

RUS

Copernicus



TRAINING KIT – LAND01

**CROP MAPPING WITH SENTINEL-2
JULY 2017, SPAIN**



Research and User Support for Sentinel Core Products

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Authors would be glad to receive your feedback or suggestions and to know how this material was used. Please, contact us on training@rus-copernicus.eu

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1 Introduction to RUS

The Research and User Support for Sentinel core products (RUS) service provides a free and open scalable platform in a powerful computing environment, hosting a suite of open source toolboxes pre-installed on virtual machines, to handle and process data derived from the Copernicus Sentinel satellites constellation.

In this tutorial we will employ RUS to identify and map different crops in an agricultural area near Seville (Spain) using Sentinel-2 satellite-borne optical data.

2 Crop mapping – background



Aerial view of the Guadalquivir marshes area.

The Guadalquivir Marshes represent one of the last territories occupied by man in the Spain's region of Andalucía. Settlements were not definitive until the 1940 decade, when the expansion of agriculture, especially rice, led a complete transformation of the area. Nowadays, 35.000 ha are used to grow rice with an average production rate of 8.500-10.000 kg/ha. Other crops such as wheat, cotton, sugar beet, or sunflower can be found as well.

Reliable information on crops is required to improve agricultural management and reduce the environmental impact of this activity. Different methods can be used to gather this information but satellite earth observation techniques offer a suitable approach based on the coverage and type of data that are provided. The imagery data from Sentinel satellites enables a new approach for agriculture monitoring. The combination of their temporal, spatial, and spectral resolutions together with relevant analysis can lead to improvements of the decision-making process.

3 Training

Approximate duration of this training session is one hour.

The Training Code for this tutorial is **LAND01. If you wish to practice the exercise described below within the RUS Virtual Environment, register on the [RUS portal](#) and open a User Service request from Your RUS service > Your dashboard.**

3.1 Data used

- One Sentinel-2A level 2A image acquire on 01 June 2017 [downloadable at @ <https://scihub.copernicus.eu/>]

S2A_MSIL2A_20170601T110651_N0205_R137_T30STG_20170601T111225

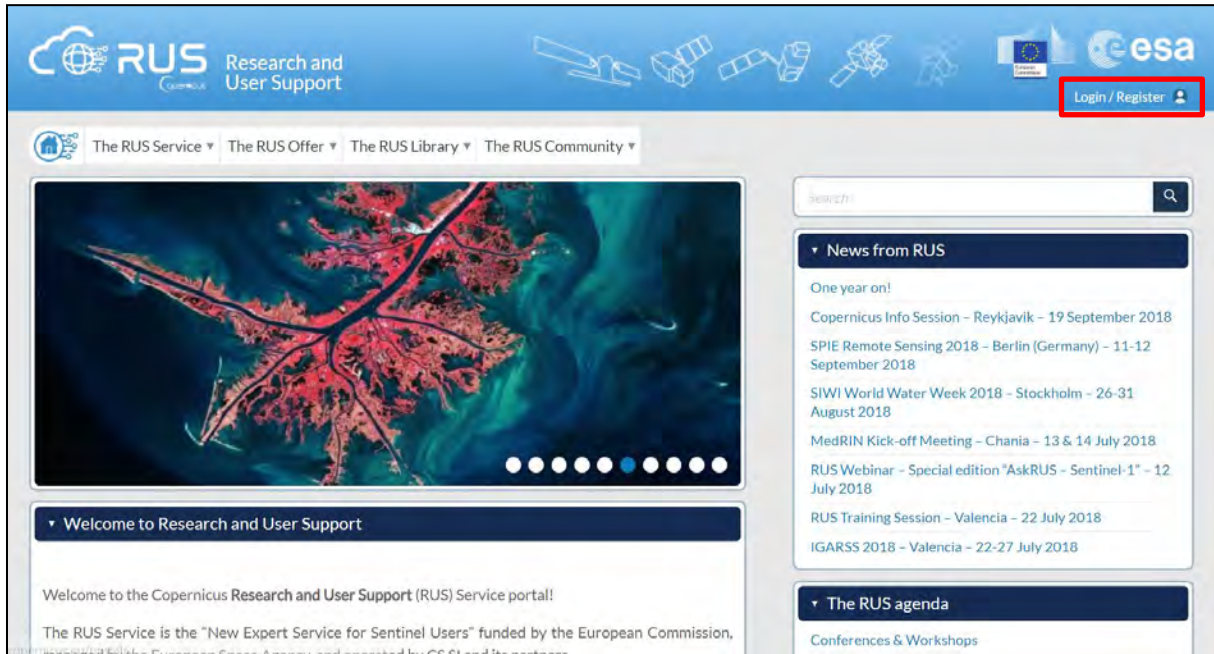
- Pre-processed data stored locally
@/shared/Training/LAND01_CropMapping_Seville/AuxData/

3.2 Software in RUS environment

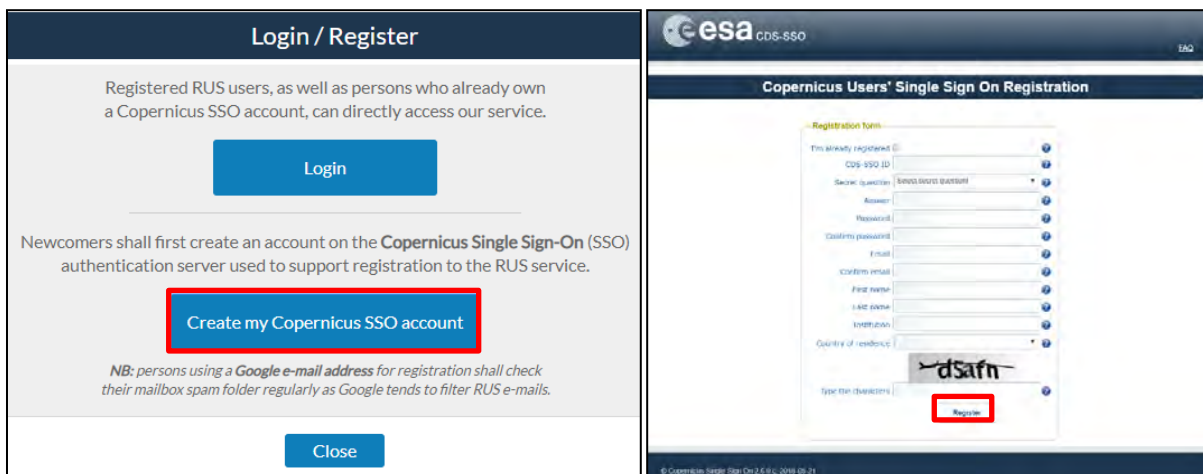
Internet browser, SNAP + Sentinel-2 Toolbox + QGIS

4 Register to RUS Copernicus

To repeat the exercise using a RUS Copernicus Virtual Machine (VM), you will first have to register as a RUS user. For that, go to the RUS Copernicus website (www.rus-copernicus.eu) and click on **Login/Register** in the upper right corner.



Select the option **Create my Copernicus SSO account** and then fill in ALL the fields on the **Copernicus Users' Single Sign On Registration**. Click **Register**.



Within a few minutes you will receive an e-mail with activation link. Follow the instructions in the e-mail to activate your account.

You can now return to <https://rus-copernicus.eu/>, click on **Login/Register**, choose **Login** and enter your chosen credentials.

Login / Register

The registration system to access the RUS service platform has moved toward the COPERNICUS Single Sign On authentication server.

- New Users who have not yet registered to the RUS portal shall first create a COPERNICUS SSO account.

Note that your Copernicus SSO account will be activated only after the reception of the third email sent by the Copernicus service. We advise you to consult [this document](#) and [this page](#) to facilitate your registration procedure.

REGISTER COPERNICUS SSO account

Users who already have a COPERNICUS SSO account can login here:

Login

Close

Credentials

CDS-SSO ID

Password

Max Idle Time half a day

Max Session Time Until browser close

Login
Reset

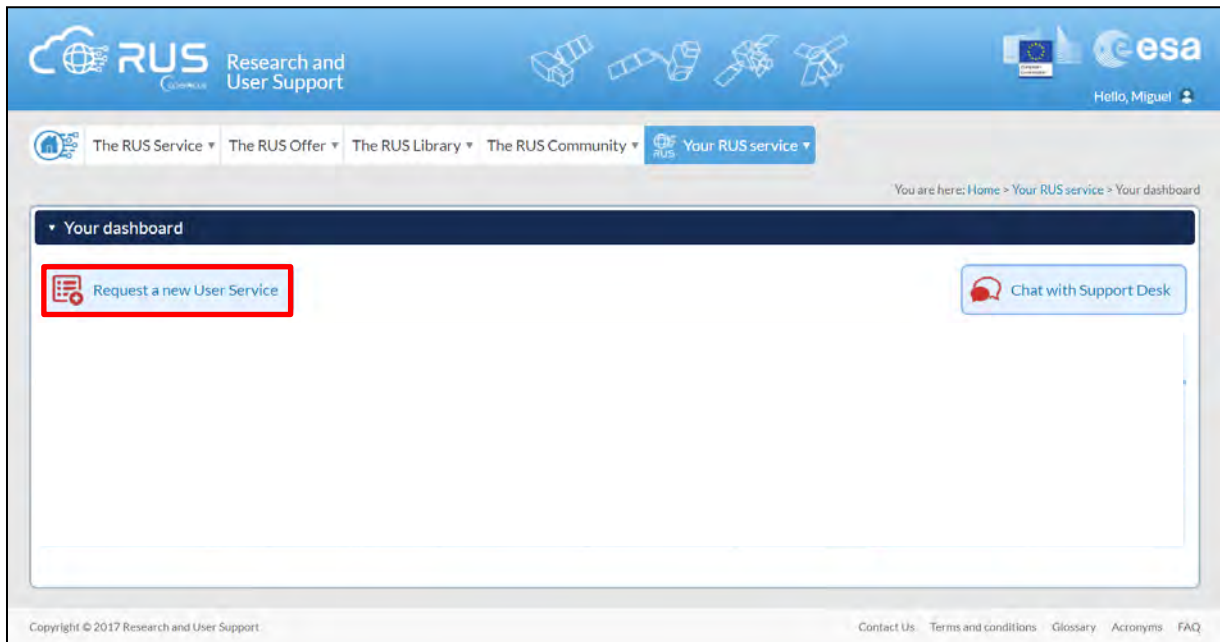
[Forgot your password?](#)

Upon your first login you will need to enter some details. You must fill all the fields.

5 Request a RUS Copernicus Virtual Machine

Once you are registered as a RUS user, you can request a RUS Virtual Machine to repeat this exercise or work on your own projects using Copernicus data. For that, log in and click on **Your RUS Service** → **Your Dashboard**.

Click on **Request a new User Service** to request your RUS Virtual Machine. Complete the form so that the appropriate cloud environment can be assigned according to your needs.



If you want to repeat this tutorial (or any previous one) select the one(s) of your interest in the appropriate field.

The image shows a 'User Support Request' form. It is titled 'Step 1/3 Your experience'. The instructions say: 'Please help us learn more about your background by answering a few questions. This information will be stored in your User Profile.' The first question is 'How many years of experience in Remote Sensing do you have?' with a dropdown menu. The second question is 'Have you already downloaded Copernicus data via the Copernicus Open access hubs?' with radio buttons for 'Yes' and 'No'. The third question is 'Have you already handled/processed Copernicus data?' with radio buttons for 'Yes' and 'No'. The fourth question is 'Do you wish to practice a tutorial exercise shown in a RUS webinar? If yes, please select your choice (hold down CTRL key for multiple selections)'. This question is highlighted with a red box and shows a list of options: HAZA01 - Flood Mapping in Malawi, HAZA02 - Burned Area Mapping in Portugal, HYDR01 - Water Bodies Mapping over Northern Poland, LAND01 - Crop Mapping in Seville, LAND04 - Land Monitoring in Cyprus, and OCEA01 - Ship Detection in Gulf of Trieste. Below the list, there is a text input field for requesting other tutorial exercises. At the bottom, there are 'Cancel' and 'Next' buttons.

Complete the remaining steps, check the terms and conditions of the RUS Service and submit your request once you are finished.

User Support Request

Summary information on your request:
 This is a collection of information selected across the USR forms.
 You can go back and edit this information if necessary.

General Information on your request:

Years of experience in Remote Sensing	5-10 years
Downloaded Copernicus data?	✓
Handled/processed Copernicus data?	✓
Webinar codes	HAZA02, LAND04

About your RUS project:

Thematic area	Cryosphere (ice and snow)
Operations to perform on RUS	Algorithm development
Preference for downloading process	Self-downloading
Foreseen activities and support needs	Develop a land cover classification
Project name	RUS_Project1

Earth Observation Data Information:

Type of Earth Observation Data:

Sentinel-1	✓
S1 - Product type	S1 - Product 1
S1 - Sensor mode	GRD
S1 - Polarisation	-
S1 - Orbit direction	-
Sentinel-2	X
Sentinel-3	X
Other	X
I don't know	X

Region of Interest:

Min Latitude	39.3303
Max Latitude	40.5877
Min Longitude	-4.6736
Max Longitude	-2.7205
Reference polygons	

Data acquisition date(s):
 None
 Additional data specifications

I have read and agree to the Terms and conditions of RUS Service.

[Back and edit](#) [Submit the request](#)

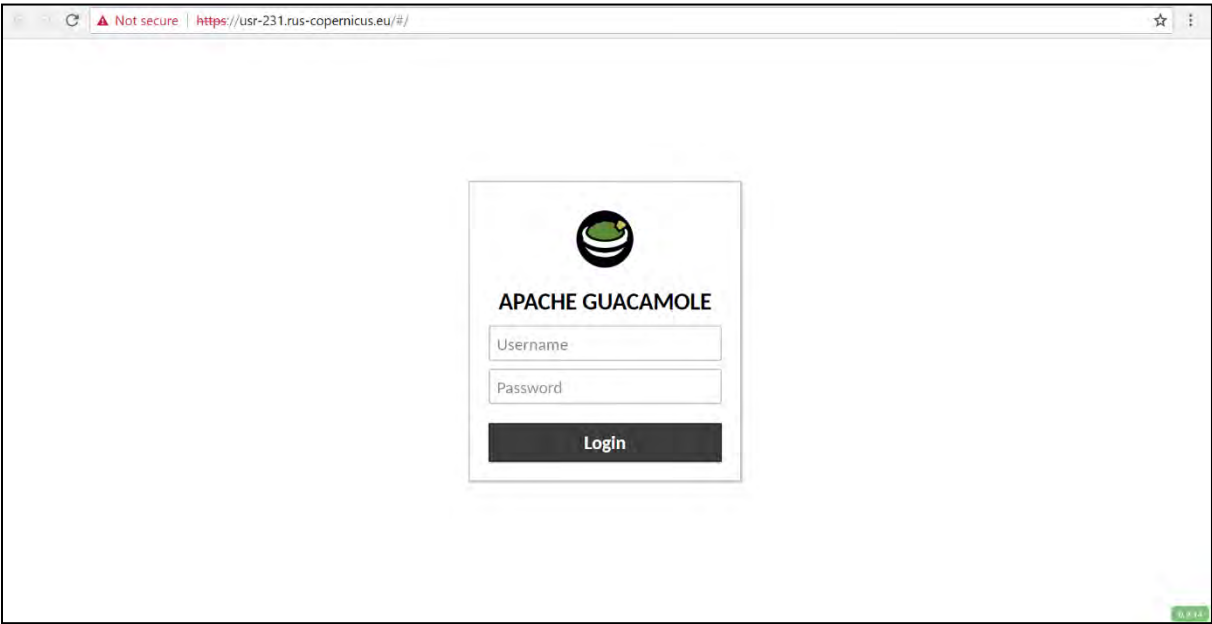
Further to the acceptance of your request by the RUS Helpdesk, you will receive a notification email with all the details about your Virtual Machine. To access it, go to **Your RUS Service** → **Your Dashboard** and click on **Access my Virtual Machine**.

The screenshot shows the RUS User Dashboard. At the top, there are navigation tabs: 'The RUS Service', 'The RUS Offer', 'The RUS Library', 'The RUS Community', and 'Your RUS service'. The current page is 'Your dashboard'. There is a 'Request a new User Service' button and a 'Chat with Support Desk' button. Below these is a table of projects:

Project Name	ID	Date of submission	Status	Actions			Virtual Environment	
RUS_training1	231	2017-08-31	Open	Follow my project	Get support	Close my service	Access my Virtual Machine(s)	Access my CPU monitoring dashboard
				Cancel my request	Get a webinar kit	Rate my service ★★★★★	Freeze my Virtual Machine(s)	Report a technical incident

The 'Access my Virtual Machine(s)' button in the table is highlighted with a red box. At the bottom of the page, there is a footer with 'Copyright © 2017 Research and User Support' and navigation links for 'Contact Us', 'Terms and conditions', 'Glossary', 'Acronyms', and 'FAQ'.

Fill in the login credentials that have been provided to you by the RUS Helpdesk via email to access your RUS Copernicus Virtual Machine.



This is the remote desktop of your Virtual Machine.

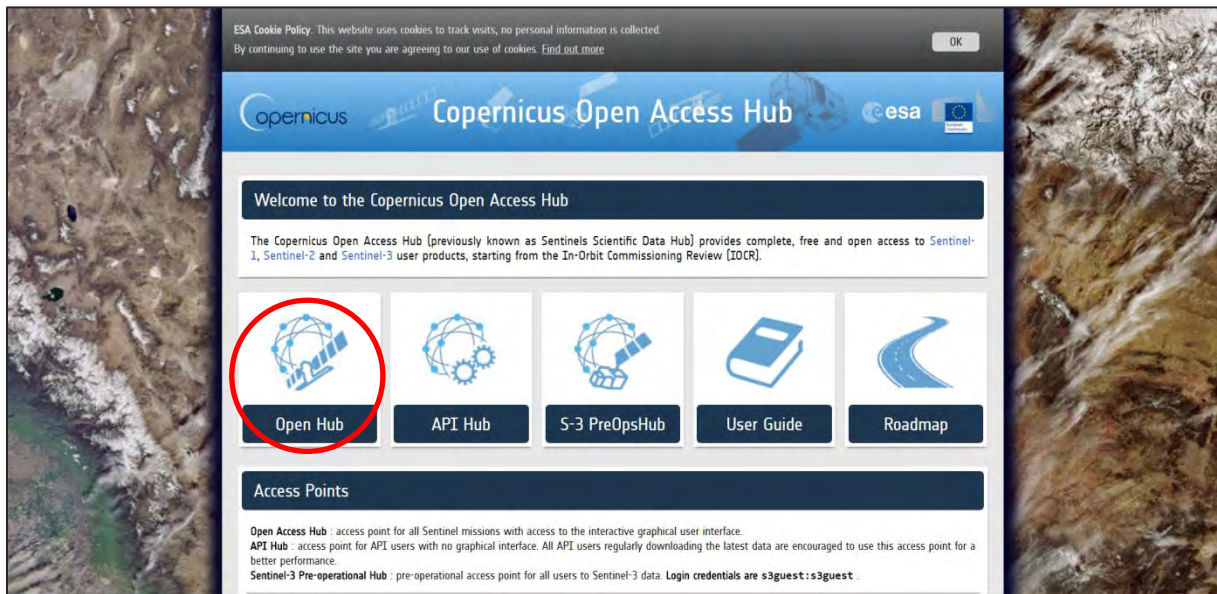


6 Step by step

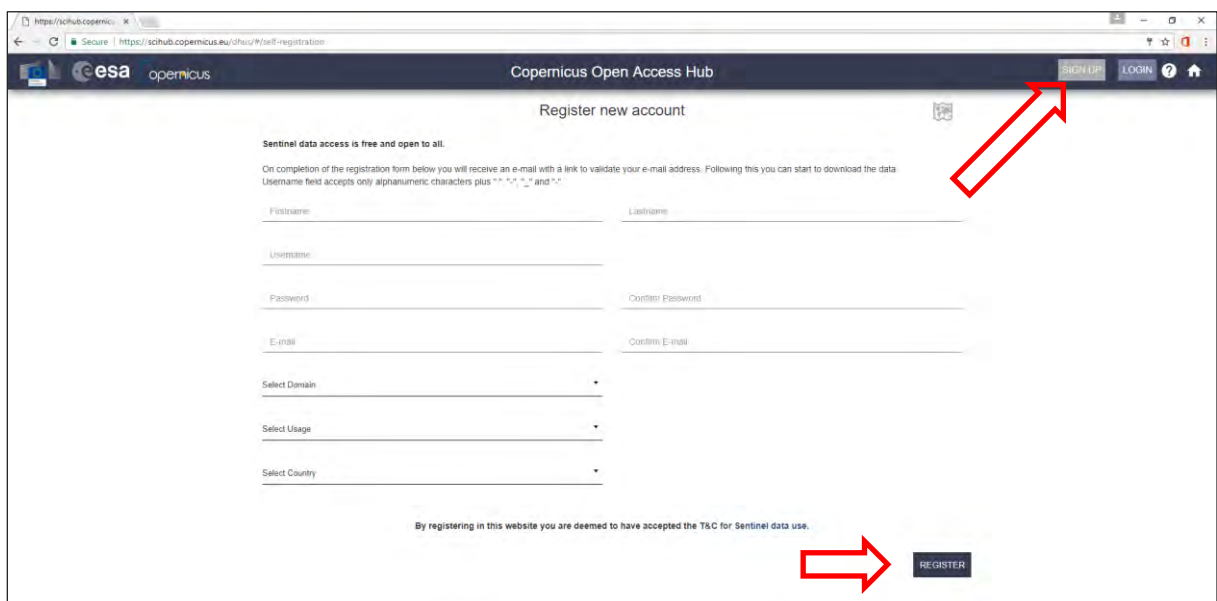
6.1 Data download – ESA SciHUB

In this step we will download the Sentinel-2A level 2A image from the Copernicus Open Access Hub using the online interface.

Go to <https://scihub.copernicus.eu/>

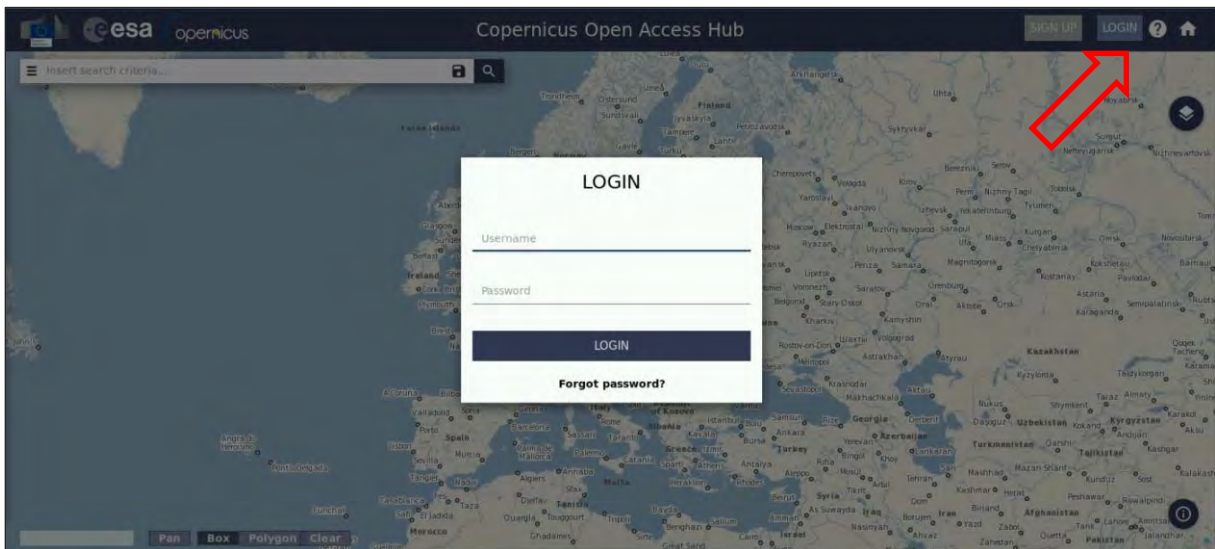


Go to Open HUB. If you do not have an account please sign up in the upper right corner, fill in the details and click register.



You will receive a confirmation email in the account you have specified: open the email and click on the link to finalize the registration.

Once your account is activated – or if you already have an account – log in.



Switch the rectangle drawing mode to pan mode by clicking on the icon in the lower left corner of the map (**Green rectangle**) and navigate to the Seville city area (**approximate area – blue rectangle**).

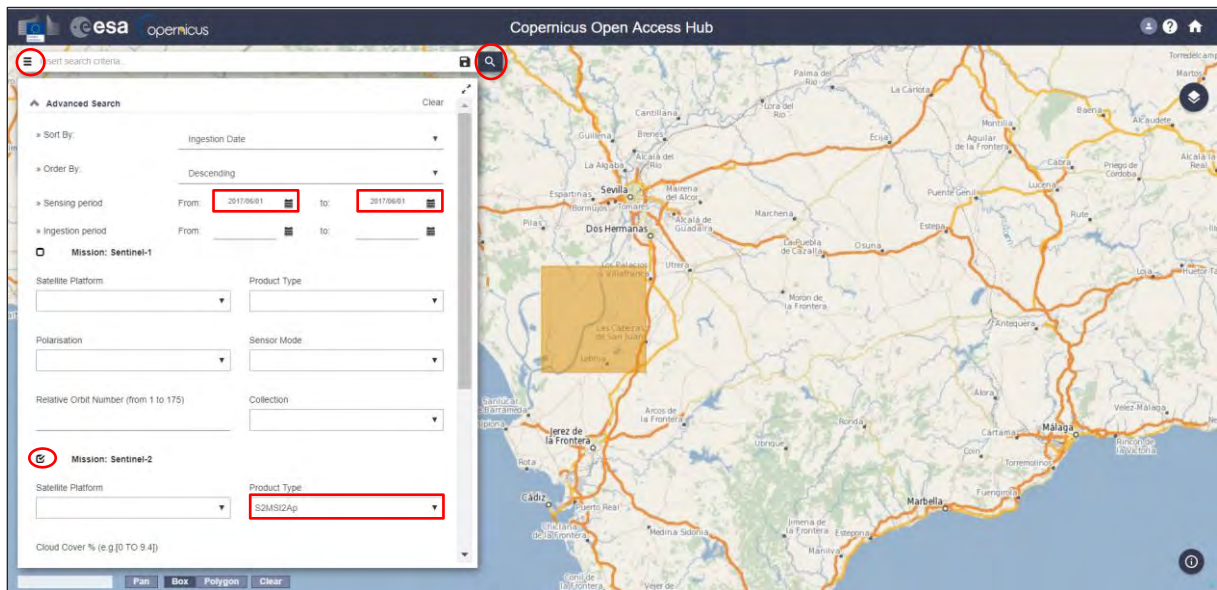


Switch now to drawing mode (box) and draw a search rectangle approximately as indicated below. Open the search menu by clicking to the left part of the search bar (☰) and specify the parameters below. Press the search button (🔍) after that.

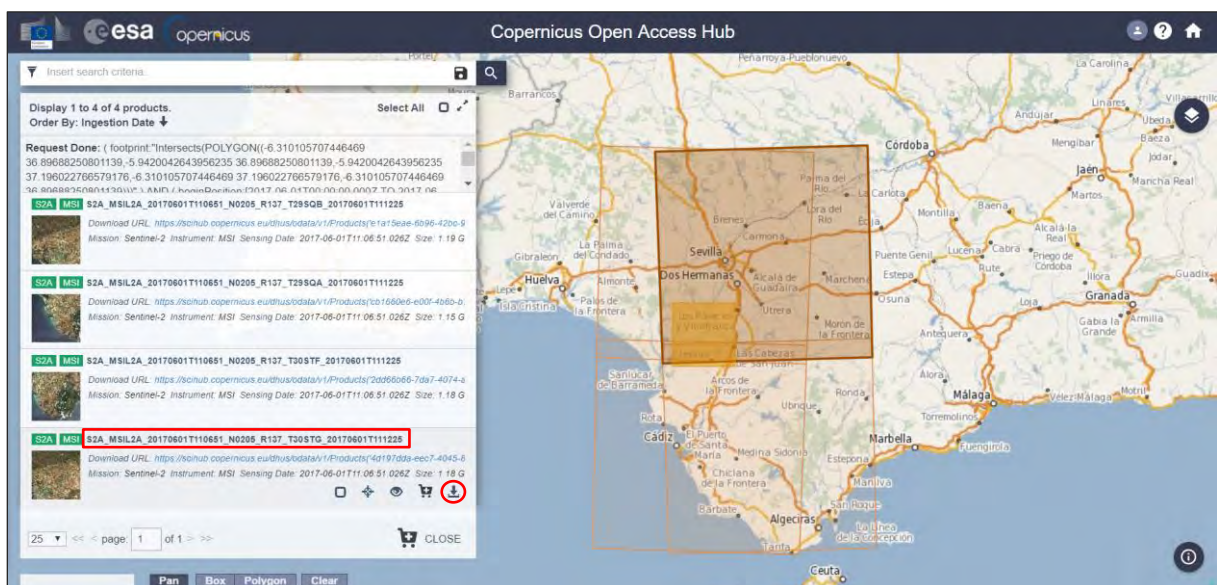
Sensing period: From 2017/06/01 to 2017/06/01

Check Mission: Sentinel-2

Product type: S2MSI2Ap




In our case the search returns 4 results depending on the defined search area. Download scene: S2A_MSIL2A_20170601T110651_N0205_R137_T30STG_20170601T111225



Move the downloaded scenes (desktop, /home/rus/Downloads) to the following path and unzip it by right clicking on it and using *Extract Here*.

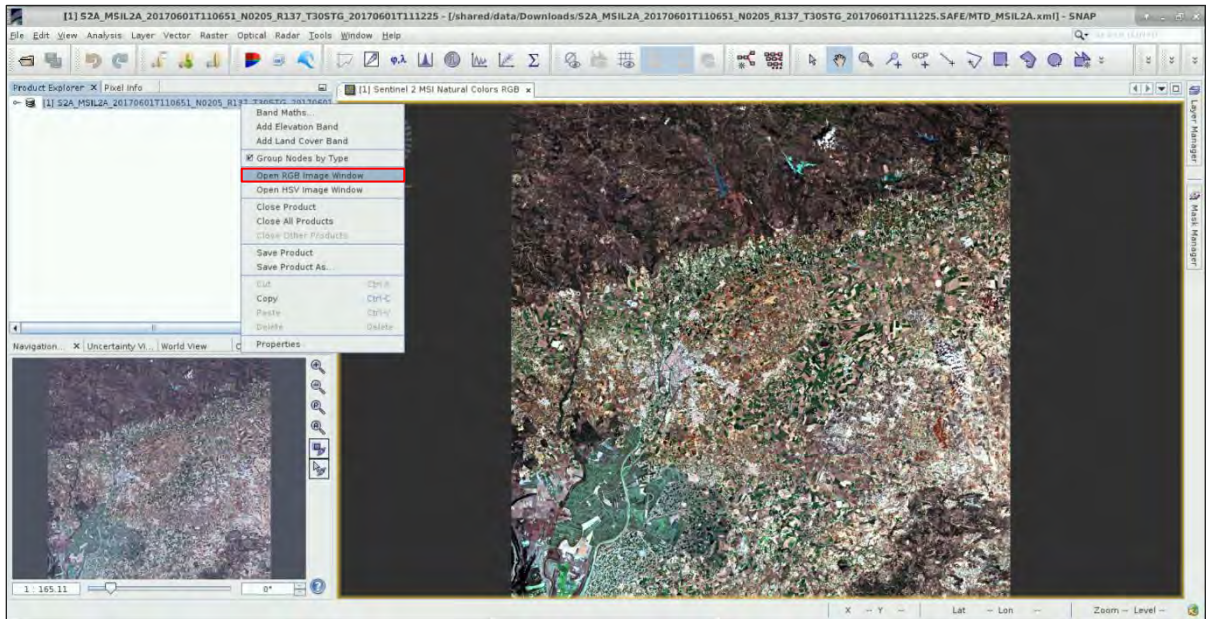
Path: *shared/Training/LAND01_CropMapping_Seville/Original*

6.2 SNAP – open and explore data

In *Applications* -> *Processing* open SNAP Desktop; click Open product (), navigate to the following path and open the product: *MTD_MSIL2A.xml* from the .SAFE folder.

Path: *shared/Training/LAND01_CropMapping_Seville/Original/*

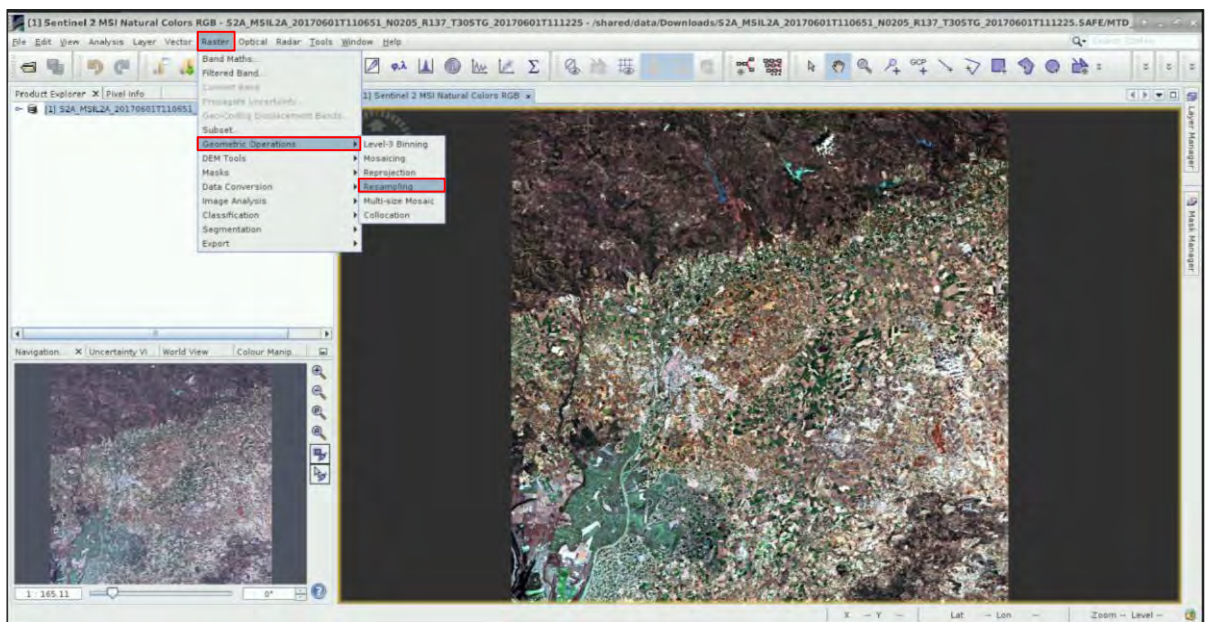
The opened product will appear in *Product Explorer* window. Right click on the product and select *Open RGB Image Window* to create and visualize an RGB composition image. Check that B4, B3, and B2 are selected for the Red, Green, and Blue channels respectively. Click *OK*.



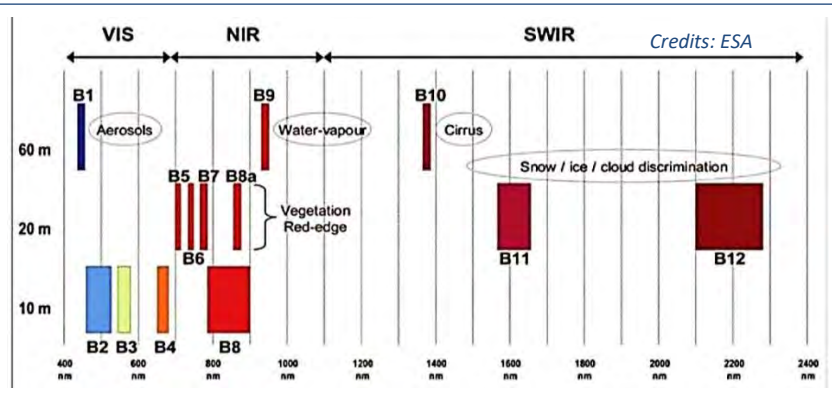
6.3 Resampling

Since the Sentinel-2 images have different pixel sizes depending on the spectral band (See NOTE 1), it is necessary to resample the product and equalize the different spatial resolutions. This step is generally required for any further processing.

Click *Raster* -> *Geometric Operations* -> *Resampling*



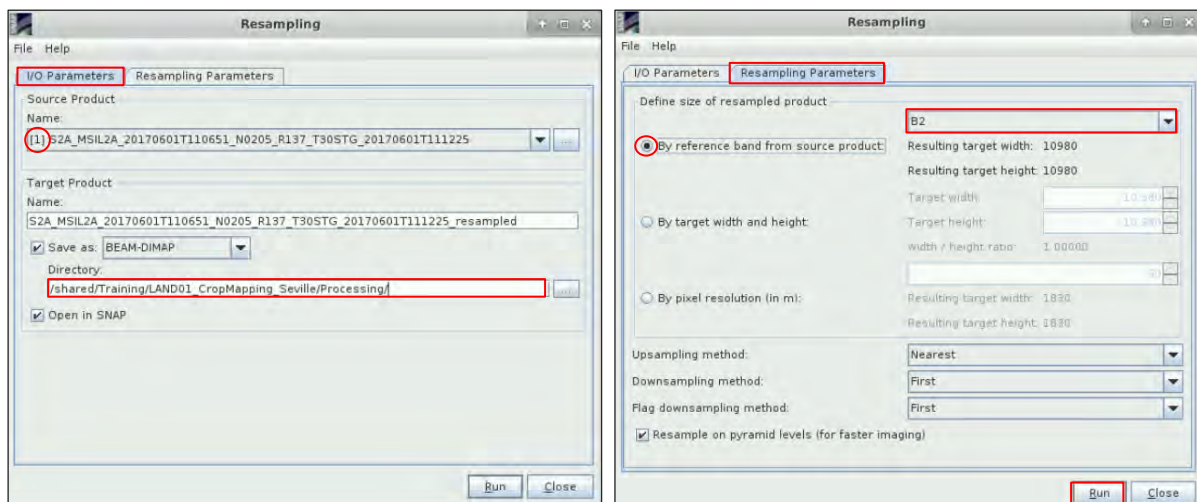
NOTE 1: Sentinel-2 images contain 13 spectral bands with three different spatial resolutions (10, 20 and 60 meters pixel size) ranging from the visible (VIS) to the Short-Wave Infrared (SWIR) part of the electromagnetic spectrum.



In the *I/O Parameters* tab, make sure that the source product starts with index [1]. Set the *Output folder* to the following path:

Path: *shared/Training/LAND01_CropMapping_Seville/Processing/*

Use this folder to save all following processing products. Go to the *Resampling Parameters* tab and select *By reference band from source product*. Select *B2* as the reference band. All other settings remain set to default values and click *Run*.



To visualize the output product, right click on it. Select *Open RGB Image Window* and click *OK*.

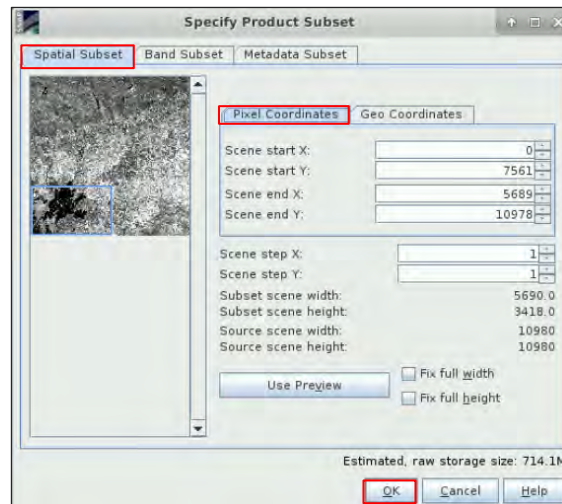
6.4 Subset

Since our Area of Interest (AOI) is quite small and there is no need to process the whole image we start with sub-setting the scene to a more manageable size (See NOTE 2). This will reduce the processing time in further steps and is recommended when the analysis is focused only over a specific area and not the complete scene. In the *Product Explorer* window, select the second resampled product and the go to *Raster -> Subset*.

NOTE 2: The subset product appears in the Product explorer but is not saved.

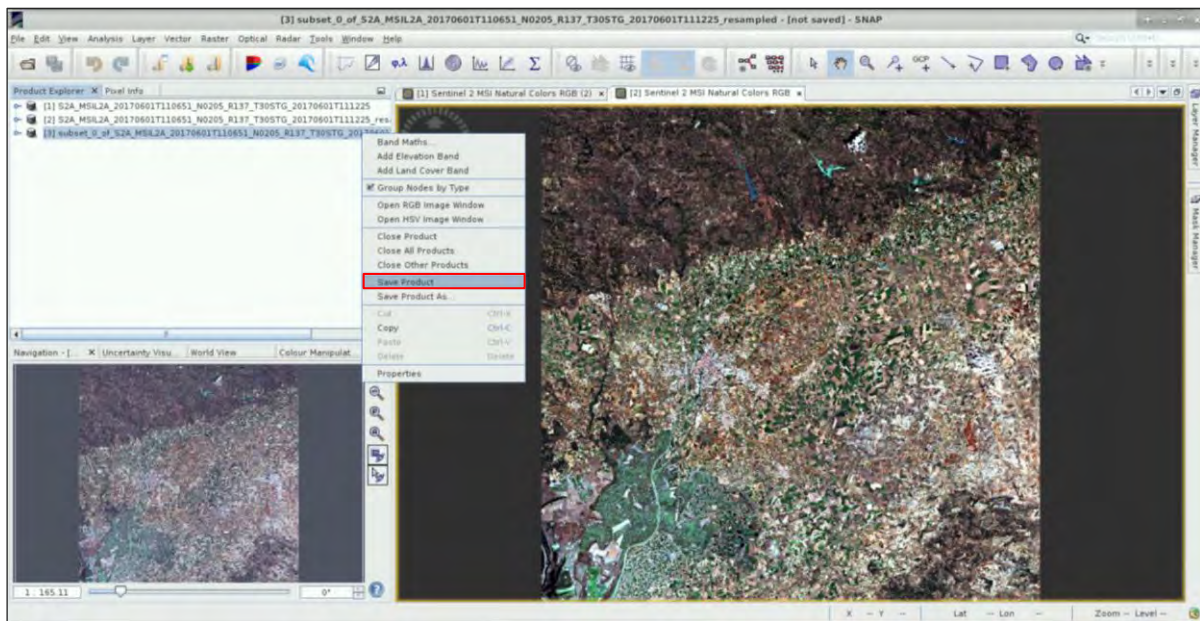
In the *Subset* menu, set the extent of the AOI to the following *pixel coordinates* and click *OK*.

Scene start x: 0 Scene start Y: 7651 Scene end X: 5689 Scene end Y: 10978



The subset product will be created immediately. Before continuing, save it to prevent errors. Right click on the subset product (index [3]) and select *Save Product*. Set the output folder to the following path and save it.

Path: *shared/Training/LAND01_CropMapping_Seville/Processing/*

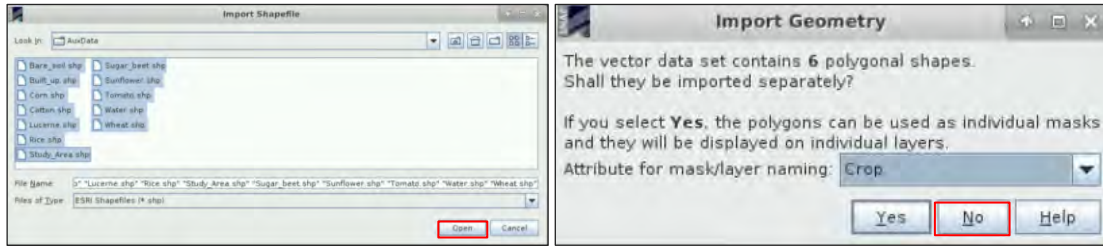


To visualize the output product, right click on it. Select *Open RGB Image Window* and click OK.

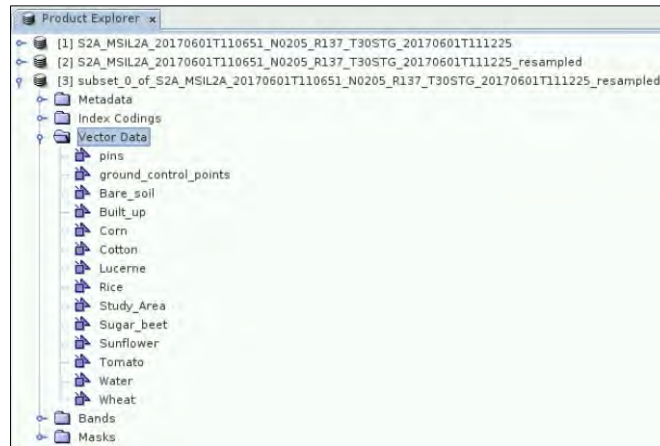
6.5 Import vector data

To prepare the data for the classification, the shapefiles of the study area and training areas must be imported. Click on *Vector -> Import -> ESRI Shapefile*. Navigate to the following path, select all the shapefiles and click *Open*. Click *No* in all the *Import Geometry* dialogs.

Path: *shared/Training/LAND01_CropMapping_Seville/AuxData/*

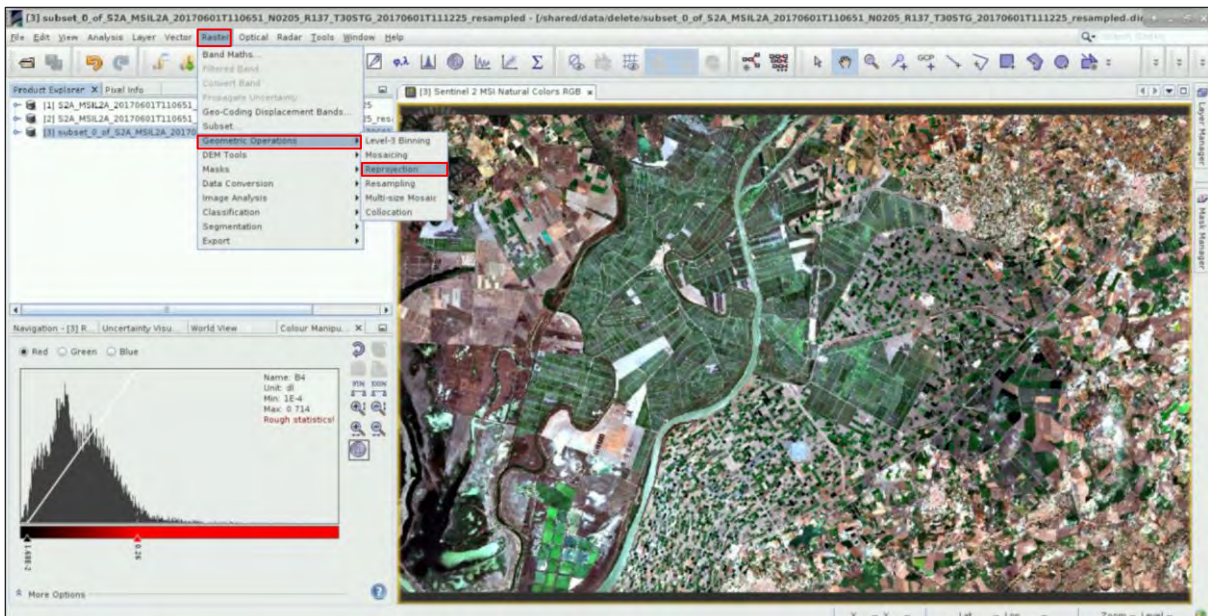


Once the vector data have been imported, do not forget to save the changes. Right click on the subset product (index [3]) and click on *Save Product*. The *Vector Data* folder of the subset product should look like the following image. Expand the product and open the *Vector Data* folder to check it.



6.6 Reproject

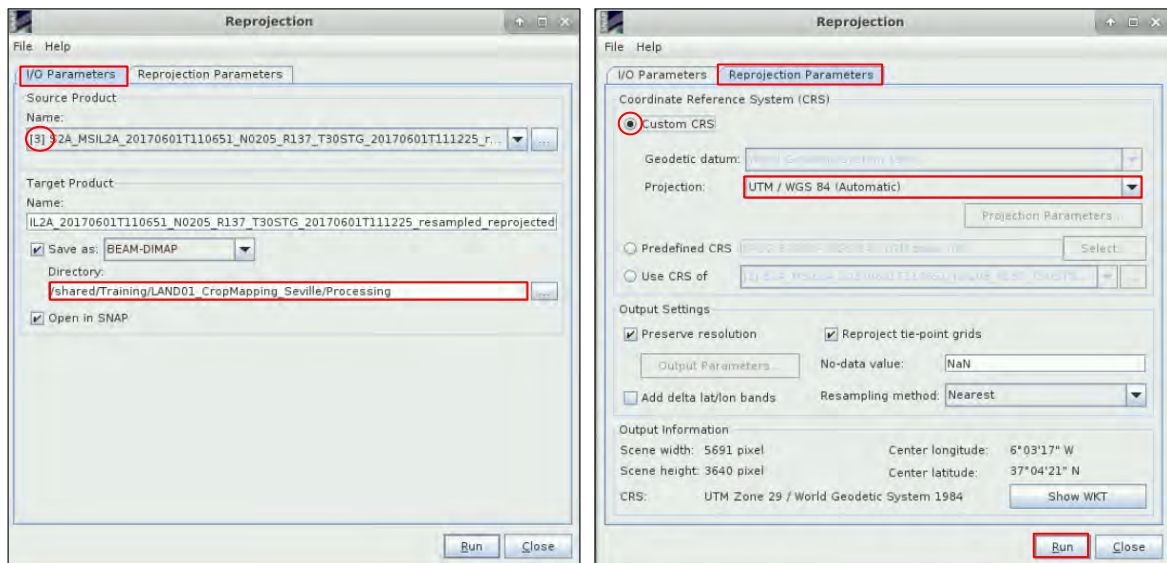
Before doing the classification, the product has to be reprojected due to software requirements. Click on *Raster -> Geometric Operations -> Reprojection*.



In the *I/O Parameters* tab make sure that the selected source product is the subset product (index [3]). Set Output folder to the following path:

Path: *shared/Training/LAND01_CropMapping_Seville/Processing/*

Move to the *Reprojection Parameters* tab. Select *Custom CRS* and choose the *UTM / WGS 84 (Automatic)* projection. All other settings remain set to default values. Click *Run*.



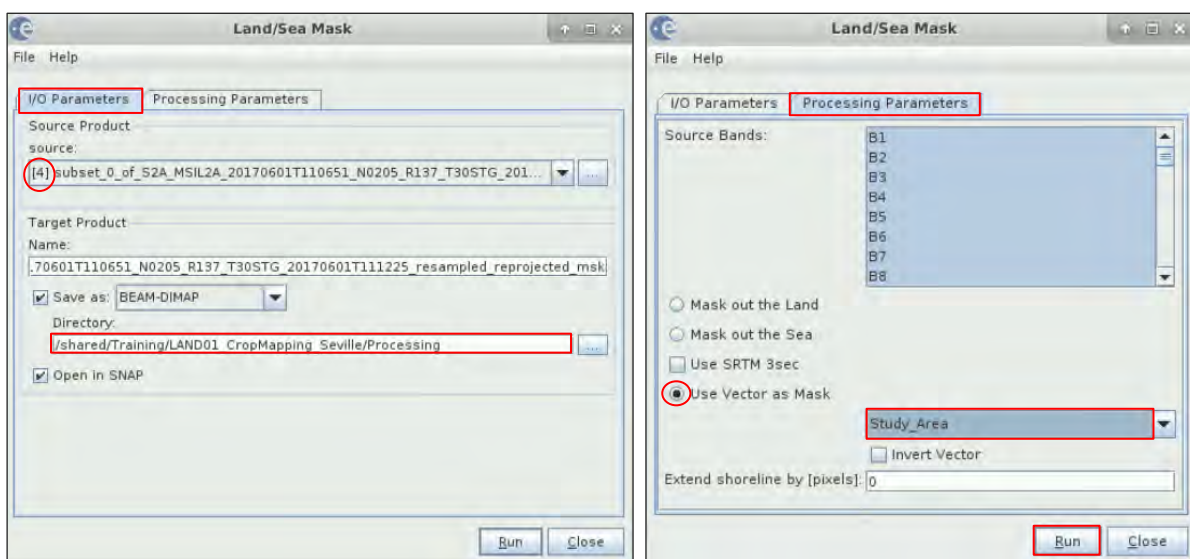
To visualize the output product, right click on it. Select *Open RGB Image Window* and click *OK*.

6.7 Mask

The last step before running the classification will be to mask out the pixels that are not inside the study area. To perform this process, click on *Raster -> Mask -> Land/Sea Mask*. Make sure the reprojected product (index [4]) is selected as input. Set the *Output folder* to the following path:

Path: *shared/Training/LAND01_CropMapping_Seville/Processing/*

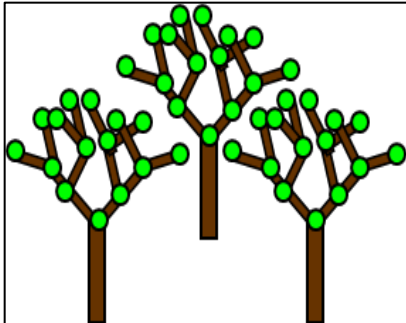
Go now to the *Processing Parameters* tab. Select from *B1* to *B12* as source bands. Uncheck the option *Use SRTM 3sec*, and select *Use Vector as Mask*. Open the drop-down menu and choose *Study_Area* as mask, then click *Run*.




To visualize the output product, right click on it. Select *Open RGB Image Window* and click *OK*.

6.8 Random Forest Classification

For this exercise, the Random Forest classification algorithm will be used (See  NOTE 3).



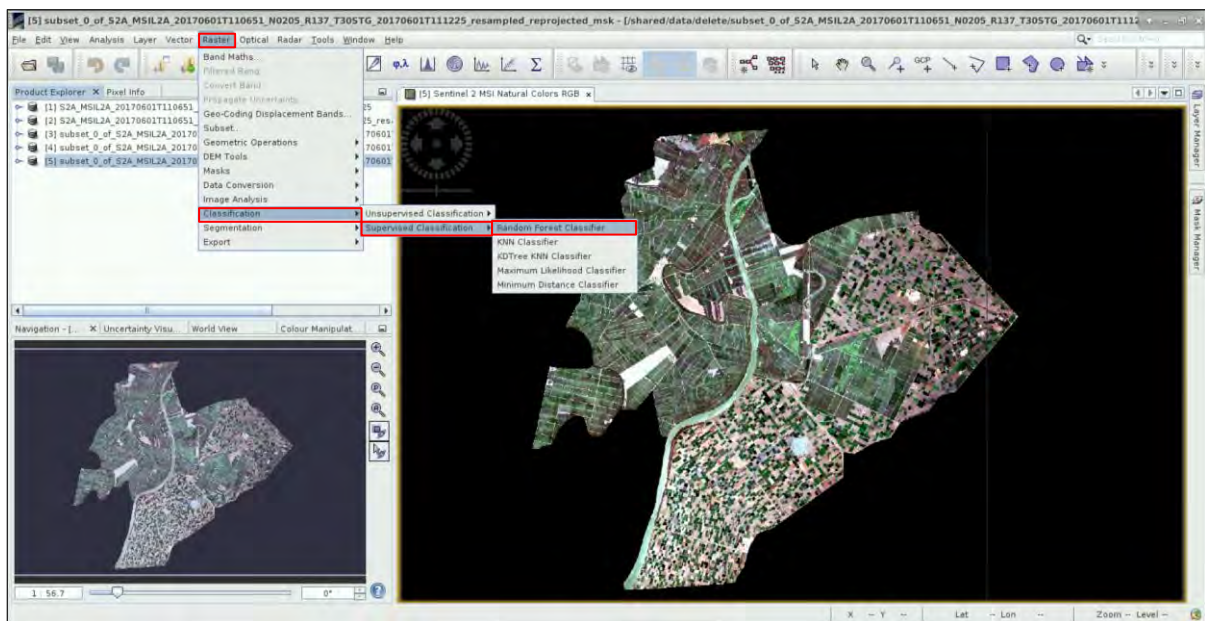
 NOTE 3: The Random Forest algorithm is a machine learning technique that can be used for classification or regression. In opposition to parametric classifiers (e.g. Maximum Likelihood), a machine learning approach does not start with a data model but instead learns the relationship between the training and the response dataset. The Random Forest classifier is an aggregated model, which means it uses the output from different models (trees) to calculate the response variable.


Decision trees are predictive models that recursively split a dataset into regions by using a set of binary rules to calculate a target value for classification or regression purposes. Given a training set with n number of samples and m number of variables, a random subset of samples n is selected with replacement (bagging approach) and used to construct a tree. At each node of the tree, a random selection of variables m is used and, out of these variables, only the one providing the best split is used to create two sub-nodes.

By combining trees, the forest is created. Each pixel of a satellite image is classified by all the trees of the forest, producing as many classifications as number of trees. Each tree votes for a class membership and then, the class with the maximum number of votes is selected as the final class.

More information about Random Forest can be found in Breiman, 2001.

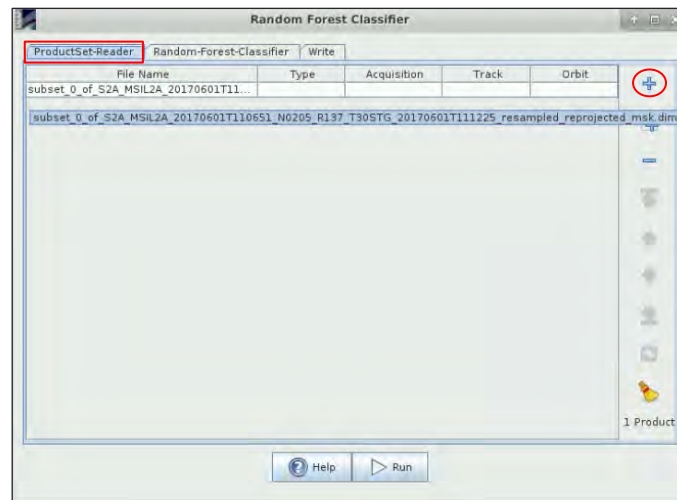
Click on *Raster* -> *Classification* -> *Supervised Classification* -> *Random Forest Classifier*



To properly visualize the product later, go to *Layer* -> *Layer Manager* and make sure that the *Vector Data* is not selected. Now, Click on the  symbol. Navigate to the following path and select the following product:

Path: /shared/Training/Crop_Mapping_Seville/Processing/

subset_0_of_S2A_MSIL2A_20170601T110651_N025_R137_T30STG_20170601T111225_resampled_reprojected_msk.dim

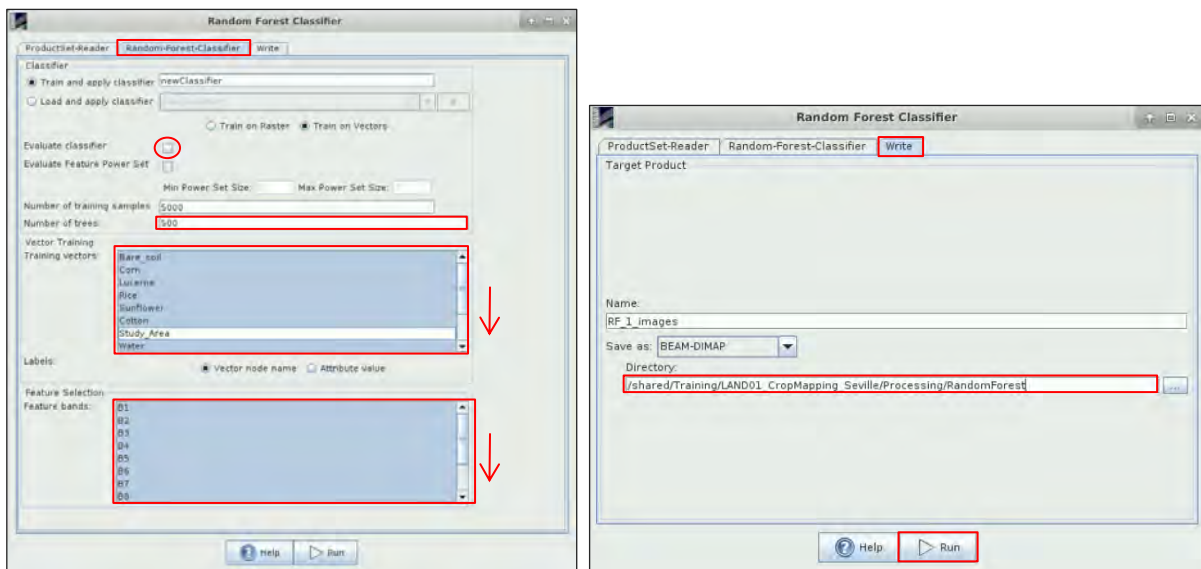


Move to the *Random-Forest-Classifier* tab and set the following parameters:

- Uncheck the Evaluate classifier option
- Set the number of trees to 500
- Select all the shapefiles as training vectors **except the Study_Area**
- Select all the bands (B1 to B12) as feature bands

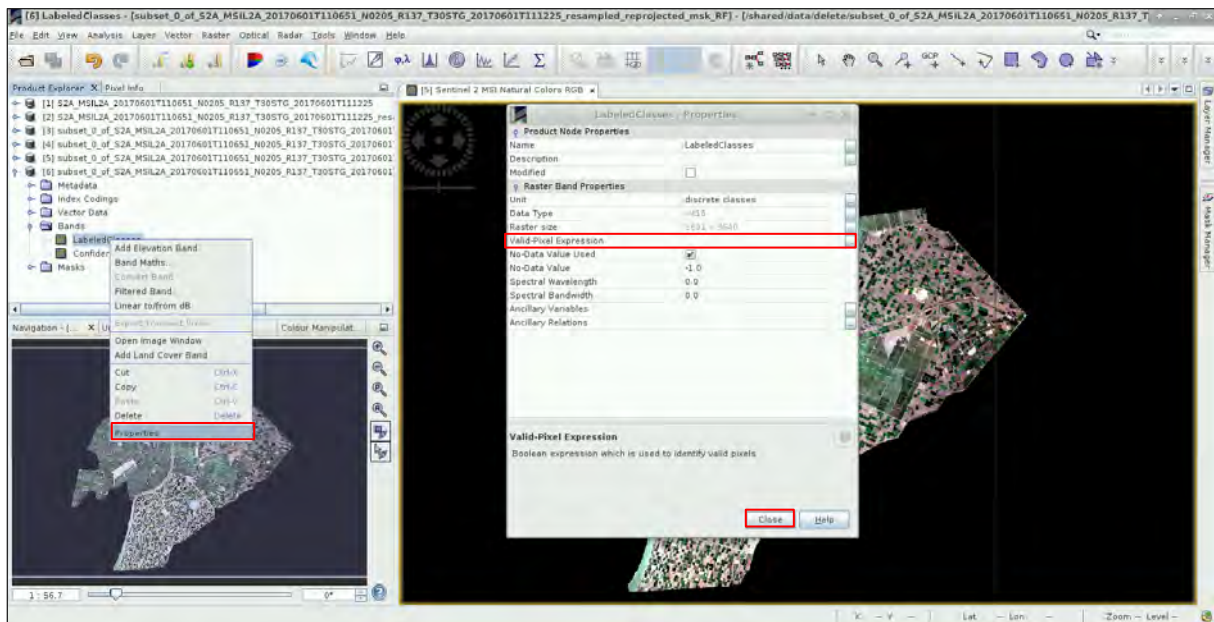
Click now on the *Write* tab, set the *Output folder* to the following path (create the *RandomForest* folder if not created yet), and specify the output name according to the number of input images used: *RF_1_images*. Finally, click *Run*.

Path: /shared/Training/LAND01_CropMapping_Seville/Processing/RandomForest/



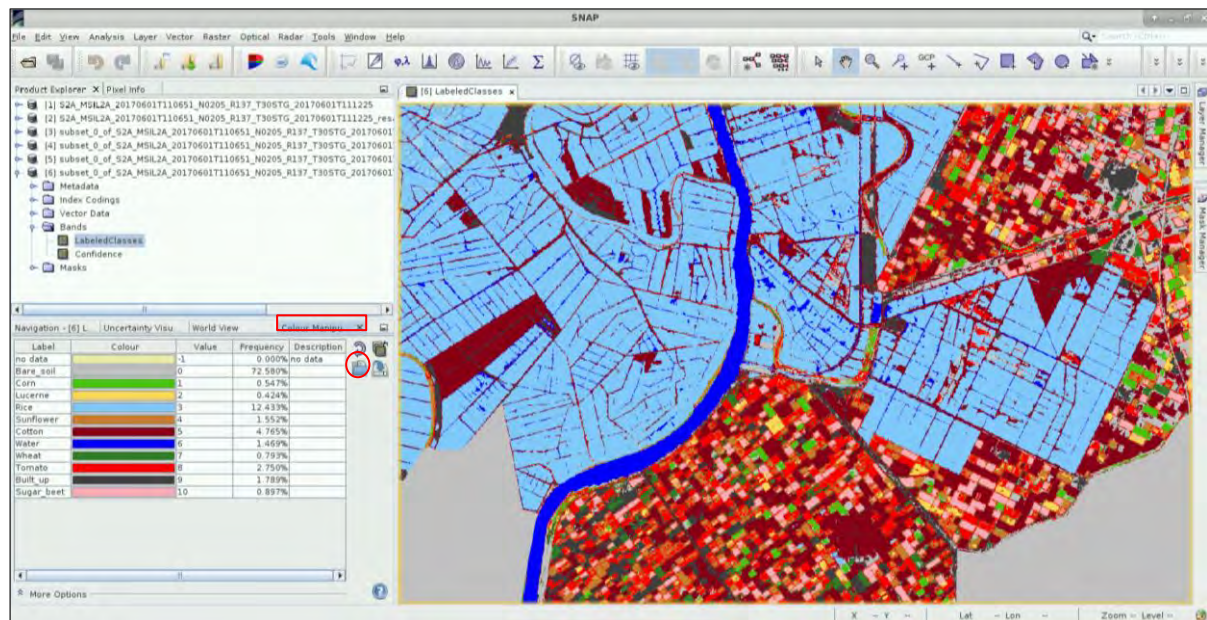
Before visualizing the classified output, the valid pixel expression has to be changed. By default, only the pixels with a confidence threshold above 0.5 are displayed. To change this parameter, expand the Random Forest product (index [6]), open the *Bands* folder, right click on the *LabeledClasses* file, and click on *Properties*.

Delete the expression $Confidence \geq 0.5$ and click *Close*.



Double click on the *LabeledClasses* file to open the classification image. You can change the colours by clicking on the *Colour Manipulation* tab located in the lower left corner or by clicking on *View -> Tool Windows -> Colour Manipulation*. Select your own colours or click on the *Import colour palette* icon (📁). Navigate to the following path and select the file *Colour_Palette_SNAP.cpd*

Path: `/shared/Training/LAND01_CropMapping_Seville/AuxData/Colour_Palette/`



To properly visualize the new product, go to *Layer -> Layer Manager* and make sure that the *Vector data* is not selected.

7 Extra steps

7.1 Multi-temporal Random Forest classification

7.1.1 Data download

To improve the classification result obtained in the previous chapter, the number of input images can be increased. In that way, the algorithm will have more information to take into account and better output can be produced.

Go back to chapter 6.1 *Data download – ESA SciHUB* and follow the steps to download the Sentinel-2 images corresponding to the following dates:

2017_06_11 → S2A_MSIL2A_20170611T110621_N0205_R137_T30STG_20170611T111012

2017_06_21 → S2A_MSIL2A_20170621T110651_N0205_R137_T30STG_20170621T111222

2017_07_01 → S2A_MSIL2A_20170701T111051_N0205_R137_T30STG_20170701T111746

2017_07_11 → S2A_MSIL2A_20170711T110651_N0205_R137_T30STG_20170711T111223

2017_07_21 → S2A_MSIL2A_20170721T110621_N0205_R137_T30STG_20170721T112025

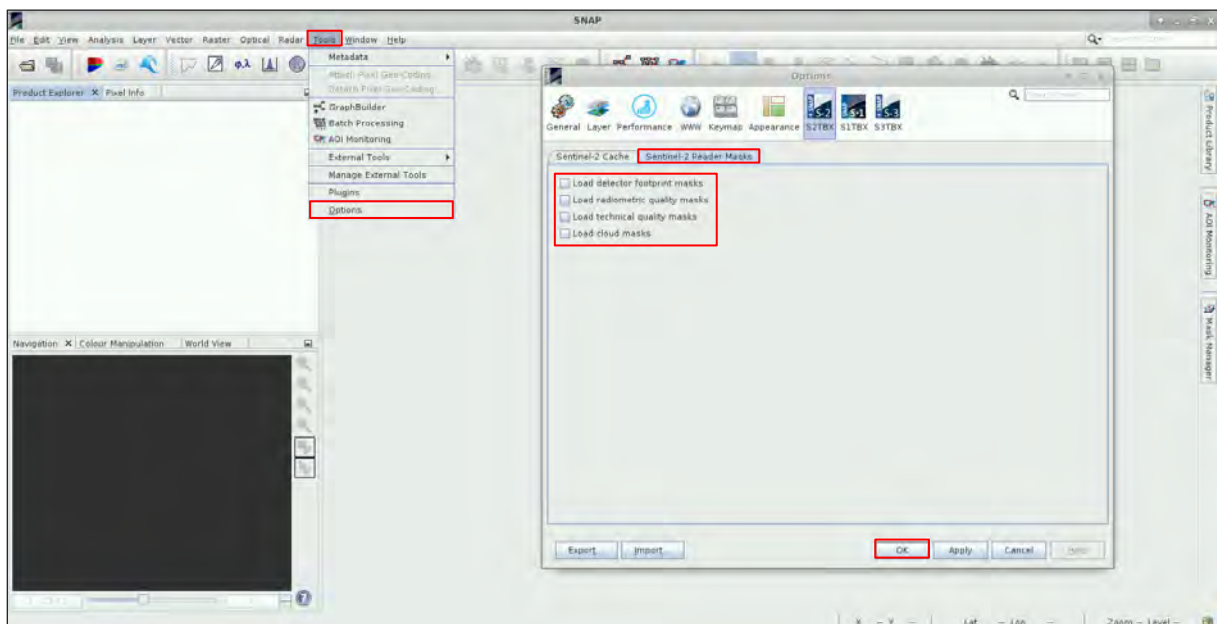
2017_07_31 → S2A_MSIL2A_20170731T110651_N0205_R137_T30STG_20170731T111220

Do not forget to move the downloaded products (desktop, */home/rus/Downloads*) to the following path and unzip them by right clicking to each one and then selecting *Extract Here*.

Path: *shared/Training/LAND01_CropMapping_Seville/Original/*

Go back to SNAP and close all the images. Right click on any of the products and select *Close All Products*. Click *No* when asked to save the product.

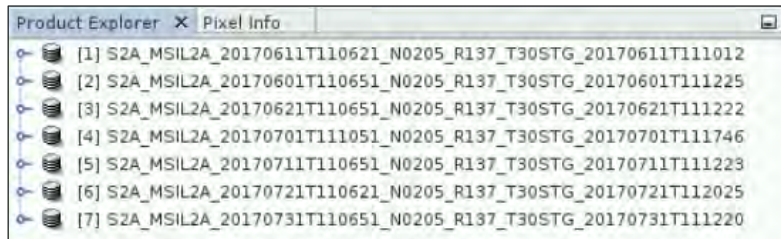
Due to software requirements, the Sentinel-2 Reader Masks have to be disabled to prevent errors. Click on *Tools -> Options* and select the *S2TBX* tab. At the *Sentinel-2 Reader Masks* tab, uncheck all the options and click *OK*.



7.1.2 SNAP Open data

Go to *File -> Open product* (📁) and navigate to the path indicated below. In each folder, open the file *MTD_MSIL2A.xml*. Start the process with the folder on top and continue successively to open all the images in chronological order. Your *Product Explorer* window should have the same content as the one shown on the figure below.

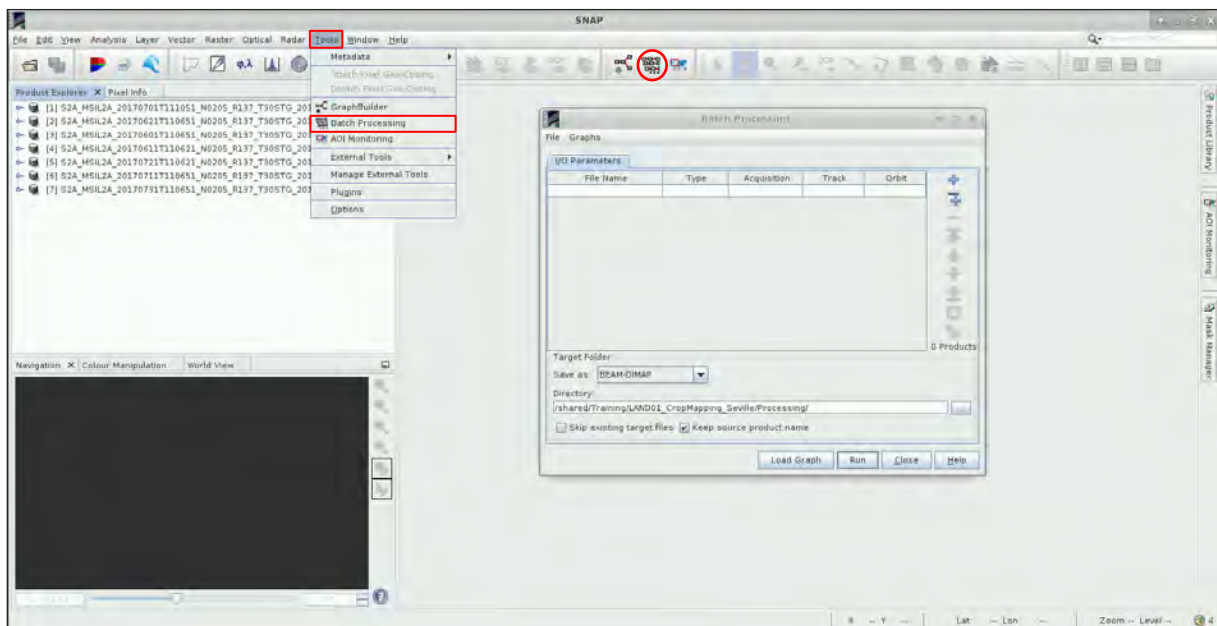
Path: *shared/Training/LAND01_CropMapping_Seville/Original/*



7.1.3 Batch Processing

Before running the multi-temporal Random Forest Classification, the images must be pre-processed as before. However, since we have more inputs to analyze, we will use the Batch Processing option included in SNAP. This feature allows the execute graphs including processing tools to a set of inputs.

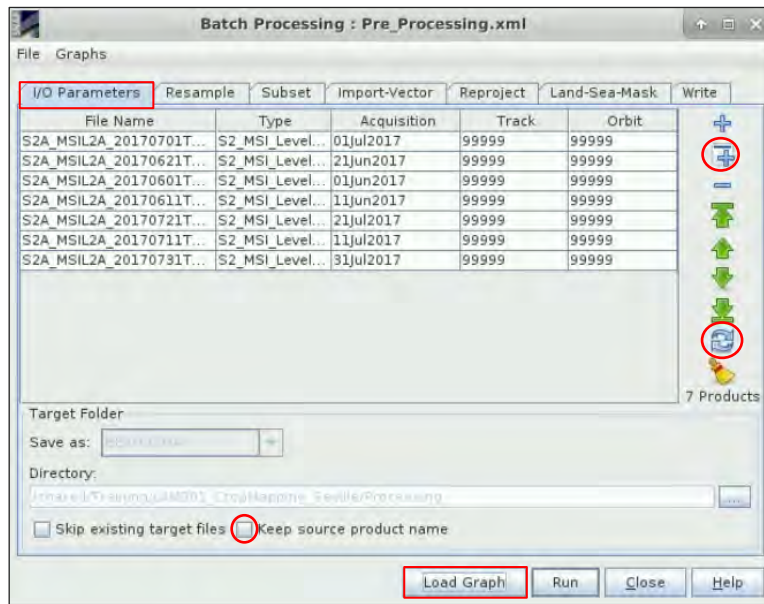
Click on *Tools -> Batch Processing* or click on the Batch Processing icon (🔧).



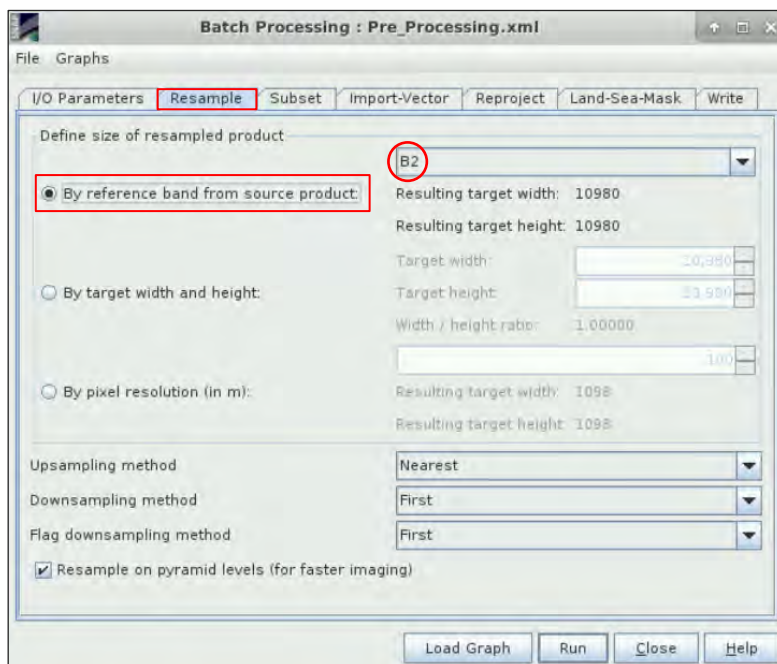
Click on the *Add Opened* icon (📁) to load all the images in the Batch Processing. Press the refresh button (🔄) to update the metadata information, and uncheck the *Keep source product name* option.

Once the Sentinel-2 images are loaded, the graph containing the pre-processing tools have to be included as well. Click on *Load Graph*, navigate to the following path and select the file *Pre_Processing.xml*.

Path: *shared/Training/LAND01_CropMapping_Seville/AuxData/Batch_Processing_Graph/*

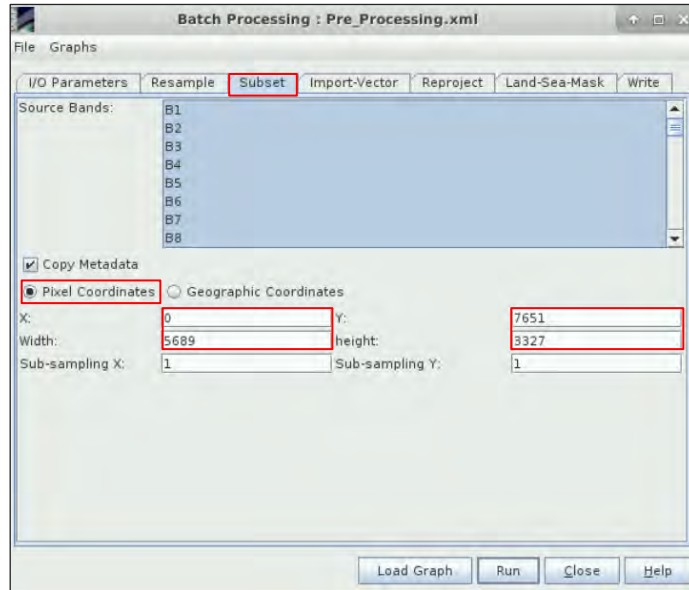


Go to the *Resample* tab and choose the option *By reference band from source product*. Open the drop-down menu and choose *B2* as reference band. All other settings remain set to default values.



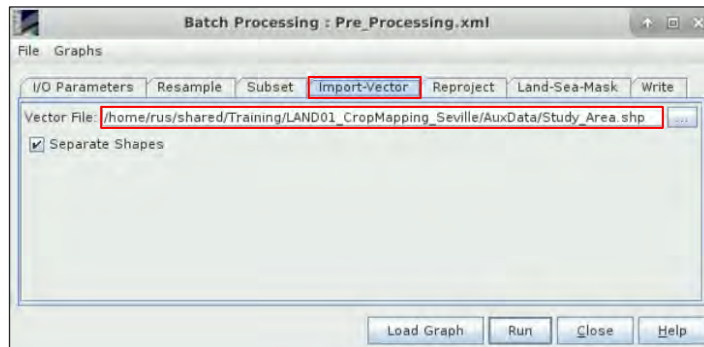
Click on the *Subset* tab and set all the bands from B1 to B12 as source bands. Select *pixel coordinates* and specify the following values. All other settings remain set to default values.

X: 0 Y: 7651 Width: 5689 Height: 3327

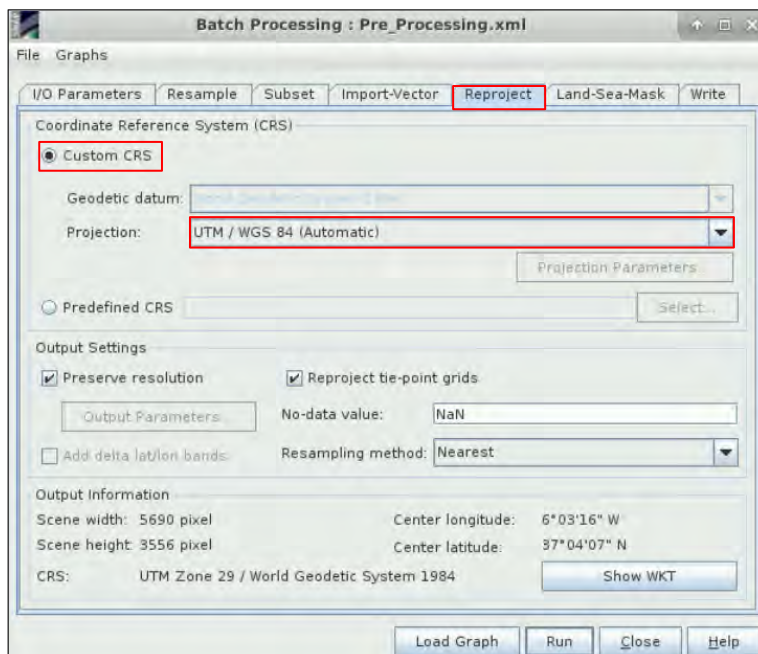


Click on the *Import-Vector* tab. Navigate to the following path and select the *Study_Area.shp* file.

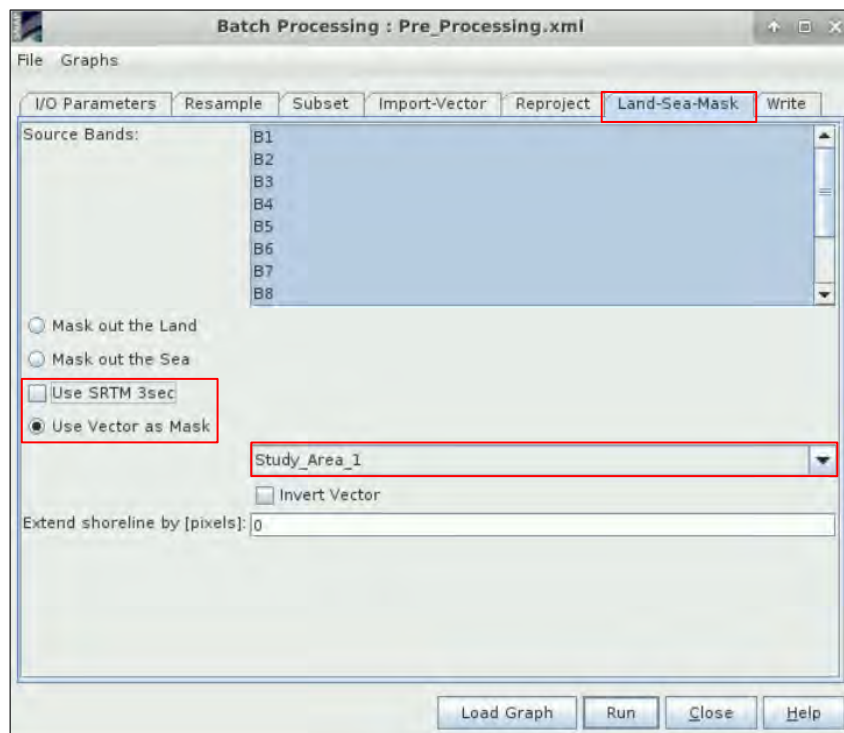
Path: *shared/Training/LAND01_CropMapping_Seville/AuxData/*



Click on the *Reproject* tab and select the *Custom CRS* option. At the *Projection*, open the drop-down menu and select the option *UTM / WGS 84 (Automatic)*. All other settings remain as default.

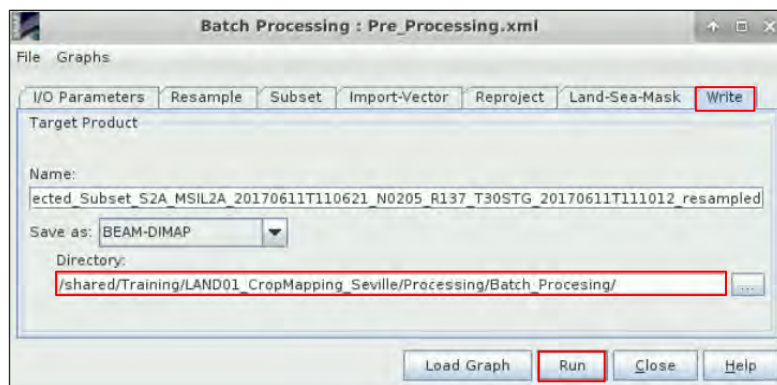


Click on the Land-Sea-Mask. Select from B1 to B12 as source bands. Uncheck the option *Use SRTM 3sec* and select *Use Vector as Mask*. At the drop-down menu choose *Study_Area_1* as mask. All other settings remain set to default values.



Finally, click on the *Write* tab and set the output directory to the following path. Then, click *Run*. If not created yet, add the *Batch_Processing* folder within *the Processing* directory.

Path: *shared/Training/LAND01_CropMapping_Seville/Processing/Batch_Processing/*



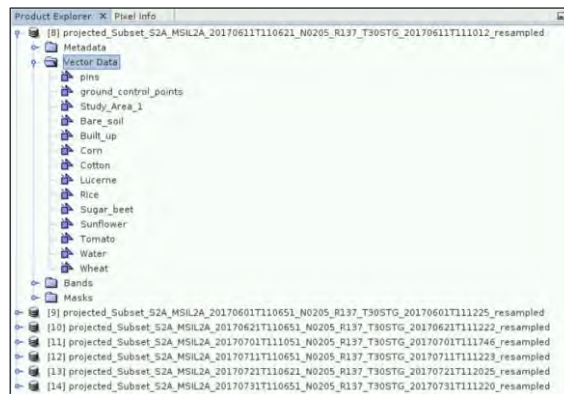
7.1.4 Random Forest Classification

After pre-processing the images, the random forest classification can be applied. First, select all the Sentinel-2 original images (files in the *Product Explorer* window with index [1] to [7]), right click and select *Close All Products*. Click *No* when asked to save the product.



Select now the first product (index [8], date 2017_06_01) and click on *Vector -> Import -> ESRI Shapefile*. Navigate to the following path, select all the shapefiles except the *Study_Area.shp* shapefile and click *Open*. Click *No* in all the *Import Geometry* dialog that will appear.


Path: *shared/Training/LAND01_CropMapping_Seville/AuxData/*

Once the vector data has been imported, do not forget to save the changes. Right click on the product (index [1]) and click on *Save Product*. The *Vector Data* folder of the subset product should look like the following image. Expand the product and open the *Vector Data* folder to check it.



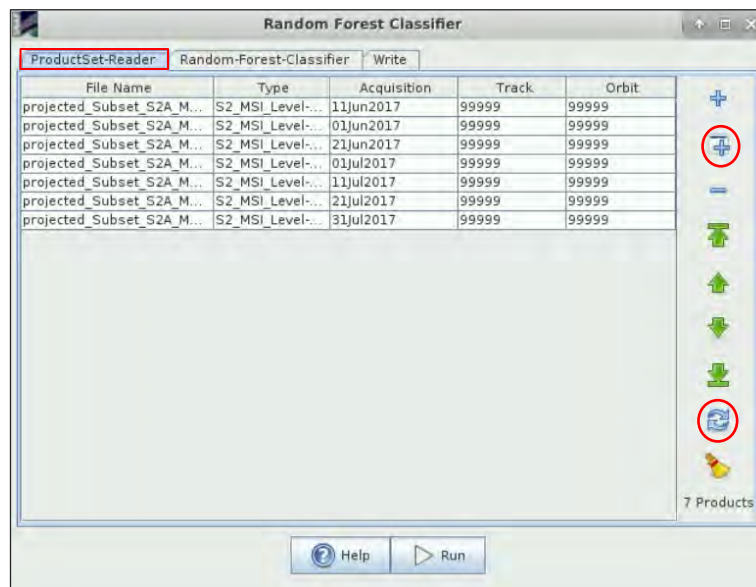
Click on *Raster -> Classification -> Supervised Classification -> Random Forest Classifier*

On the Product-Reader tab, click on the *Add Opened* icon () to load all the images. Press the refresh button () to update the metadata information.

You can now decide the number of images you want to use for the multi-temporal Random Forest Classification. The classification can be repeated as many times as desired and with different number of Sentinel-2 images as input. To remove an image from the list, select it and press the  icon.


Remember to always include the image from 2017_06_01 (index [1]) since it is the one containing the training vectors.

For this exercise we will run the multi-temporal Random Forest Classification using all the S2 images.

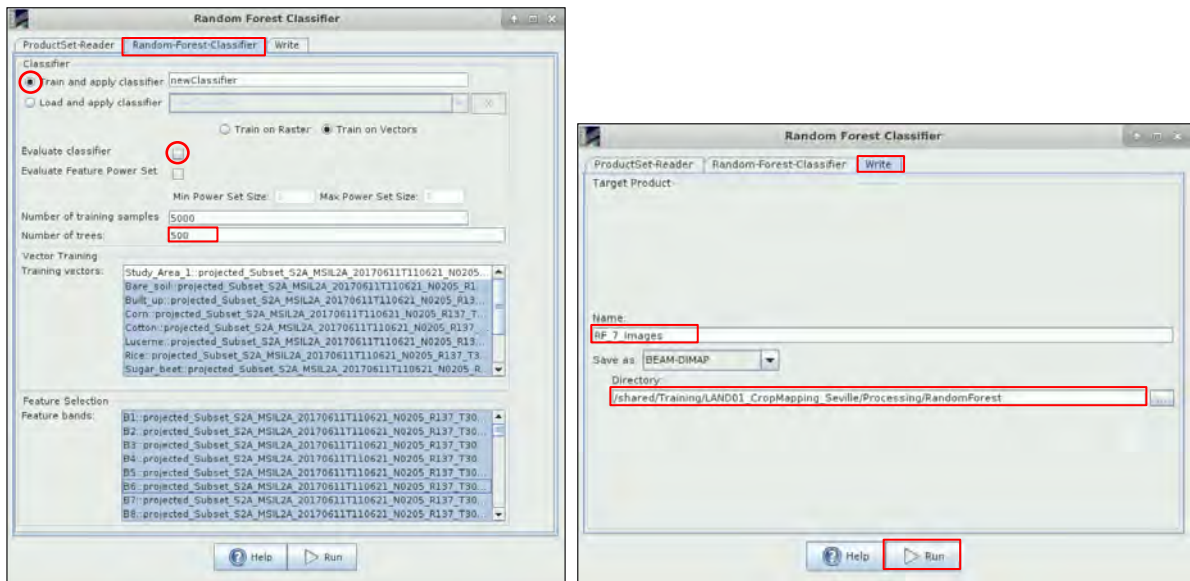


Move to the *Random-Forest-Classifer* tab and set the following parameters:


- Select the option *Train and apply classifier*
- Uncheck the Evaluate classifier option
- Set the number of trees to 500
- Select all the shapefiles as training vectors **except the *Study_Area.shp***
- Select all the bands as feature bands

Click now on the *Write* tab, set the output folder to the following path, and specify the output name according to the number of input images (e.g. 'RF_7_images'). Finally, click *Run* (See  NOTE 4).


Path: `shared/Training/LAND01_CropMapping_Seville/Processing/RandomForest/`



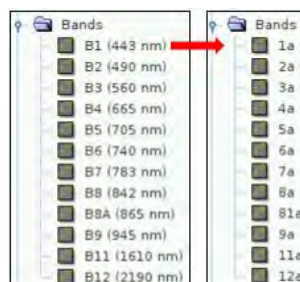
To properly visualize the result, go to *Layer -> Layer Manager* and make sure that the *Vector Data* field is not selected. Once the classification is done, remember to change the confidence threshold. Expand the Random Forest classification product, open the *Bands* folder right click on the *LabeledClasses* file, and click on *Properties*. Delete the valid-pixel expression *Confidence >= 0.5* and click *Close*.

Double click on the *LabeledClasses* file to open the classification image. You can change the colours by clicking on the *Colour Manipulation* tab located in the lower left corner or by clicking on *View -> Tool Windows -> Colour manipulation*. Select your own colours or click on the 'Import colour palette' icon (). Navigate to the following path and select the file *Colour_Palette_SNAP.cpd*

Path: `shared/Training/LAND01_CropMapping_Seville/AuxData/Colour_Palette/`

 NOTE 4: Due to a SNAP issue, it is possible that an error will appear. In case you see the message *Error: [Nodename: Random-Forest-Classifer] Cannot select feature band B1 in more than one product* you need to rename all the bands of 6 out of 7 products (do not change the first one, the image from 20170601, since it contains the training vectors). For this, expand each product, open the *Bands* folder, right click on each band, and click *Properties*. As an example, change the name of the first band in the second product (20170611) from B1 (443 nm) to 1a as shown in the image below. Do the same for the remaining bands.

For the third product change the name from B1 (443 nm) to 1b and continue accordingly. Repeat this step for all bands of the remaining products. Remember to save the products after the changes have been made (right click on the product -> *Save Product*).



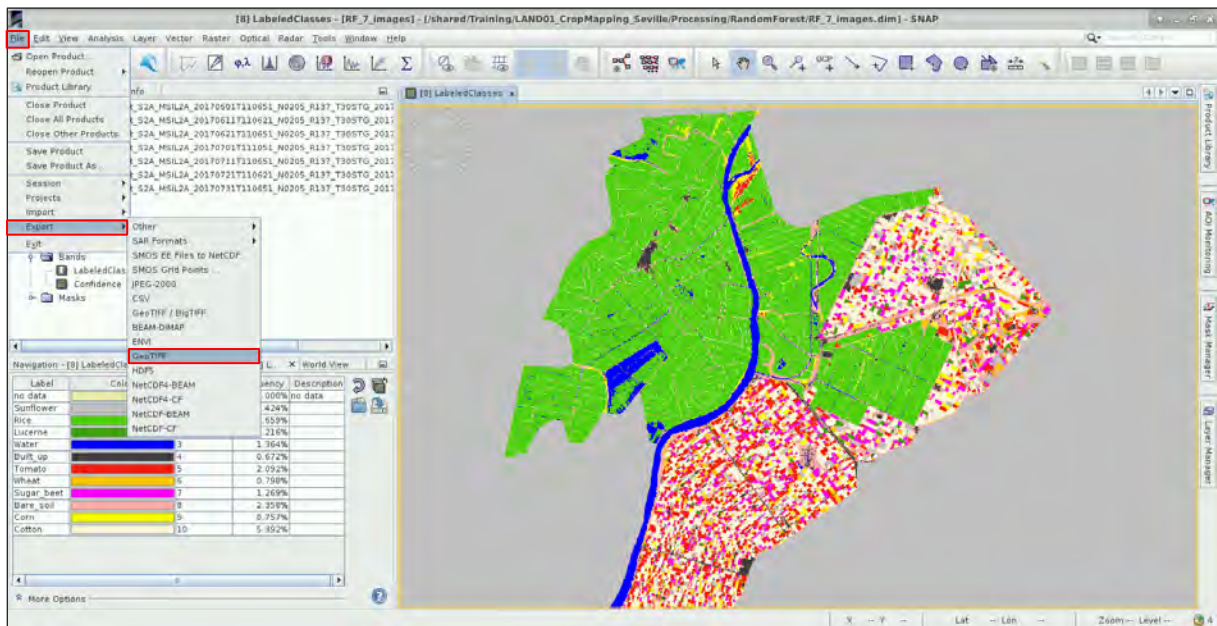
7.2 Export to QGIS

To import the classification raster in QGIS, we will convert it into GeoTIFF format. You can perform this step for the single-date Random Forest classification or for the multi-temporal Random Forest classification.

Expand now the classified product and open the *LabeledClasses* band.

Click on *File* -> *Export* -> *GeoTIFF* and save the product in the following path with the appropriate name: *RF_* + number of images used + *_images* (e.g. *RF_7_images*).

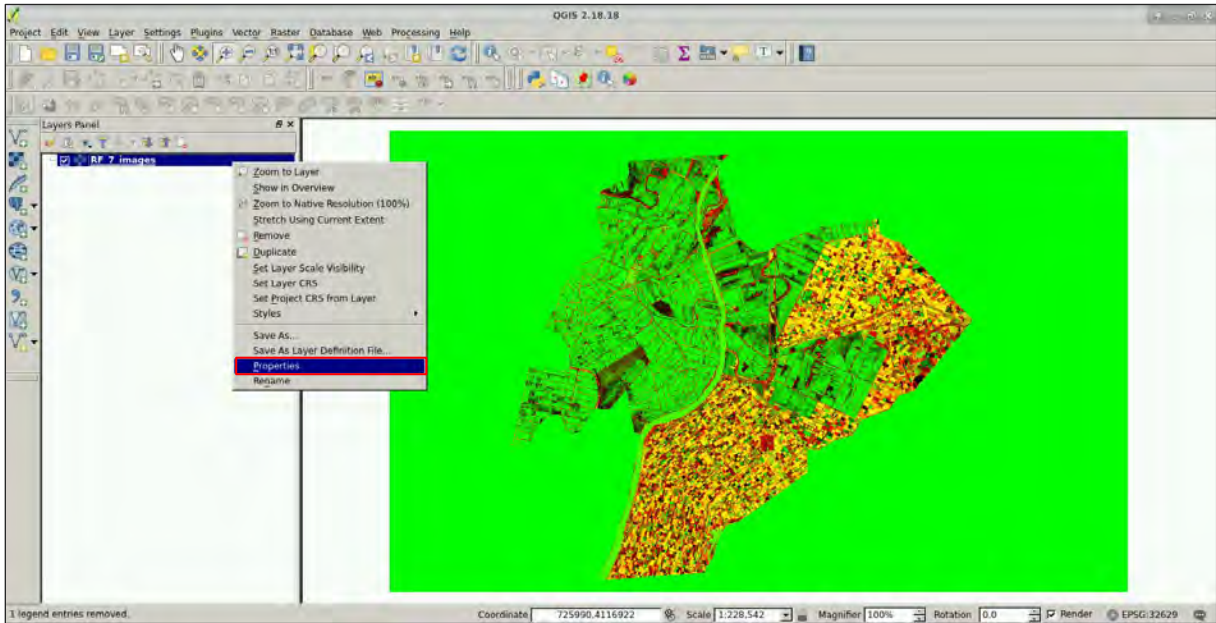
Path: *shared/Training/LAND01_CropMapping_Seville/Processing/RandomForest/*



Minimize SNAP and open QGIS (Applications -> Processing -> QGIS Desktop). Press the *Add Raster Layer* button (). Navigate to the following path and select the Random Forest classification GeoTIFF file. Click Open.

Path: *shared/Training/LAND01_CropMapping_Seville/Processing/RandomForest/*

The classification product is open as a multiband raster file. To change the visualization, right click on opened file and select *Properties*.



Select the *Style* tab on the left panel and choose the following parameters:

Render type: Singleband pseudocolor

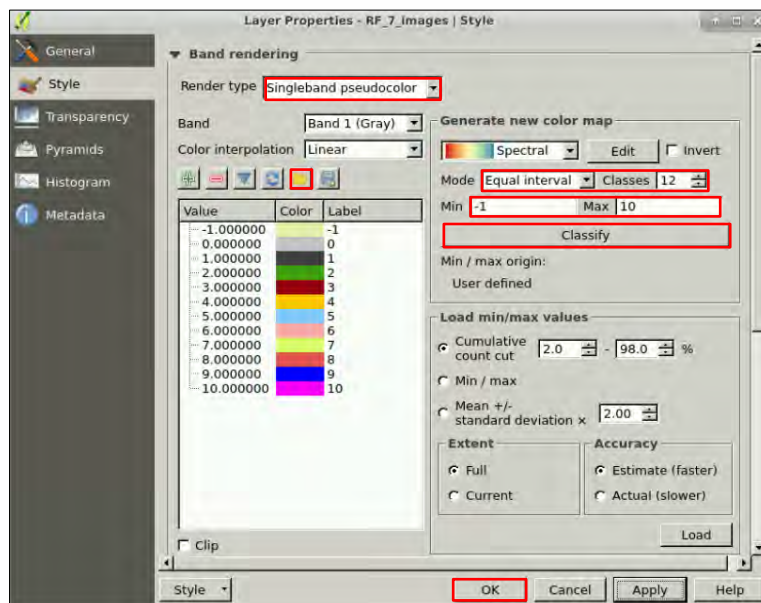
Mode: Equal Interval

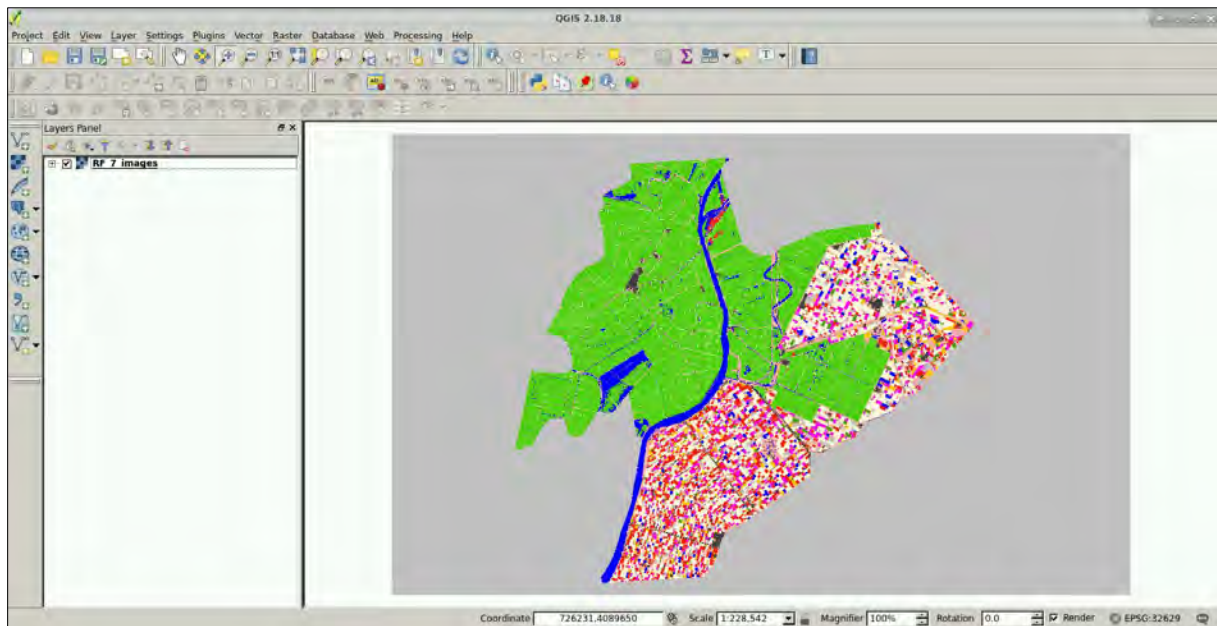
Classes: 12

Min / Max: -1 / 10

Press *Classify*. You can choose your own colours or use a predefined colour palette. Press the 'Load Colour Map' icon (📁), navigate to the following path, select *Colour_Palette_QGIS.txt* and click *OK*.

Path: *shared/Training/LAND01_CropMapping_Seville/AuxData/Colour_Palette/*





THANK YOU FOR FOLLOWING THE EXERCISE!

8 Further reading and resources

Breiman, L. (2001). Random Forests. *Machine Learning*, 45, 5–32, 45(1), 5–32.

Mentch, L., & Hooker, G. (2016). Quantifying Uncertainty in Random Forests via Confidence Intervals and Hypothesis Tests. *Journal of Machine Learning Research*, 17(1), 1–41.
<http://doi.org/10.1080/10618600.2016.1256817>

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