

SEO Laboratory



→ EARTH OBSERVATION SUMMER SCHOOL

Earth System Monitoring & Modelling

scientific exploitation of operational missions

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Citizen Generated Content and FOS Participative Platforms: VGI



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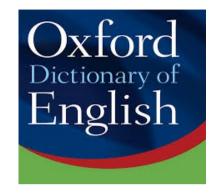
Citizen science and VGI

Quality Assessment of OpenStreetMap Data

Our systems and platforms



Citizen science: scientific work undertaken by members of the general public, often in collaboration with or under the direction of professional scientists and scientific institutions.



June 2014

It is a fairly new name but an old practice





Citizen science

- Set of practices in which citizens participate in data collection, analysis and dissemination of a scientific project (Cohn 2008)
- Classification (Haklay 2013)
 - 'classic' citizen science: amateurs engaged in traditional scientific activities
 - community science: measurements and analysis carried out by amateurs in order to set action plans to deal with environmental problems
 - citizen cyberscience: use of computers, GPS receivers and mobile phones
 - x volunteered computing: citizens download data, run analyses on their own computers and send back data to the server
 - **×** volunteered thinking: citizens perform classification works
 - *x* participatory sensing: applications centered on mobile phones capabilities



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Citizen Science and Europe

 JRC Summit Technical Report "Citizen Science and Smart Cities" - February 2014 (Max Craglia and Carlos Granell)



https://ec.europa.eu/jrc/en/publication/eur-scientific-and-technical-research-reports/



Citizen- Generated Geographic Information

: Typology of Citizen-Generated Geographic Information

Explicitly Geographic		Implicitly Geographic	
Explicit or Active Volunteering	This is "True" Volunteered Geographic Information in the strictest sense. Examples include Open Street Map.	Volunteered (geo)spatial information (VSI). Examples would include Wikipedia articles about non-geographic topics, which contain place names	
Implicit or Passive Volunteering	Citizen-generated geographic content (CGGC). Examples would include any public Tweet referring to the properties of an Identifiable place.	Citizen-generated (geo)spatial content (CGSC) such as a Tweet simply mentioning a place in the context of another (non- geographic) topic.	

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Citizen Observatories Projects

GEOSS Citizen Observatories https://www.youtube.com/watch?v=05aWijbfxq4





Citizens as sensors



http://vgibox.eu/

Mapping and the Citizen Sensor

Home The Action V Working Groups V Meetings V About COST

http://www.citizensensor-cost.eu/



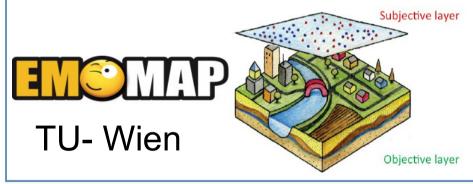
COST Action TD1202 is an EU funded inter-disciplinary networking activity that involves almost 30 countries and seeks to enhance the role of citizen sensors in mapping.

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Other Projects (just a selection...)

The EmoMap project

- To create a "subjective" layer aggregating people's <u>subjective</u> <u>experiences in space</u>, and overlay this layer on top of existing "<u>objective</u>" geospatial data
 - Crowdsourcing approaches, social media data analysis
 - Geography (GIScience), Environmental Psychology, Urban Planning, Architecture, Policy Making, Computer Science, ...
 - An important source for Smart City: as humans are recipients of smart services



http://cartography.tuwien.ac.at/emomap/

Open Air Lab OPAL Surveys

- Community Scientists staff who work directly with communities and schools to carry out:
 - Survey activities
 - Training events
 - Talks, workshops, conferences
- · Surveys can also be carried out independently
- Survey results are entered on the OPAL website
- So far, over 50,000 submissions
- Over 10% survey return rate



http://www.opalexplorenature.org/

www.everyaware.eu/







The name was coined in 2007 (Goodchild), but it was already a real practice.

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Geopaparazzi. Because not all paparazzis are evil!

Volunteered Geographic Information: OSM

- The most popular project of Volunteered Geographic Information (VGI):
 - v born in 2004 for streets, then evolved into the largest, most diverse, most complete & most up-to-date geospatial database of the world
 - increasing number of contributors (currently about 2.5M)
 - database available under an open license (ODbL)
 - increasing interest from the academic community



Quality assesment of OpenStreetMap Data

- Earliest researches on OSM quality assessment were all focused on streets, that were the initial mapping target of the OSM project.
- Recently, researches on other OSM elements have begun to appear:
 - completeness and accuracy of OSM point features related to schools in Denver (Jackson et al. 2013)
 - accuracy of OSM land use features in Portugal and Germany (Estima and Painho, 2013; Jokar Arsanjani et al. 2015)
 - completeness and accuracy of the public properties mapped in OSM for Victoria (Kalantari and La, 2015)
 - completeness and accuracy of building footprints in OSM



Assessing street quality

- ✓ Novel methodology to compare OSM and authoritative road datasets:
 - fully automated
 - focused on spatial accuracy and completeness
 - flexible, i.e. not developed for a specific dataset
 - **x** made of required and optional operations
 - x users can define the value of the parameters involved to adapt the procedure to their specific authoritative datasets
 - x users are supposed to be familiar with the authoritative dataset used as reference
 - built with FOSS4G (Free and Open Source Software for Geospatial)
 - **x** reusable and extensible in case of need
- Currently developed as 3 GRASS GIS modules:
 - written in Python
 - available with a Graphical User Interface (GUI)



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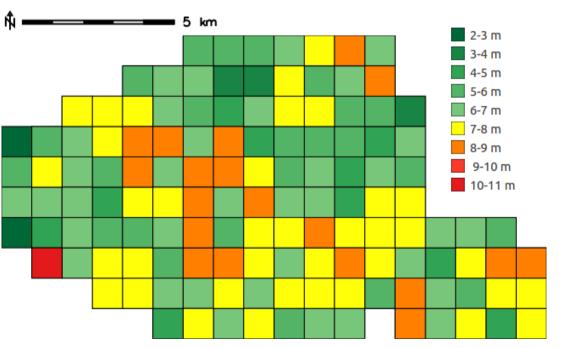


Step 1

sensitivity analysis on the buffer width

- Step 2
 - cleaning of OSM dataset to make it comparable with the authoritative dataset

Step 3

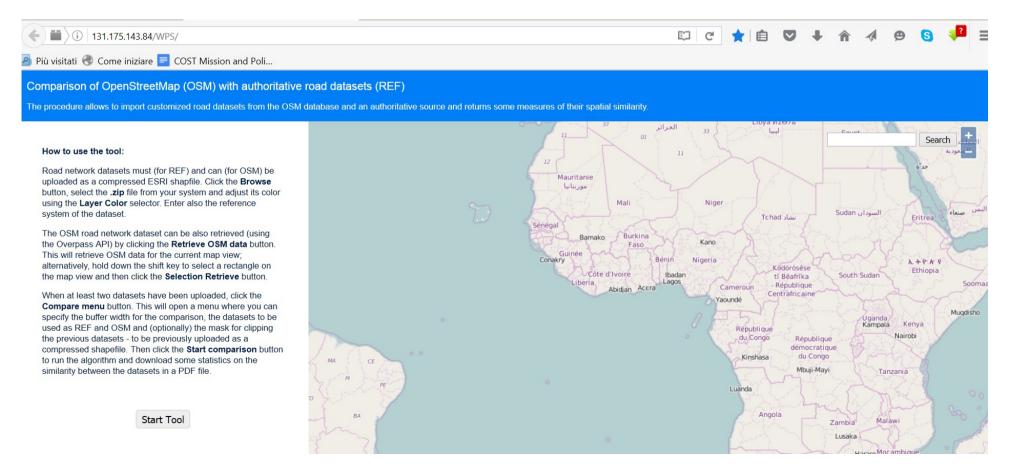


grid-based evaluation of OSM accuracy

Example max deviation of OSM from IGN : case study Paris



- ✓ Step 1 → WPS client http://131.175.143.84/WPS
- ✓ Steps 2/3 → code available in github https://github.com/MoniaMolinari/OSM-roads-comparison



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AUTHORS	AREA	PURPOSE	RESULTS
Goetz and Zipf (2012)	Germany	Investigate the suitability of OSM data for 3D building model generation	Low completeness (30%); only the 0.5% of buildings with info about the number of levels
Hecht et al. (2013)	North Rhine Westphalia and Saxony (Germany)	Evaluate the OSM building completeness by means of a comparison against an official dataset.	Low degree of completeness; higher in urban areas
Fan et al. (2014)	Munich City (Germany)	Comparison between OSM and ATKIS (Authority Topographic- Cartographic Information System) buildings	High completeness; deficiencies in attributes; high similariry in shape;offset of 4 m
Tornros et al. (2015)	Ludwigshafen Municipality (Germany)	Assessment of OSM building completeness by means of a comparison with the official cadastre data	Analysis of the different assessment methods and their effects on the completeness results
Fram et al. (2015)	Sheffield, Leeds and london (UK)	Investigate the potential of OSM data in Risk Management Solutions. Comparison with Ordnance Survey dataset.	Completeness very variable both within and among UK cities
Klonner et al. (2015)	Bregenz (Austria)	Combine up-to-date OSM building data with the rarely up-to-date LiDAR information	Satisfactory level of upgrade of OSM dataset; suitability for the proposed application



Building quality assesment

- The quality assessment has been performed by comparing the OSM data (downloaded in January 2016) against the building layer of the official vector cartography of Milan Municipality (produced in 2012).
- Two different quality parameters were evaluated:
 - completeness evaluation based on methods suggested by literature
 - positional accuracy evaluation based on a novel, quasi-automated matching algorithm developed at GEOlab – PoliMI
- The completeness analysis was performed through the area ratio unit-based method proposed by Hecht et al. (2013)

 $C = A_{OSM} / A_{REF}$

C = completeness

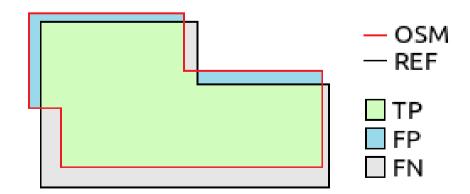
 A_{RFF} = total area of reference buildings

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 A_{OSM} = total area of OSM buildings

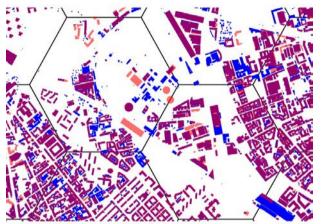


- The area ratio method can introduce an overestimation of C due to exceeding data available in OSM. For this reason the computation of three additional rates is recommended:
 - True Positive (TP): the areas of agreement between the datasets
 - False Positive (FP): the OSM building areas which do not exist in the REF dataset
 - False Negative (FN): the REF building areas which do not exist in the OSM dataset.









DATASETS



- **REF:** buildings of Milan (Lombardy Region)
- **OSM:** building of Milan (OpenStreetMap)
- GRID: hexagonal grid

For each cell *k* of the grid:

• Extract the CELL

v.extract input=GRID output=CELL cats=k

• Extract OSM buildings

v.overlay ainput=OSM atype="area" binput=CELL btype="area" operator="and" output=OSM_CELL

- Extract REF buildings
 v.overlay ainput=REF atype="area" binput=CELL btype="area" operator="and" output=REF_CELL
- Calculate the area of OSM_CELL and REF_CELL v.to.db map=OSM_CELL (or REF_CELL) option= "area" -p + Python code





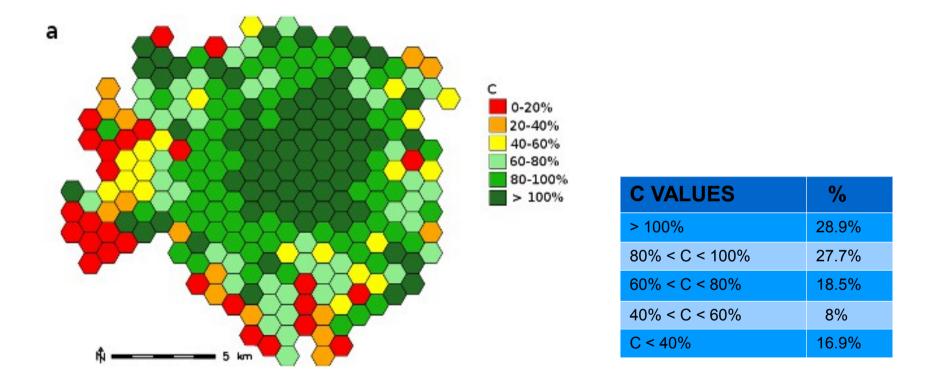
For each cell *k* of the grid:

- Calculate the completeness index as (Area_{OSM}/Area_{REF})*100
 Python code
- Extract the overlapped area between OSM_CELL and REF_CELL v.overlay ainput=OSM _CELL atype="area" binput=REF_CELL btype="area" operator="and" output=TP
- Calculate area of TP
 v.to.db map=TP option= "area" -p + Python code
- Calculate TP rate as (Area_{TP}/Area_{REF})*100 Python code



Completeness analysis results

Spatial distribution of completeness rate in Milan area:

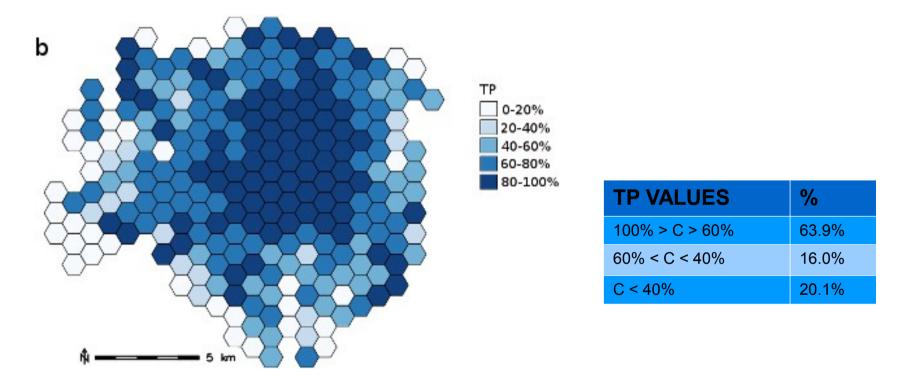


The completeness of the OSM dataset is very high in the city center and gradually decreases when moving towards the periphery.



TP analysis results

Spatial distribution of TP rate in Milan area:



 Results largely confirm the trend observed for C: OSM completeness is higher in the city center and gradually lower in the peripheral areas.



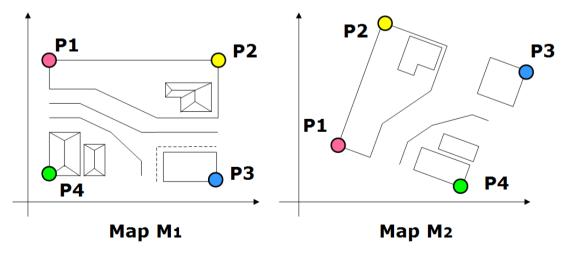
Positional accuracy assessment

Algorithms allowing to:

- the quasi-automated detection of homologous pairs between REF and OSM by means of geometric, topological and semantic analyses;
- the application of a set of warping transformations to the OSM dataset in order to optimize its match with the REF dataset

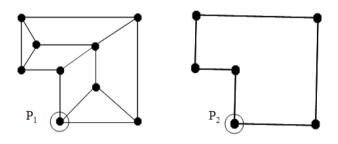
Homologous pairs:

A point PA on map M1 is homologous of a point PB on map M2 if the geographic feature related to the two points "corresponds".

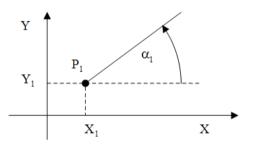




Different representation of the same feature:



Angle (direction) of a segment:

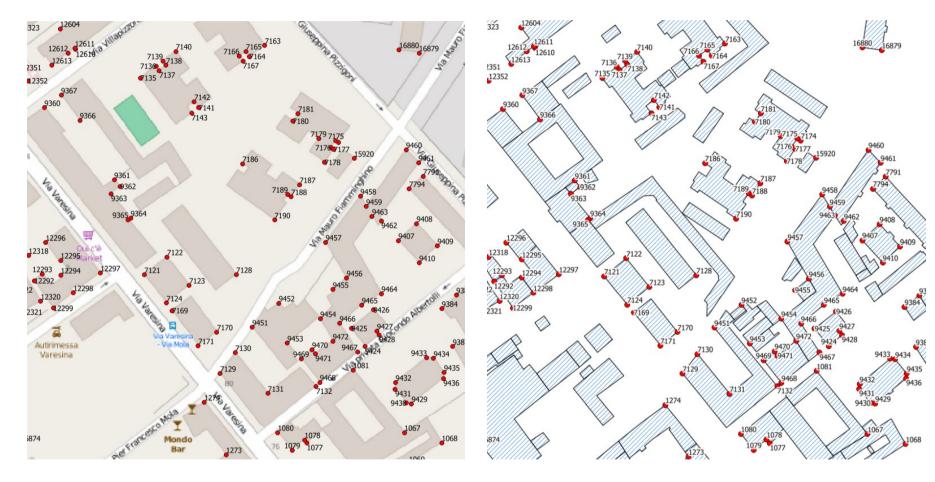


Examples of compatible – incompatible points:

Point P_1 on c_1	Point P ₂ on c ₂	Geometrical check	Angle relations	Result
\checkmark			$\alpha_1 < \alpha_{TOL}$ $\alpha_2 < \alpha_{TOL}$	Compatible points
_		α_1	$\alpha_1 > \alpha_{TOL}$ $\alpha_2 < \alpha_{TOL}$	Incompatible points



Positional accuracy assessment: results

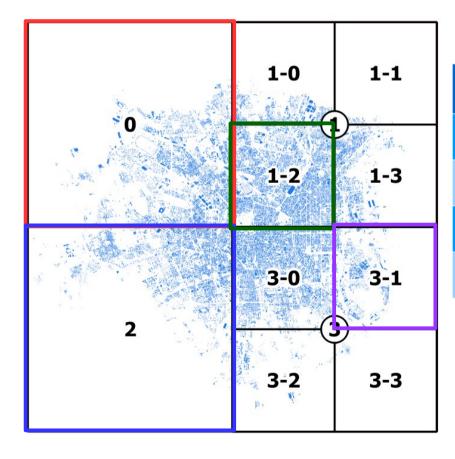


Homologous points OSM buildings Homologous points REF buildings



Positional accuracy analysis results

The number of homologous pairs detected is approximately 100 000



Cell	Points	Trasf.	ΔΥ μ [m]	ΔX μ [m]	d μ [m]
	19135	None	0.45	0.46	0.81
1-2	16480	None	0.35	0.46	0.77
2	18732	None	0.44	0.43	0.79
3-1	4318	None	0.28	0.41	0.71

The positional accuracy is the same in both Milan center and periphery.



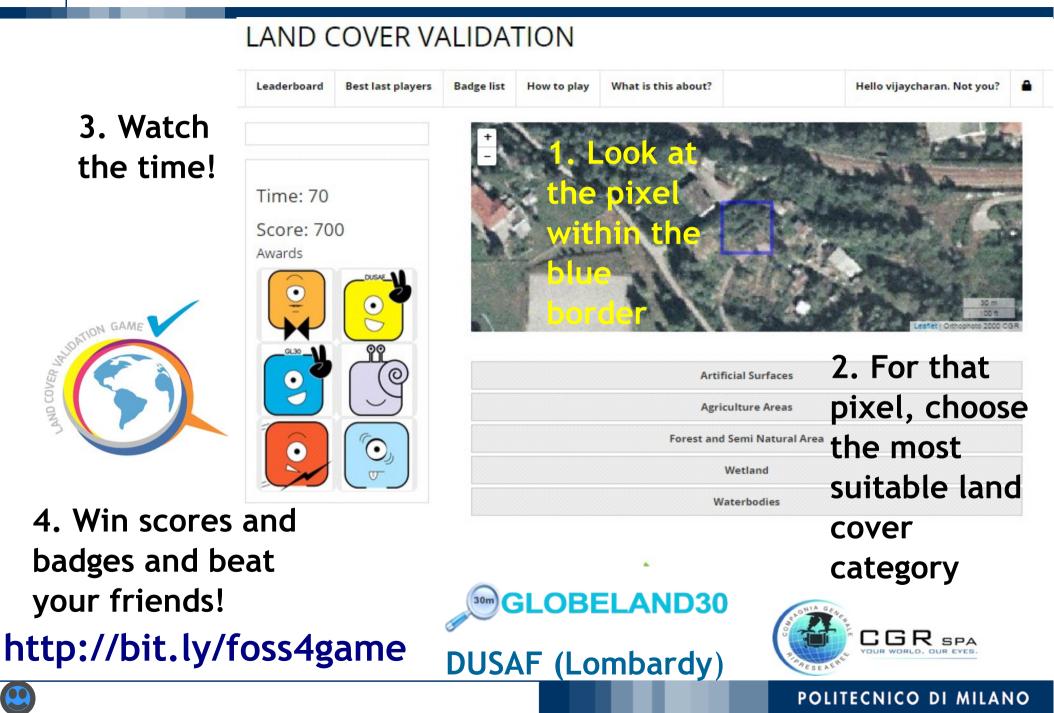
Positional accuracy analysis results

Using the homologous points detected, it is possible to estimate the parameters of an affine or MR spline transformation to remove the systematic translation and reduce the mean distance: this warped layer may become the new version in the OSM database

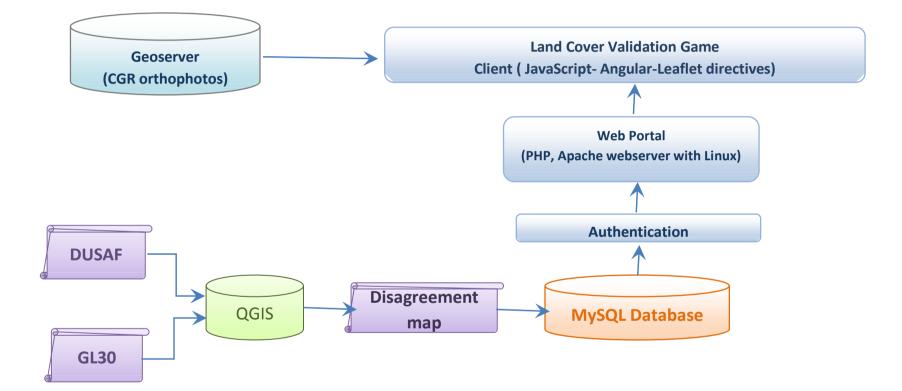
Points	Trasf.	d <i>μ</i> [m]
19135	None	0.81
	Affine	0.56
	Spline MR	0.50
16480	None	0.77
	Affine	0.57
	Spline MR	0.50
18732	None	0.79
	Affine	0.55
	Spline MR	0.49
4318	None	0.71
	Affine	0.55
	Spline MR	0.48
	19135 16480 18732	19135 None Affine Spline MR 16480 None Affine Spline MR 18732 None Affine Spline MR 4318 None Affine



Volunteered thinking



Land cover validation game architecture



DUSAF Agreements	87 %
GLOBELAND30 Agreements	11 %
Disagreements	1 %



Participatory sensing applications







Street furniture

Biodiversity













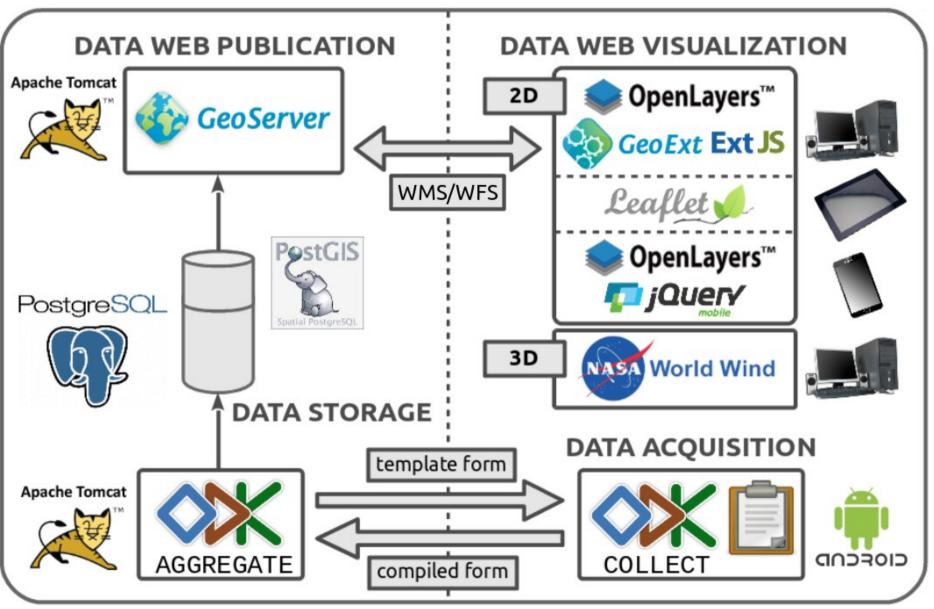




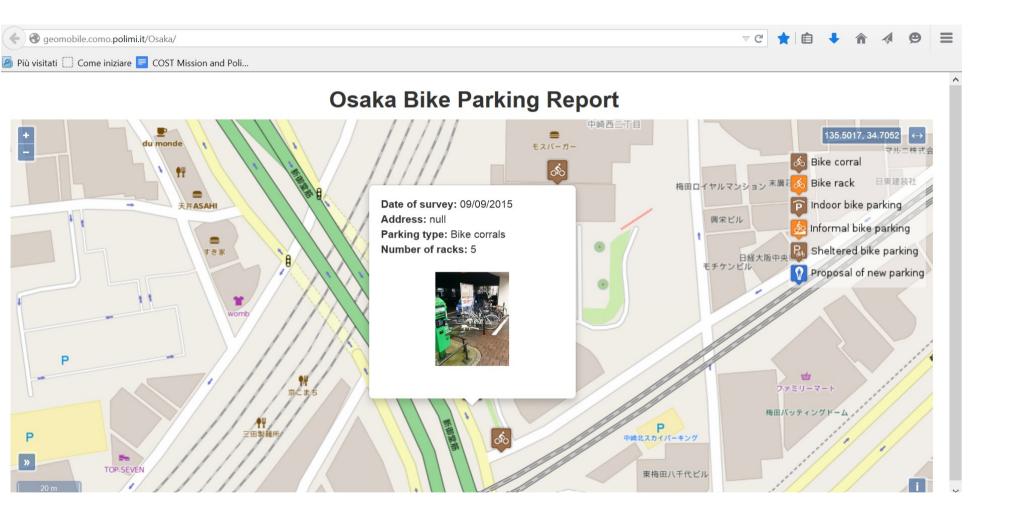
Participatory sensing FOSS architecture ³³

SERVER

CLIENT







OpenLayers http://geomobile.como.polimi.it/Osaka/



	INSTRUCTIONS		
STEP	WINDOWS	LINUX	
1) Install the Java Virtual Machine (JVM)	- Download and install <u>from here</u>		
2) Install the multimedia viewer	- Download and install from here		
3) Launch the Java Control Panel:	- Launch the Windows Start menu - Click on Programs - Find the Java program listing - Click on Configure Java	- Open the Terminal Window - Type: ControlPanel	
4) Set the JVM security exception:	- Click on the Security tab - Click on the Edit Site List button - Click Add in the Exception Site List window - Add the IP: 131.175.143.48		
5) Start the application	- Click here or on the banner below		
	Select Preferences in the Options menu of the 3D Viewer Check the VLC radiobutton, click the Browse button and select the following vlc executable file		
6) Configure the multimedia viewer	for 64bit version: C:\Program Files\VideoLANVLC\vlc.exe for 32bit version: C:\Program Files x86\VideoLANVLC\vlc.exe		

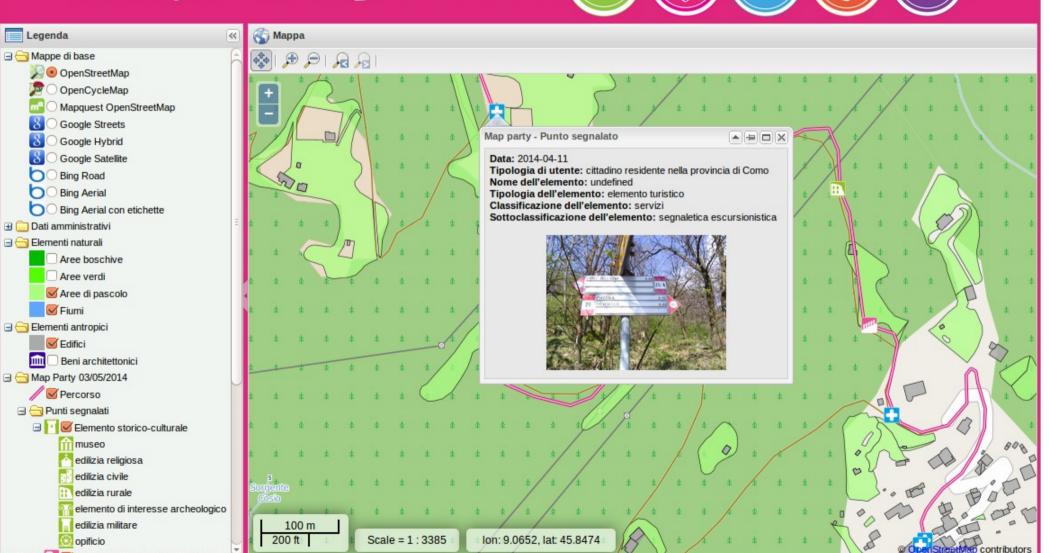


http://geomobile.como.polimi.it/policrowd2.0/ http://viaregina2.como.polimi.it/Osaka/



Mapping elements along cultural paths

MapParty! 3 MAGGIO 2014



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Via Regina Cross-platform App

The application relies on Apache Cordova mobile application development framework.

- The map is built using mobile-friendly Leaflet library.
- The data is stored in JSON format in a document-oriented NoSQL PouchDB/CouchDB database.
- Moreover the data stored in the ODK Aggregate server is displayed.

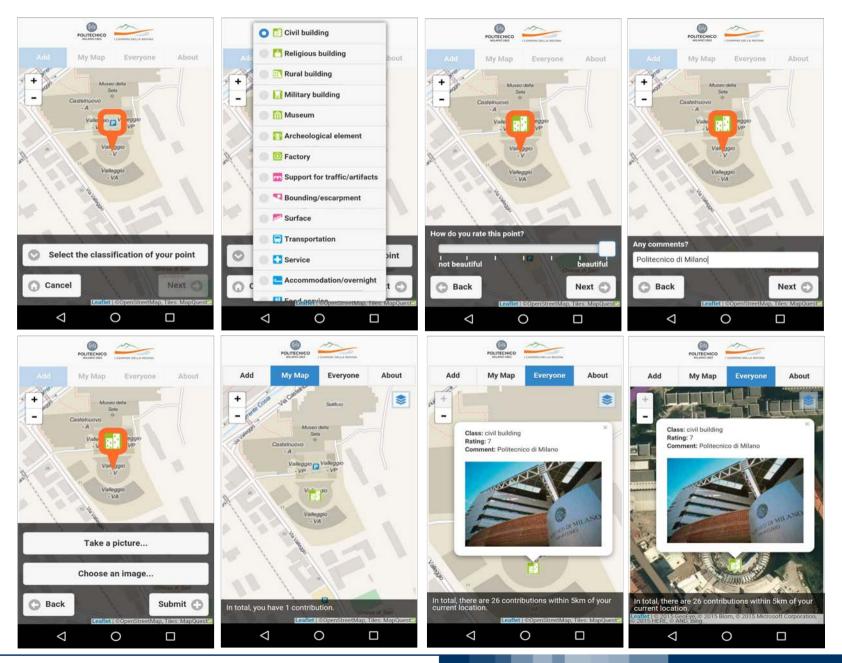
The App is available as Web App

http://viaregina3.como.polimi.it/app/

or in Play and Apple Stores (Via Regina)

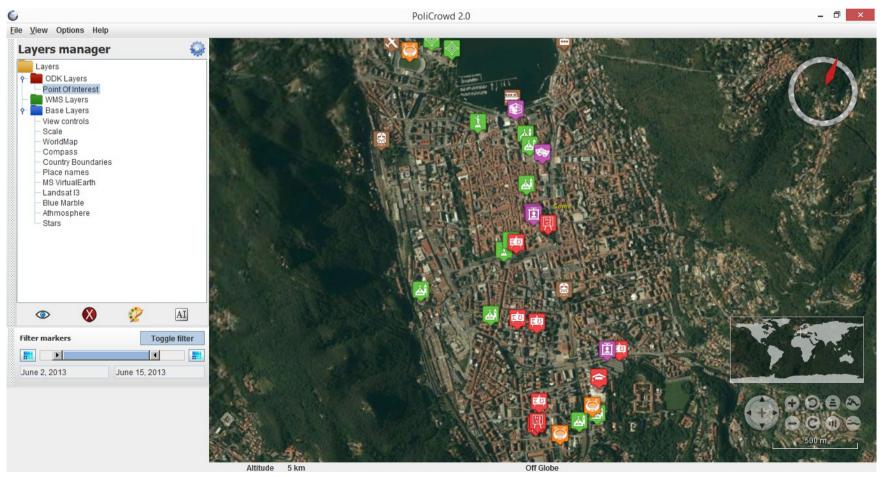


Via Regina Cross-platform App



PoliCrowd – A social World Wind platform³⁹

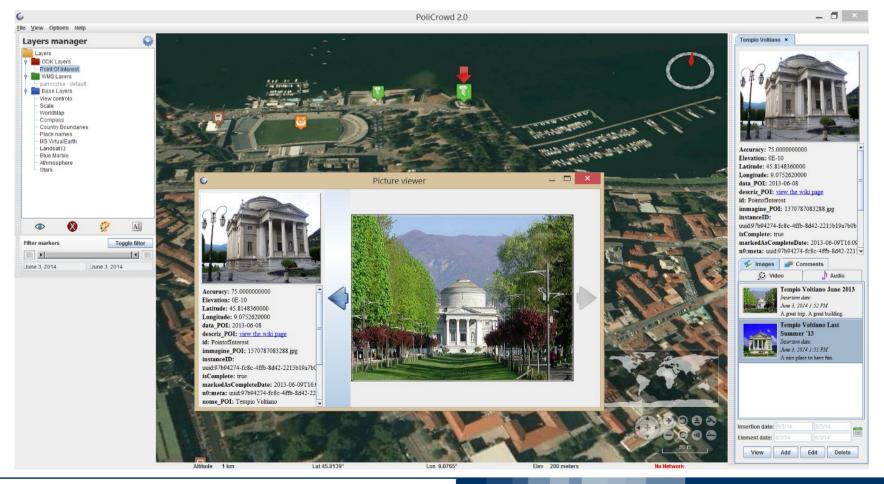
- ✓ Web-based 3D participatory platform, ongoing (Brovelli et al. 2013)
 - Born for tourism, culture, sports & transportation Points Of Interest (POIs)
 - POIs 3D visualization on NASA World Wind virtual globe
 - participative functionalities: POIs collaborative enrichment & project creation





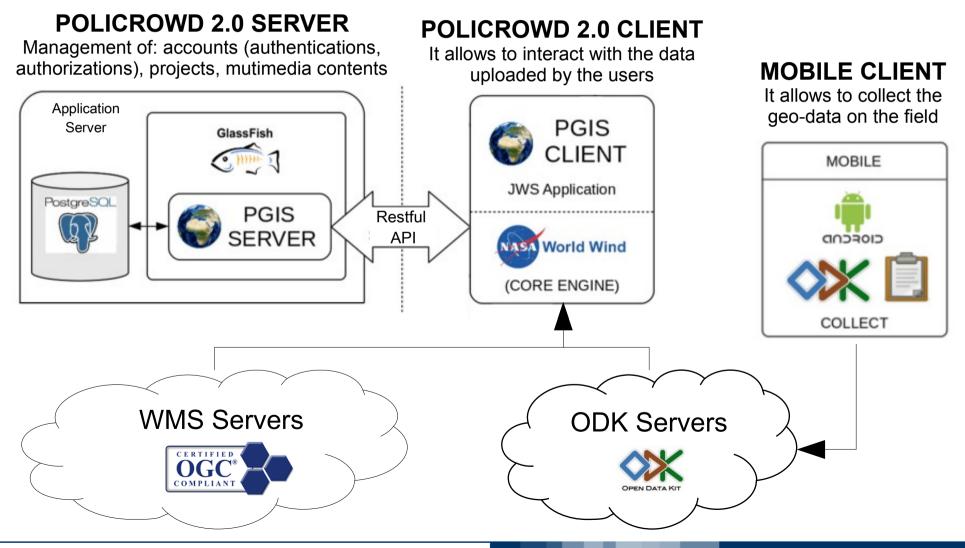
PoliCrowd2.0 – A social World Wind platform

- Web-based 3D participatory platform
 - non mono-thematic application connection to any WMS and ODK server
 - customizable data styling & multimedia support
 - support for time dimension (4D visualization)

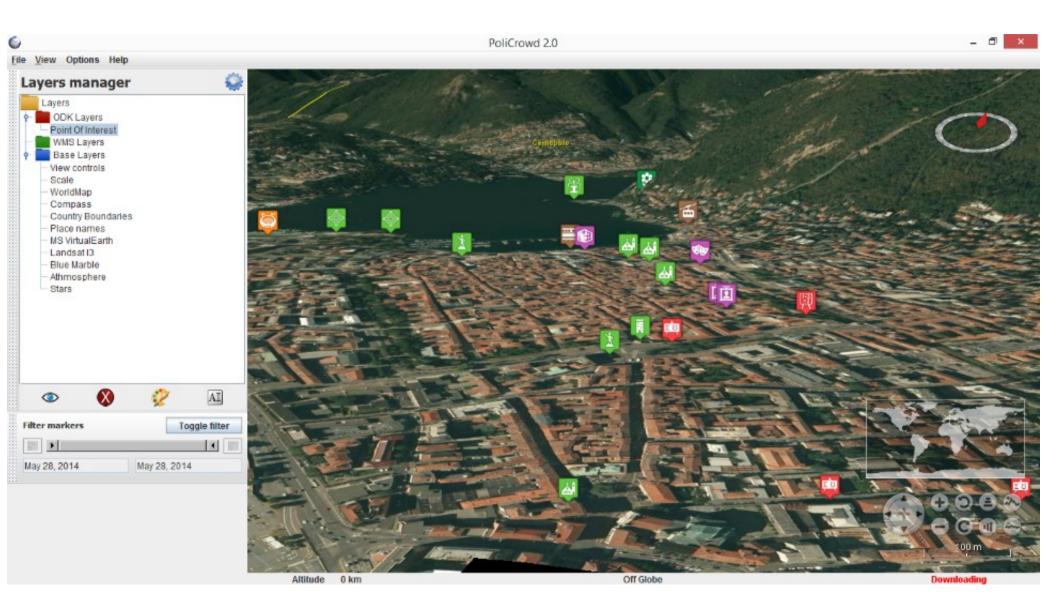




In addition to the WMS servers, PoliCrowd 2.0 has also an innovative capability to directly connect with any Open Data Kit (ODK) server available on the network and publish the related data collected by the community











Every user can:

- create, save and share their own projects
- populate them with both WMS and ODK layers

WMS and ODK layers can be added:

- by entering the specific URL of the server
- by selecting from a default list, constantly updated by aggregating all the servers time to time inserted by the community

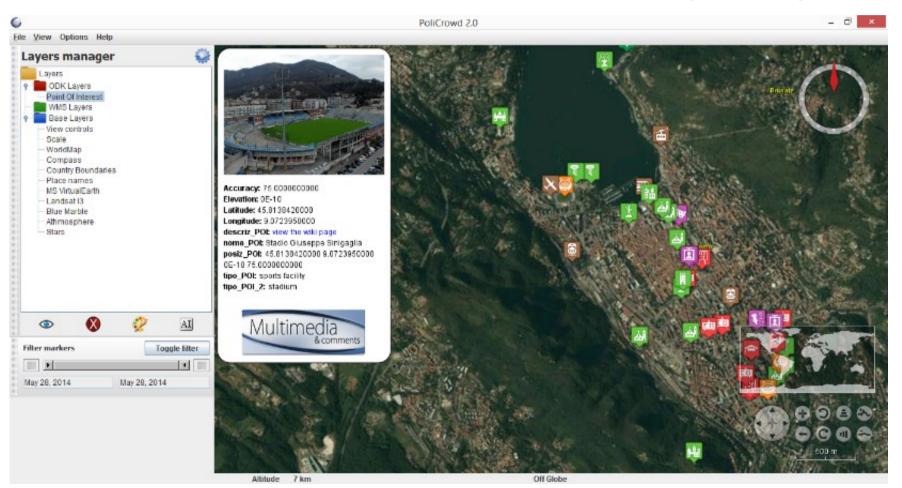
	Add new server			
Server type Name Description URL Username Password	WMS VMS ODK			
	Servers/layers	; manager		
	Servers http://geomobile.como.polimi.it:8080/ODKAggregate Soil Threats, luca WMS Loc, luca	Layers USA Population : Population in the United USA Population : Population in the United USA Population : Default Polygon		
		Tasmania cities : Capital cities Tasmania roads : Default Styler for simp Tasmania state boundaries : Green poly Tasmania water bodies : Blue lake		

All the projects are publicly accessible by design, in order to promote the community participation.



Policrowd 2.0: POIs information

- Clickable POIs placemarks
- Visualization of the ODK Collect-reported information (including picture)

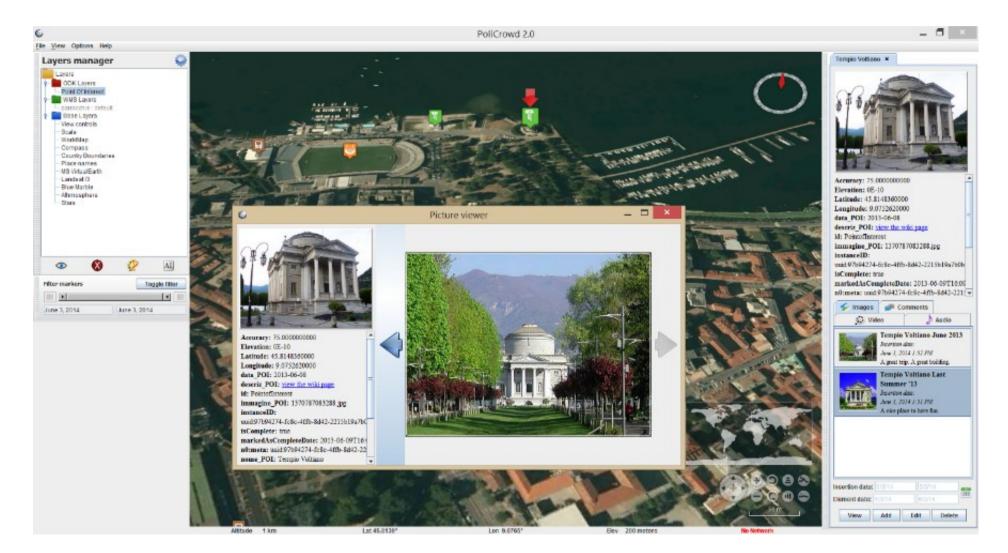


- ODK layers are fully customizable, thanks to a suitable layer management interface
- Users select the fields they want to display for each layer of a given project, and personalize marker icons by picking them from a default collection or providing them manually
- Styles are also shareable, so that users can take advantage of the already available icons provided by other users in their own projects

6	ODK Layer Preferences	×					
Fields visibility Layer icons							
		Icon chooser ×					
Active field: tipo_POI_2	Load shared style: - None -	Restaurants and b		Tourism	Transportatio		
Default		Letters and Culture entertail		Media vents H	ealth and educe		-
Default			tus	-		R	
concert	Aboriginal	Airshow-2	Anniversary	Anthropo		1	
university	Ð	1	Ø	(
middle school	Art-museum	Billiard-2	Bowling	Bullfight	Bustour		
हिंध high school		Casino-2	Cinema	Circus	Coins	Comedyclub	
Share style	Default icon Pick from collection Pick f	rom file					

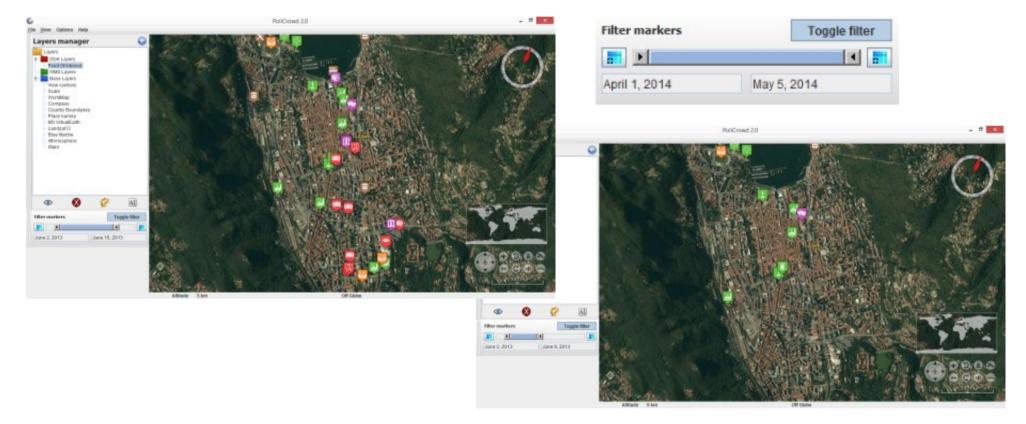
Policrowd 2.0: Collaborative POIs characterization

Every marker is open to collaborative contribution: everyone can add their POIrelated textual (comments) and multimedia contents (images, audios and videos)



Policrowd 2.0: the 4th dimension (time)

- The time bar enables temporal filtering of all the POIs on the globe, just by picking a given date or setting a range
- More in-depth navigation through the content



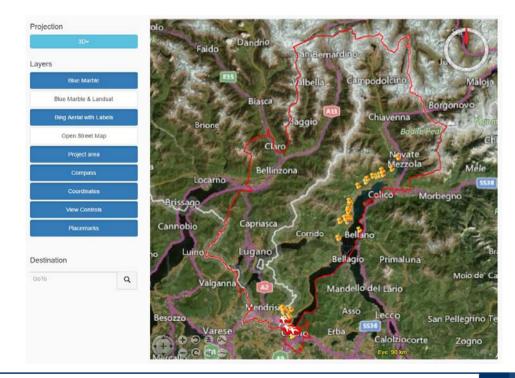
• The same capabilities are also made available for multimedia data, which can be independently filtered according to the date of the content upload or (if provided) to the actual date of the element, e.g. useful to filter historical data



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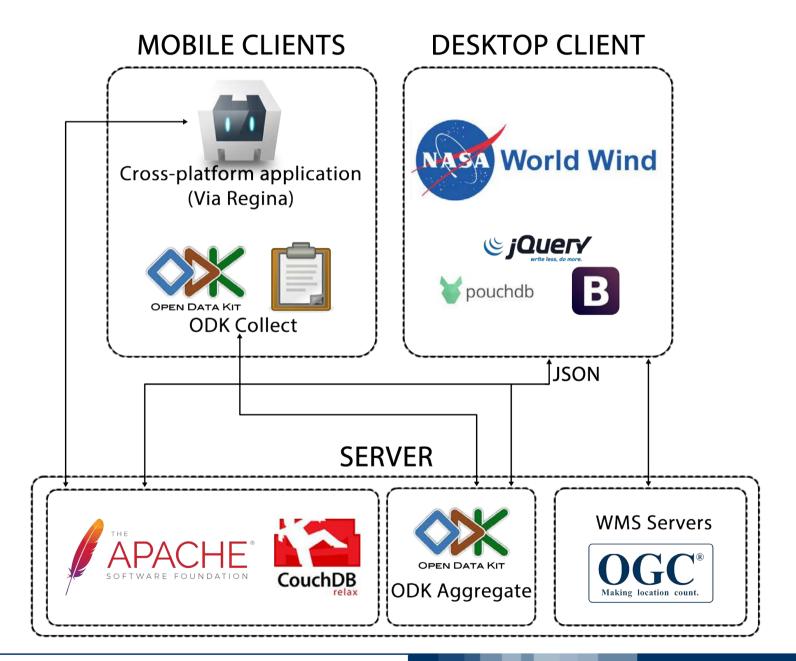


- The virtual globe, developed using NASA Web World Wind API is able to display data stored in the ODK Aggregate server of Via Regina project and in CouchDB database of aforementioned cross-platform application, both on desktop and on mobile devices through WebGL supported browsers.
- http://viaregina3.como.polimi.it/WorldWind/





WWW Policrowd Architecture





Thanks for your attention!

Thanks to all people contributing on these topics: Carolina Arias, Irene Celino, Eylul Kilsedar, Marco Minghini, Monia Molinari, Daniele Oxoli, Marco Pelucchi, Gabriele Prestifilippo, Vijay Venkatachalam, Giorgio Zamboni, Mayra Nucci Zurbaran

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