъ
Project Description						
Project Name:						
Comment:						
Sensor: NO SENSOF	8					~
DB: ua2023						





# **ARTMO's retrieval toolboxes:**

### **LUT-based inversion toolbox**

💽 LUT	-based Inve	rsion Toolbo	x [v. 1.13]			
Input	Settings	Validation	Retrieval	Tools	Help	ч



### Machine learning regression algorithm toolbox (MLRA)

🔺 MLF	A Toolbox	[v. 1.23]				x
Input	Settings	Validation	Retrieval	Tools	Help	Ľ



### **Spectral indices toolbox**







Contents lists available at ScienceDirect

ISPRS Journal of Photogrammetry and Remote Sensing

journal homepage: www.elsevier.com/locate/isprsjprs

### Experimental Sentinel-2 LAI estimation using parametric,

non-parametric and physical retrieval methods - A comparison

VI

Jochem Verrelst<sup>a,\*</sup>, Juan Pablo Rivera<sup>a</sup>, Frank Veroustraete<sup>b</sup>, Jordi Muñoz-Marí<sup>a</sup>, Jan G.P.W. Clevers<sup>c</sup>, Gustau Camps-Valls<sup>a</sup>, José Moreno<sup>a</sup>

<sup>a</sup> Image Processing Laboratory (IPL), Universitat de València, València, Spain <sup>b</sup>Department of Bioscience Engineering, Faculty of Sciences, University of Antwerp, Antwerp, Belgium <sup>c</sup>Laboratory of Geo-information Science and Remote Sensing, Wageningen University, Wageningen, The Netherlands



#### Table 9

Best performing parametric, non-parametric and LUT-based inversion method and associated mapping speed.

Retrieval algorithm	RMSE	$R^2$	Mapping speed (s)
Tian 3-band formulation	0.615	0.823	3.847
VH-GPR	0.436	0.902	73.884
Pearson chi-square inversion	0.802	0.745	3706.965



RGB HyMap

0 1 2 3 4 5 LAI  $[m^2/m^2]$ 



LAI ( $\mu$ ) [m<sup>2</sup>/m<sup>2</sup>]



**GPR** 



% CV





Residues 45/59



# **Operational processing?**



Characteristic	Parametric	Non- parametric	RTM-based	Hybrid
Generalization capacity		-	++	++
Mapping Speed	++	+		+
Uncertainties		++*	+	++*
Accuracy	+	++	+	++
Variables	++	++	+	+

\* Some machine learning methods (e.g. probabilistic or ensemble methods)

### **CHIME: Copernicus Hyperspectral Imaging Mission**

CHIME will carry a visible to shortwave infrared spectrometer to provide global routine hyperspectral observations. The mission will support new and enhanced services for sustainable agricultural and biodiversity management, as well as soil property characterisation.

### **Technical concept:**

Routine spectroscopic observation in contiguous spectral bands:

- Instrument: Pushbroom Imaging Spectrometer 400 – 2500 nm, Δλ
   <= 10nm</li>
- Revisit 10 15 days
- GSD (spatial resolution): 30 m
- Sun synchronous orbit (LTDN 10:30 11:30)
- Nadir view covering land and coastal areas
- High radiometric accuracy, low spectral/spatial misregistration





### **CORE Data Products:**

The mission shall provide access to Level-1B, Level-1C and Level-2A products accessible via DIAS and with API support:

- Bottom-of-Atmosphere (BOA) reflectance (atmospherically corrected)
- Ortho rectified geometry
- Basic pixel classification (opaque clouds, thin clouds, cloud shadows, vegetation, water, snow etc.)
- Additionally –>
   Vegetation products (Level-2B)



Many factors play a role. Spectral variability: quantity & quality & applied ML algorithm



Rivera-Caicedo, J. P., Verrelst, J., Muñoz-Marí, J., Camps-Valls, G., & Moreno, J. (2017). Hyperspectral dimensionality reduction for biophysical variable statistical retrieval. ISPRS journal of photogrammetry and remote sensing, 132, 88-101.



Verrelst, J., Berger, K., & Rivera-Caicedo, J. P. (2020). Intelligent sampling for vegetation nitrogen mapping based on hybrid machine learning algorithms. *IEEE Geoscience and* **48/59** *Remote Sensing Letters*, 18(12), 2038-2042.

### Workflow CHIME vegetation traits models:



Use RTMs (e.g. PROSPECT-PRO -

SAIL) to generate a LUT composed

by pairs (e.g. 1000) of vegetation

parameters and spectra.

#### **Active learning**

Select the most representative

samples from the training dataset

via a **diversity** or entropy criteria.

Later, add non-vegetated spectra.

CHIME-like data

PCA



PCA2 PCA1

Okay?

Dimensionality reduction with **PCA** (20 components).

#### **Train GPR algorithms**



With the **LUT optimized** for vegetation and non-vegetated surfaces, train probabilistic ML algorithms.

Maps + uncertainties



Final outputs of the workflow.

#### Apply to new observations

ARTMO



PRISMA images resampled to CHIME band settings

#### Validate the models



Assess models' performance against field data and vegetation reference scenes.



Verification and Validation vegetation models through E2E using

Page. 35

### CNC estimates in [g/m<sup>2</sup>]



Verrelst, J., Rivera-Caicedo, J. P., Reyes-Muñoz, P., Morata, M., Amin, E., Tagliabue, G., ... & Berger, K. (2021). Mapping landscape canopy nitrogen content from space using PRISMA data Jopps Journal of Photogrammetry and Remote Sensing, 178, 382-395.

### Relative uncertainties in [%]: used as mask (e.g. only ≤20%)



#### **Conclusions CNC study:**

- A workflow for operational mapping of CNC designed for spaceborne imaging spectroscopy missions
- Hybrid method based on PROSAIL-PRO and GPR
- GPR provides associated uncertainty estimates
- Model applied to PRISMA and succesfully validated

# **ARTMO's tools:**

K Sensor Module [v. 1.06]

# Sensor & spectral resample:

Sentinel-2						👻 🔳 S	pectral filter	SNR
Unit wavelength		Band	details					
Micrometers	^		Band name	Min	Max	Center	FWHM	SNR
Wavenumber		1	Band1	433	453	443	20	129
GHz		2	Band2	457.5000	522.5000	490	65	154
MHz		3	Band3	542.5000	577.5000	560	35	168
Index		4	Band4	650	680	665	30	142
Unknown		5	Band5	697.5000	712.5000	705	15	117
	Ŧ	6	Band6	732.5000	747.5000	740	15	89
		7	Band7	773	793	783	20	105
		8	Band8	784.5000	899.5000	842	115	174
		0	Band8a	855	875	865	20	72

Option t	D:Uocher	n\Google Dr	ive\ARTMO_tu	torial/ARTM	O\data\CH	RIS\SPA	RC_200	13_29bare	Browser	onvert factor	
Tab	-		HeaderLines		pose	Select	targets		All Non		
				OK	(					Unit w	vaveleng
01234567	891011121314	181920212224 454847484950	2526272829303	13233		1	Select	Colu Ce	de	Micro	meters
3846566	676889707172	737475767778	79808182838485	5888990		1	12	1		- Ward	number
91929394	959697989910	010110210310	4105106107108	109110116		2			-	GHz	TOTTION I
11711811	912012112151	519242632146	9101115182025	2636124671618	81920	3	2	4	2	MHz	
8.61442	52543.36938.7	5747.4144444	14444444444444444	444444444					3	Index	
444422.8	62020202023	39320.1292015	5.59417.5452022	217202014.5		6			6	Unkno	wn
14.514.51	4.514.514.520.	4514.99812.45	110.96514.514.5	14.514.535.5		2		7	9		
48,548,54	8 548 548 548 1	535.534.354.96 548.548.548.54	1230.030.030.030.1	48,548,548,5			121		7	*	
2.891.861	6722 12 10000	000000000000	000000000000000000000000000000000000000			Selec	r Senso	Centinel 1			
03.843.09	3.023.943.612.		3.223.7432.74.13	13.183.97							
3.564.524	264.7742.362.	261.851.631.90	22.881.411.342.4	12.11.841.58		Rando	m subse	rt [%]	📃 Add sp	ectral noise	OK
	1	2	3	4	5	6		7	8	9	10
1	0	1	2	3	4		5	6	7	8	
2	0	49.7990	51,6330	50.3810	51		51	51	51	51	5
3	0	3.8400	3.0900	3.0200	3.9400	3	6100	2.8700	3.7100	3	
4	0	0.6300	0.6300	0.6300	0.6300	0	6300	0.6300	0.6300	0.7300	0.820
5	0	179.8000	179.8000	179.8000	179,8000	179	8000	179.8000	179.8000	179.8000	179.800
6	0	0.6000	0.6000	0.6000	0.6000	0	6000	0.6000	0.6000	0.7000	0.800
7	410.5600	357	297	355	325		477	397	385	325	33
8	441.3700	346	382	400	357		542	430	389	357	34
	101 0100	0.00	000	100	947		674	422	414	0.07	
9	401.2400	300	382	+00			5/1	432		-307	36

### **Emulation:**

EMU	LATOR Too	olbox [v. 1.11	]			Л	Tra Multiple input	aining data	Validation data	a) Spectral
Input	Settings	Validation	Emulator	Tools	Help 🏻		variables (e.g.	Single output MLRAs + PCA	r Multi-output MLRAs	output (e.g. reflectance)
configuration module (v. 1.08) Map E: (PROSPECT4_1000 E: Sate	v Same	- X				J		Valida	ation	enulated hyperspec
¢ V	Verault NO SENSOR	Variable min I: Leaf Structural P ab: Chlorophyll a+	100		PROSAIL		10	00	PROINFOR	M

### Global sensitivity analysis:

GSA type:	Satelli					<ul> <li>subsamples:</li> </ul>	1000
RT model				Sen	sor		
Prospect 4		~	Default	NO	SENSOR		
- RTM input	settings						
Group					Select	Variable	mi
Leaf			~	1		N: Leaf Structura	IP
Variable				2		Cab: Chlorophyll	a+
N: Leaf Stru	ctural Para	malar	~	3		Cw: Equivalent w	/at 1.00
Extremal V	ariables			4		Cm: Dry matter	con 1.00
Empty			$\sim$				
Range	max	Distribution			٢		
min		Sobol	~			Delete selected	Delete all
min 1	4						
min 1	4	Add varial	ble				
RTM outp	4 V All	Add varial	bie				
RTM outp Group	4 All uts	Add variat	bie	Se	lect	RTM output	G
RTM outp Group Leaf	4 All uts	Add variat	bie dia	Se 1	lect Z Ref	RTM output lectance of the I.	G Leaf

PROSAIL

600 800 1000 1200 1400 1600 1800 2000 2200 2400

Wavelength [nm]

otal SI [%]

400



 $\square$ N  $\blacksquare$ Cab  $\blacksquare$ Cw  $\blacksquare$ Cm  $\blacksquare$ LAI  $\blacksquare$ LAIs  $\blacksquare$ LAD  $\square$ LAIu  $\blacksquare$ SD  $\blacksquare$ H  $\blacksquare$ CD  $\blacksquare$ SZA  $\blacksquare$   $\rho_s$ 



Dr. Santiago Belda Palazón Dr. Jochem Verrelst Dr. Juan Pablo Rivera Dr. Luca Pipia Pablo Morcillo



#### Sliding window: 1 years, Step: 1 month



Belda, S., Pipia, L., Morcillo-Pallarés, P., Rivera-Caicedo, J. P., Amin, E., De Grave, C., & Verrelst, J. (2020). DATimeS: A machine learning time series GUI toolbox for gap-filling and vegetation phenology trends detection. *Environmental Modelling & Software*, *127*, 104666. 53/59

# MLCA Classification toolbox - v.1.1





# WHAT IS ALG?

#### ATMOSPHERIC LOOK-UP TABLE GENERATOR (ALG)

ALG is a software tool that facilitates generating large databases for a variety of atmospheric Radiative Transfer Models (RTM). ALG allows consistent and intuitive user interaction to enable configuration and execution of model simulations, storing RTM data for any spectral configuration in the optical domain.

வ AtmLutGen File Tools Help Load LUT Run Package configuration simulations LUT Aerosol Atmosphere toolkit generator RAMI ATM Aeronet and Satellite RAMI4ATM Radiosondes simulator o Emulation Settings tool jorviser@gmail.com



×



ALG v3.2 (Jul. 2022) Copyright (C) Univ. of Valencia

#### MODTRAN

www.modtran.spectral.com Based on the DISORT solver and a modelization of gas absorptions by the kcorrelation method. Spectral range and resolution: UV to TIR at 0.1 cm-1

#### 6SV

salsa.umd.edu/6spage.html

Based on the SOS solver with polarization and decoupled scattering and absorption. Spectral range and resolution: VIS to SWIR at 2.5 nm

#### libRadtran

http://libradtran.org

Collection of functions and programs for calculation of solar and thermal radiation in the Earth's atmosphere. libRadtran is freely available under the GNU General Public License.

#### ARTDECO

#### www.icare.univlille.fr/artdeco/

Tool that gathers several models and data for the simulation of radiances and fluxes observed by passive sensors (no hyperspectral) in the UV to **TIR** range



Estévez, J., Salinero-Delgado, M., Berger, K., Pipia, L., Rivera-Caicedo, J. P., Wocher, M., ... & Verrelst, J. (2022). Gaussian processes retrieval of crop traits in Google Earth Engine based on Sentinel-2 top-of-atmosphere data. *Remote Sensing of Environment*, 273, 112958. 56/59

# GEE





https://github.com/SentiFLEXinel



