



P. Cipollini, H. Snaith - A short course on Altimetry

Altimetry 2 – Altimeter data processing (from satellite height to sea surface height)



Satellite height to sea surface lifremer height

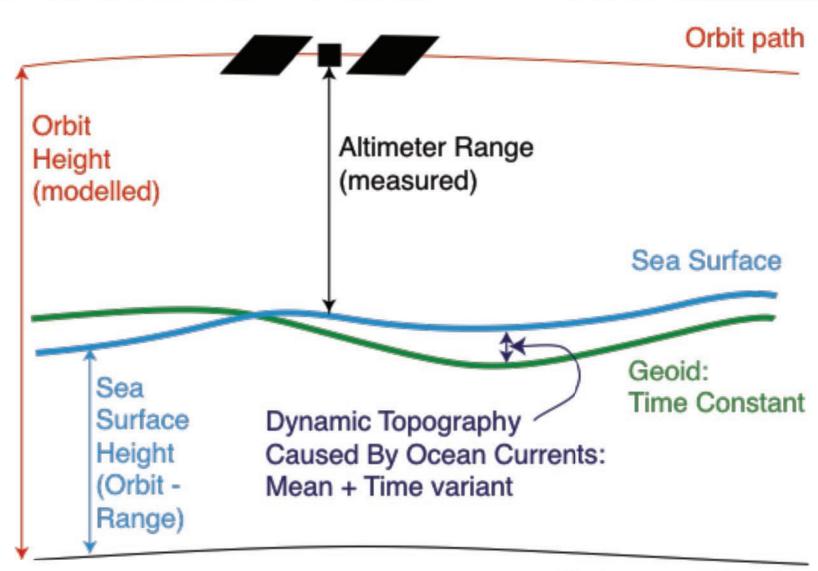


- The altimeter measures the altitude of the satellite above the earth surface
- The oceanographer wants a measurement of sea level
- Steps that need to be taken
 - Instrument corrections
 - Platform corrections
 - Orbit determination
 - The effect of refraction: ionospheric, wet/dry tropospheric
 - Sea surface effects









Reference Ellipsoid





Ifremer Altimeter Corrections & Orbits



- Platform Corrections due to instrument geometry and other effects on the satellite
- Orbits must be known as accurately as possible
- Correction for atmospheric delay effects
- Correction for surface effects
- Correction for barometric effects
- Estimating/Removing the geoid
- Estimating/Removing tides





Platform corrections



- The Earth is not round.
 - The true shape of the earth is the geoid
 - As the satellite orbits the Earth it moves closer and further away responding to changes in gravity
- Satellite is moving towards and away from the earth
- A Doppler correction applied to range
- Other platform corrections are applied to range and need not worry the scientist...
 - Eg correction for the distance between the centre of gravity of the spacecraft and the altimeter antenna
- ...unless something goes wrong
 - eg the USO (Ultra Stable Oscillator) range correction for RA-2 on board Envisat



Ifremer Orbits



- From the altimeter measurement we know the height of the satellite above the sea surface
- We want to know the height of the sea surface above a reference (the geoid or an ellipsoid)
- Therefore we need to know the satellite orbit, to a few cm or less, relative to the same reference
- This is done through a combination of satellite tracking and dynamical modelling.
- A dynamical model is fitted through the tracking data. Solutions cover a few days at a time.
- The tracking information comes from DORIS, GPS and Satellite Laser ranging (SLR)



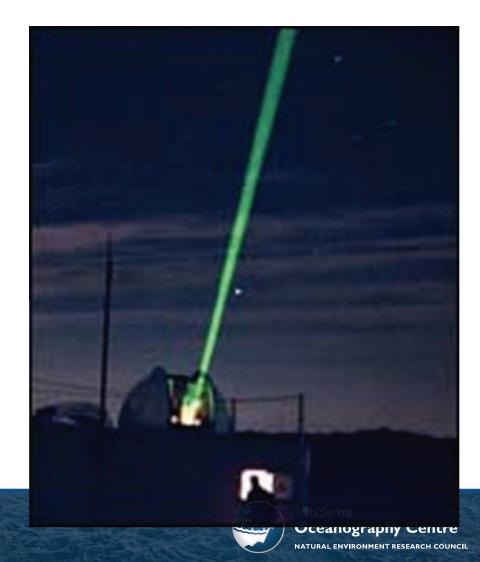






DORIS

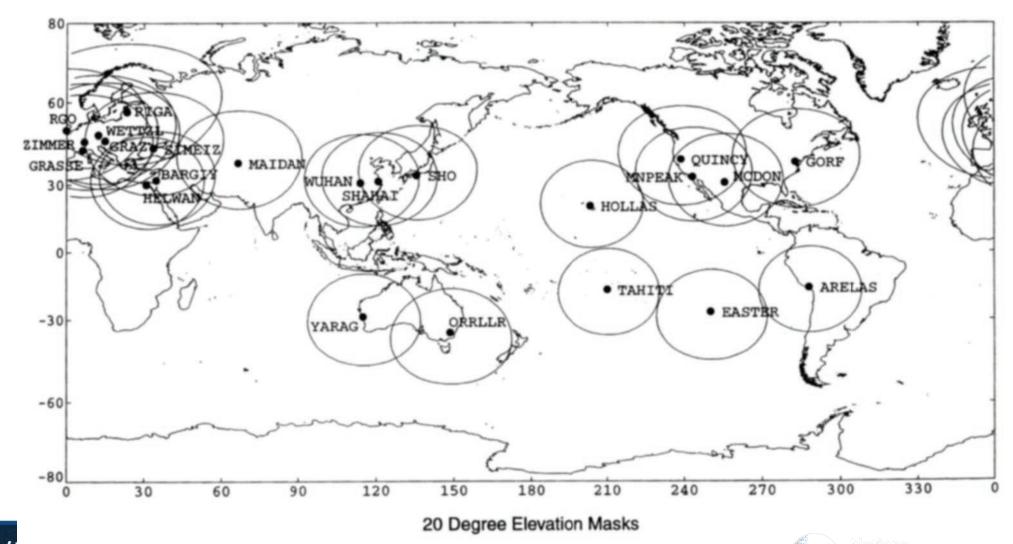
SLR





Ifremer SLR Stations



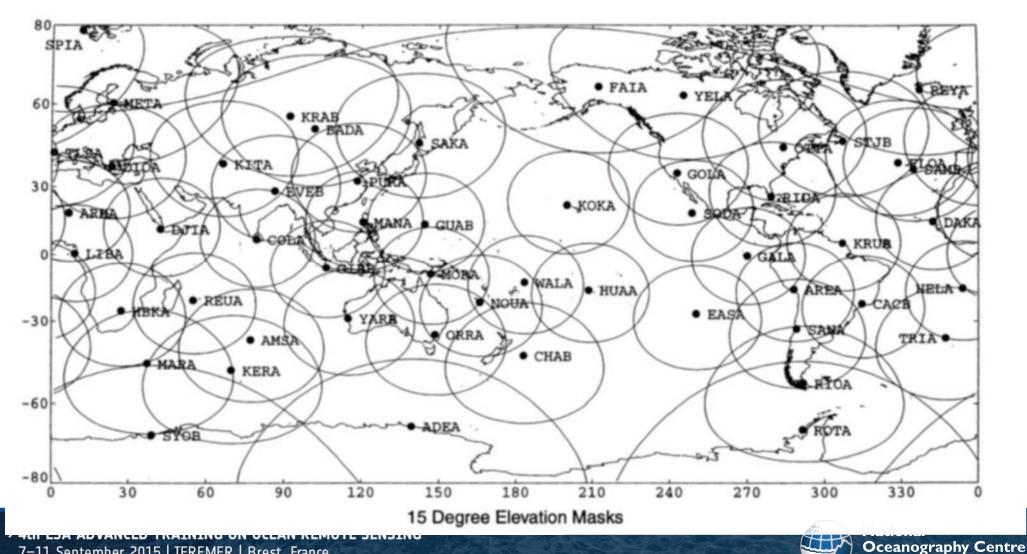




Ifremer DORIS stations



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Ifremer Quality of orbits



- The quality of orbits are measured by the reduction of crossover differences and by comparison to SLR stations
- TOPEX/Poseidon and Jason orbits are now good to the ~2-cm level
- ERS-2 and ENVISAT: ~3 cm
 - more affected by drag, as in lower orbit, and much larger, than T/P and Jason



Topex/Poseidon latest Orbit Ifremer Error Budget



- Size of observed error in orbit model, by parameter
 - Gravity, 2.0 cm
 - Radiation pressure, 2.0cm
 - Atmospheric drag, 1.0 cm
 - Geoid model, 1.0 cm
 - Solid earth and ocean tide, 1.0 cm
 - Troposphere, < 1 cm
 - Station location, 1.0 cm
- ⇒ Total radial orbit error, 3.5 cm
 - Mission design specification, 12.8 cm
- With latest, state-of-art models, the above total orbit error decreases to ~2.0 cm





Ifremer Atmospheric Corrections



- As the radar signal travels through the atmosphere it is slowed down w.r.t. speed of light in the vacuum
- Since we need speed to estimate range, we must correct for this effect.
- There are three parts of the atmosphere that must be taken into account
 - lonosphere
 - Dry troposphere
 - Wet troposphere



Ifremer lonospheric correction



- Caused by free electrons in the ionosphere
- Frequency dependent so it can be measured with a dual frequency altimeter:

ERS-1/2 × Topex ✓ Jason-1/2 ✓ Envisat ✓ (only up to 17/01/08) GFO × Cryosat × AltiKa × (Ka band almost unaffected by ionosphere)

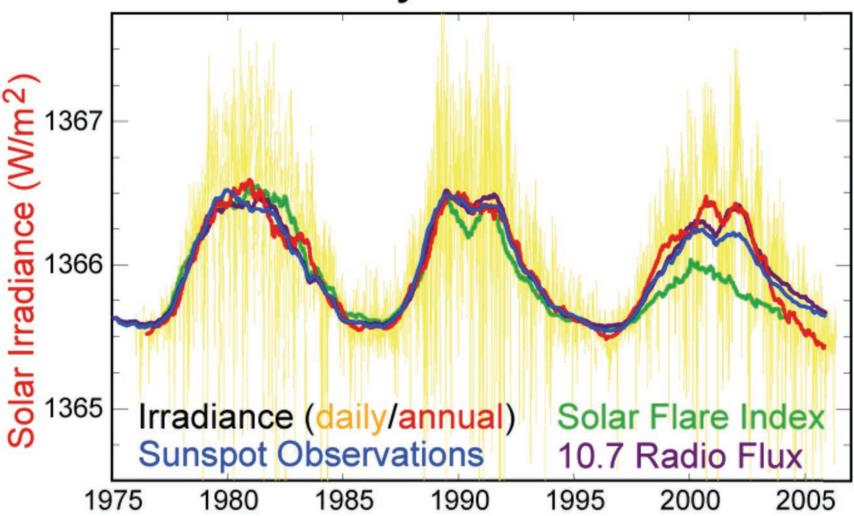
- Otherwise use a model or other observations from another dual frequency radar system (GPS, DORIS)
- Average value 45mm, s.d. 35mm
- Depends on solar cycle and time of day
- GIM (based on GPS, produced by JPL) is a good product to use for single-frequency altimeters







Solar Cycle Variations



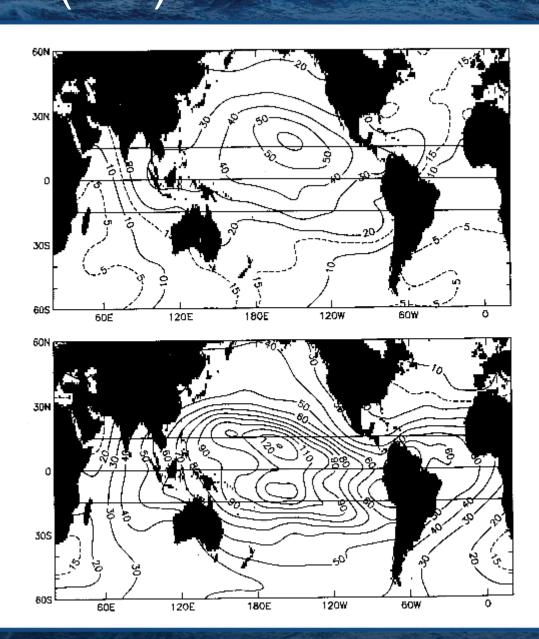
http://spaceodyssey.dmns.org/media/13466/solar-cycle-data.png



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Typical lono correction values (mm)





Low solar activity

High solar activity





Dry Tropospheric Correction



- Due to O₂ molecules in the atmosphere
- Derived from atmospheric pressure (from met models) by:

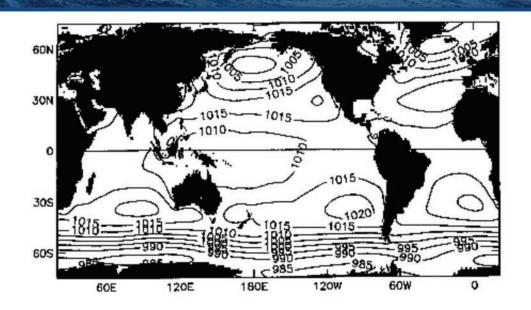
```
Dry_trop = 2.277 p (1 + 0.0026 cos(2 \times latitude)) (mm) (hPa)
```

Average value 2300 mm, s.d. 30 mm

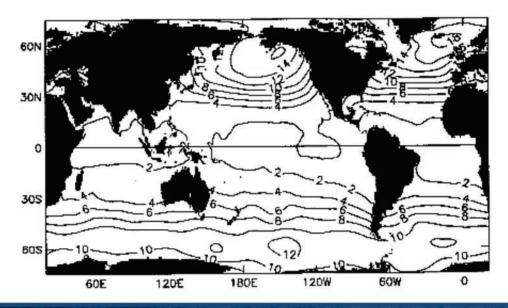








Winter DJF Air Pressure Mean (hPa)

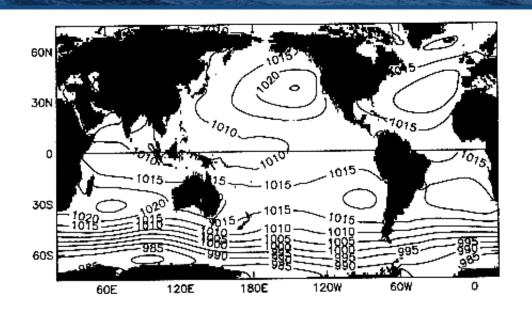


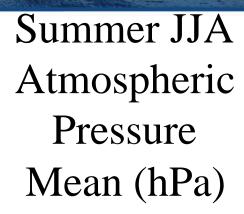
Standard deviation

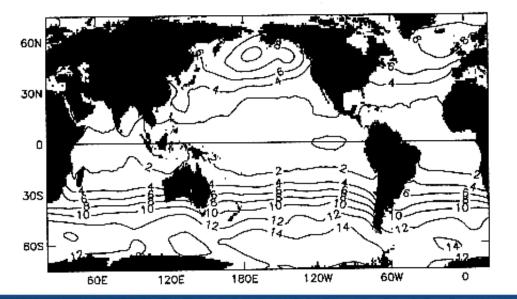












Standard Deviation



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Wet Tropospheric Correction



- Caused by water vapour in the atmosphere
- This is a difficult correction due to the high temporal and spatial variability of water vapour
- Average value 150 mm, s.d. ~50 mm
- Obtained by microwave radiometer on satellite
 - two frequency on ERS-1/2 and Envisat
 - three frequency on T/P and Jason-1/2
- Or from weather forecasting models (ECMWF)
- New approach: from GPS measurements and/or passive microwave radiometers on other satellites
 - GPD and DCOMB corrections by Univ. Porto

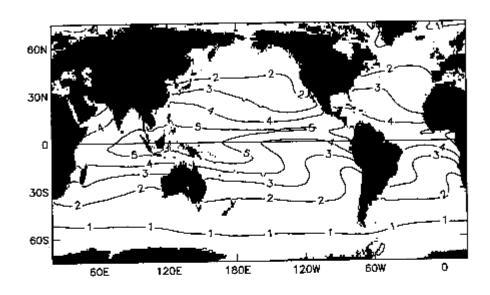


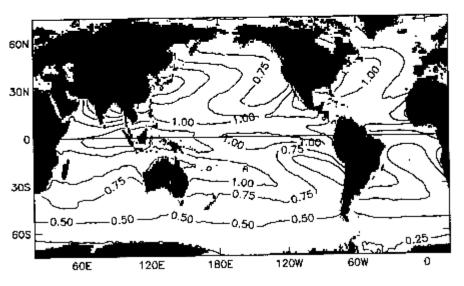




Tropospheric water vapour from SSM/I Mean (g/m²)

Standard deviation







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Atmospheric corrections - summary



- Ionospheric correction: 2-20 cm [+/- 3 cm]
 - Caused by presence of free electrons in the ionosphere
 - Use model or measure using dual frequency altimeter
- Dry tropospheric correction: 2.3 m [+/- 1-2 cm]
 - Caused by oxygen molecules
 - Model the correction accurately using surface atmospheric pressure
- Wet tropospheric correction: 5-35 cm [+/- 3-6 cm]
 - Caused by clouds and rain (variable)
 - Measure H₂O with microwave radiometer
 - Or use weather model predictions
 - Or (more recent approaches): path delays from GPS stations;
 measurements from other satellite-borne passive radiometers

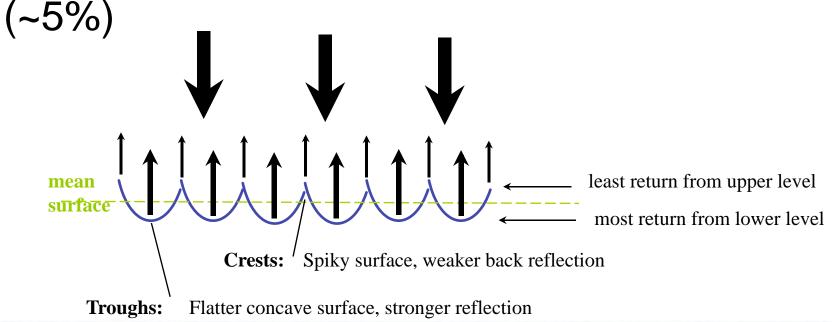


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Sea State Bias Corrections



- Tracker bias
 - Problem with "tracking" the pulse when the sea is rough
- Electromagnetic Bias
 - Radar return from the troughs is stronger than from the crests
- First approx: empirical correction based on H_s





State of the art in sea state bias



- There is as yet no theoretical method for estimating the sea state bias.
- We are therefore forced to use empirical methods
- We find the function of H_s (and U₁₀ that is wind) that minimises the altimeter crossover differences or the differences w.r.t in situ observation (from wave buoys)
- Sea State Bias is intimately linked to the retracking model adopted
- Sea State Bias for SAR altimetry, is particularly in need of better characterization.





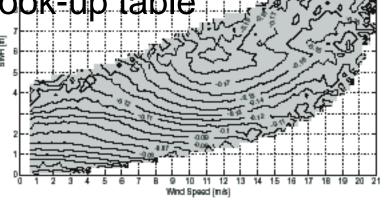
Parametric vs non-parametric



- With parametric methods we have a specified function for the SSB and estimate the parameters of this function, e.g. the BM4 model used for TOPEX
 - → Then we use the fitted function
- With non-parametric methods we compile statistics and smooth the resulting 2-d histogram

→Then we use the histogram as look-up table

An example non-parametric SSB



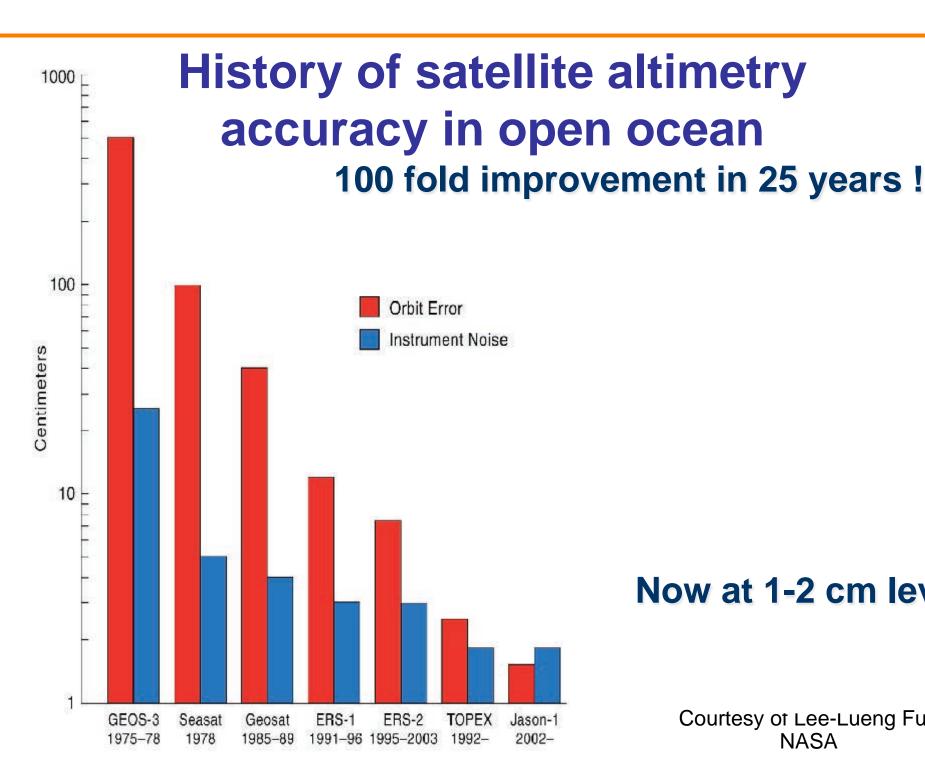


Example of TOPEX Error Budget for 1-Hz Ifremer measurement (from Chelton et al 2001)



Source	Error
Instrument Noise	1.7cm
Ionosphere	0.5cm
EM Bias	2.0cm
Skewness	1.2cm
Dry Troposphere	0.7cm
Wet Troposphere	1.1cm
Orbit	2.5cm
Total	4.1cm





Now at 1-2 cm level!!

Courtesy of Lee-Lueng Fu., NASA

Envisat and Sentinel-3 Error Ifremer Budget



Table 7Estimated Sea Surface Height (SSH) error budget for the Sentinel-3 topography mission.

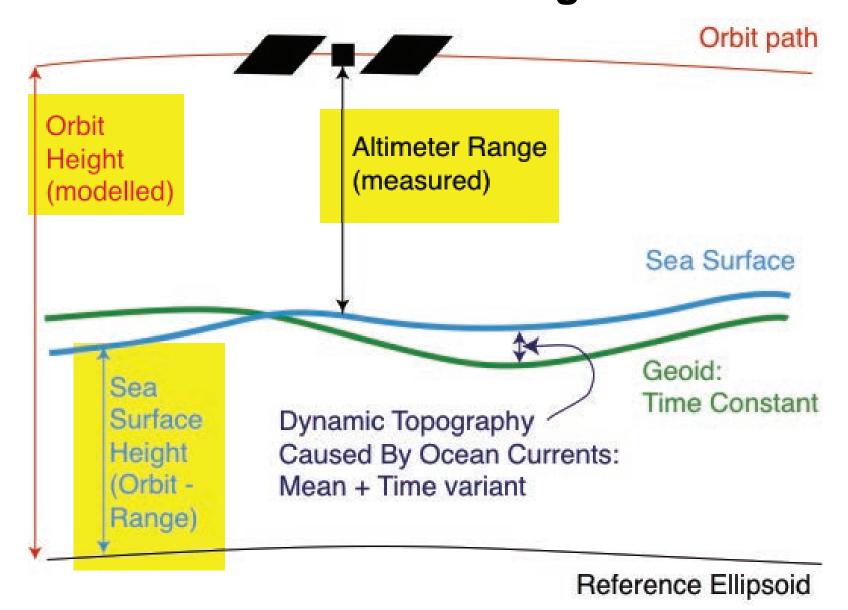
Source	ENVISAT error [cm]	S-3 error [cm]	Contributor
Altimeter noise	1.8	1.4 for LRM	SRAL
Sea state bias	2	2	SRAL
Ionosphere	0.5	0.5	SRAL
Dry troposphere	0.7	0.7	SRAL
Wet troposphere	1.4	1.4	MWR
Total range error	3.1	2.9	
Radial orbit error	1.9	1.9	POD
Sea Surface height error	3.6	3.4	

from Donlon et al., 2012

Altimeter noise expected in SAR mode < 1 cm (@ 1 Hz, 2m SWH)



All the processing seen so far is to get a good SSH=orbit-range



Next: what is there in the SSH?

Interpreting Ocean Surface Ifremer Topography

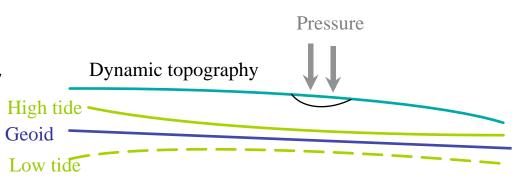


Geoid (~100 m)

- Time invariant
- Not known to sufficient accuracy
- To be measured independently (gravity survey)

Tides (~1-2 m)

- Apply a tidal prediction
- New tidal models derived from altimetry
- Choose orbit to avoid tidal aliasing



reference level

Atmospheric pressure (~0.5 m)

 Apply inverse barometer correction (1mbar ~ 1 cm)

Dynamic topography (~1 m)

The intended measurement

Some of these we want to correct for – or not, depending on the application!!!



Atmospheric pressure Ifremer (the "Inverse Barometer" Correction esa

- When air pressure changes the ocean acts like a barometer (in reverse). High air pressure depresses the sea surface, low air pressure raises it.
- 1 mbar (hPa) change in air pressure is approximately equal to a 1cm change in the sea surface
- Good in mid and high latitudes not in Tropics
- Also, not very accurate in enclosed basins (like the Mediterranean)
- and there are other-high frequency fluctuations of the ocean
- Latest high-resolution barotropic models (like MOG2D/T-UGO) allow a very accurate correction of the atmospheric forcing





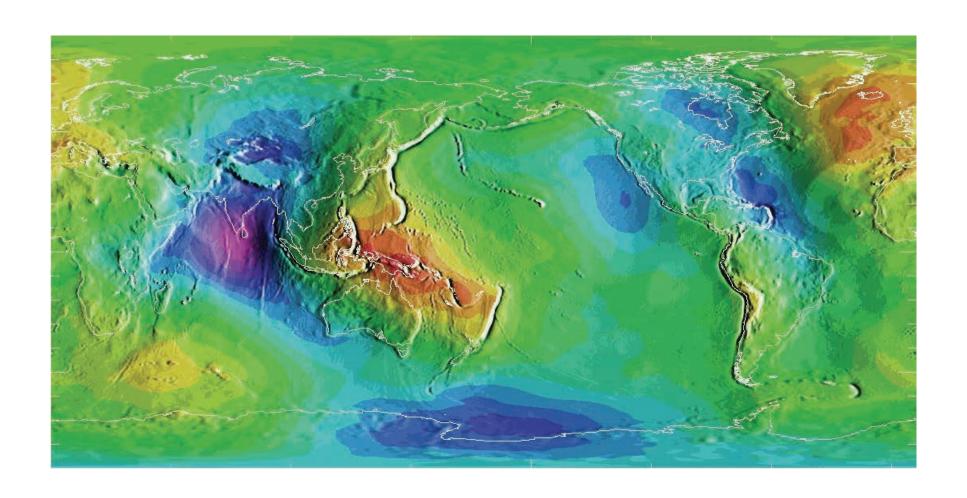
The problem of the Geoid



- The geoid is the surface of equal gravity potential on the Earth's surface (the shape of the Earth)
- The ellipsoid is an approximation to the shape of the Earth
- We know the ellipsoid we do not know the geoid with the accuracy we would like!!!



The Geoid



Scale: magenta (-107 m) to red (84.5 m)

Ifremer The Geoid

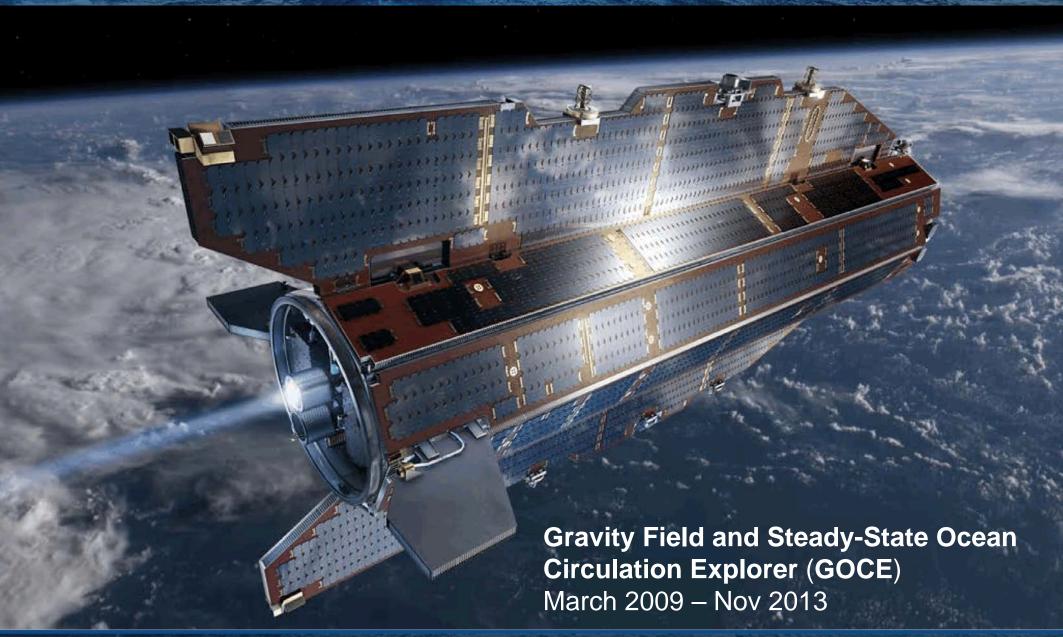


- The geoid is usually expressed in terms of spherical harmonics (sine curves on the sphere). These have degree and order
 - Degree and order 360 is a resolution of approx. 1°
- Sea surface pressure and hence geostrophic currents are in terms of sea surface height relative to the geoid
- We measure sea surface height (and hence slopes) relative to the ellipsoid.



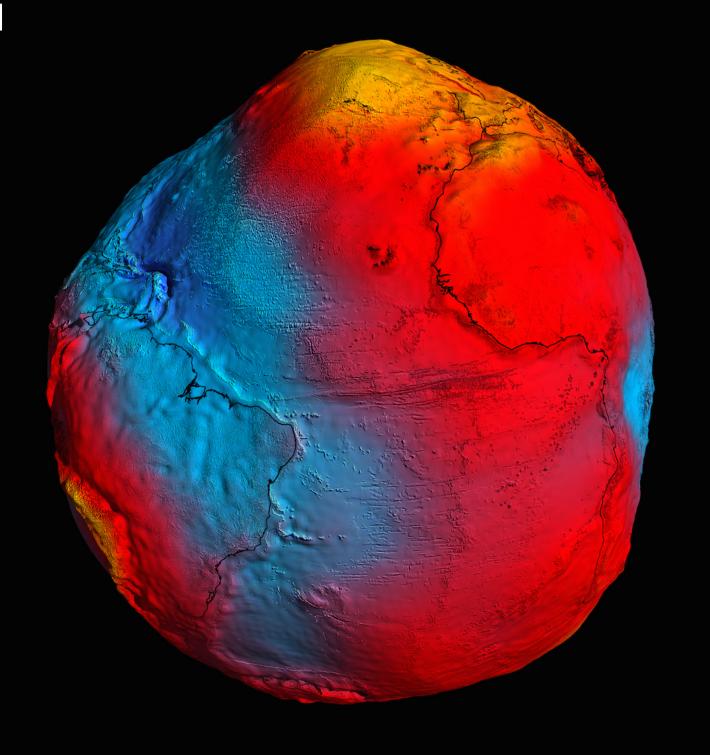
Ifremer GOCE







GOCE geoid





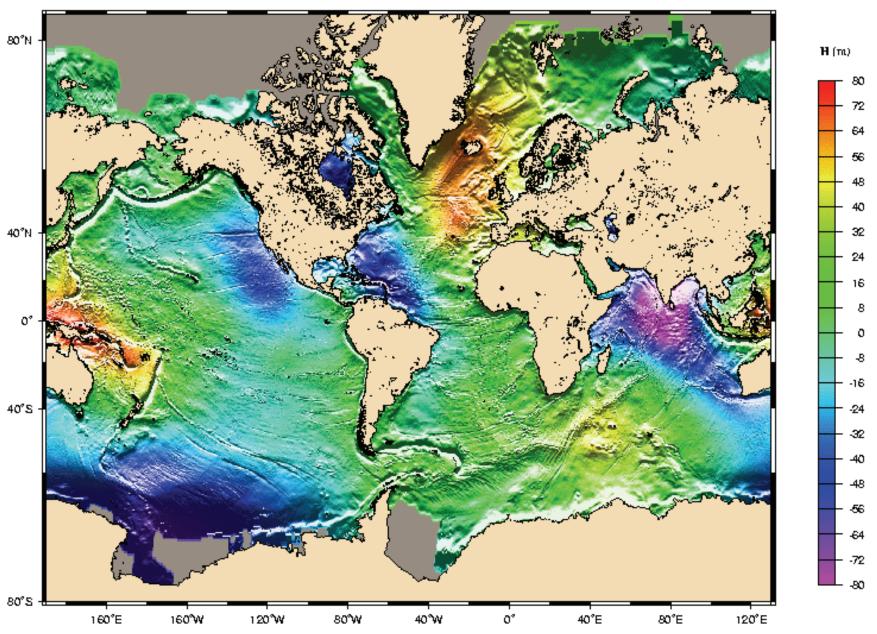
Ifremer Removing the Geoid



- The geoid is time invariant (approximately)
- So if we subtract a mean sea surface we will remove the geoid
- But we lose ...
- ... the mean circulation



Mean sea surface



Ifremer SSH residuals



- The sea surface height residual (or Sea Surface Height Anomaly - SSHA) is what remains after removing the mean in each location (Mean Sea Surface)
- Any constant dynamic topography (from steady currents) will have been removed!
- Contains only the time-varying dynamic topography
- May still contain time varying errors
 - Un-removed tidal or barometric signal
 - Orbit error
- With the recent independent accurate geoid models (from GRACE and ESA GOCE mission) we are getting closer to be able to subtract the geoid and work with absolute dynamic topography (much better for oceanographers!)



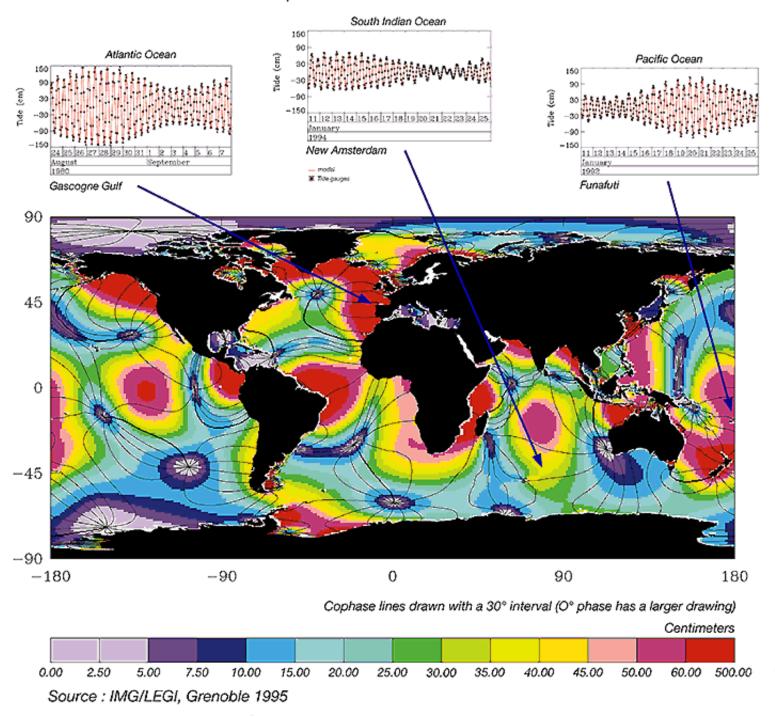
Ifremer Tides



- If we are going to use altimetry for oceanographic purposes we need to remove the effect of the tides
- Alternatively we could use the altimeter to estimate the tides - tidal models have improved dramatically since the advent of altimetry!
- In general we use global tidal models to make predictions and subtract them from the signal



The up and down of the ocean tides



Ifremer More tides!



- As well as the ocean tide we have to consider
 - the loading tide (the effect of the weight of water). This
 is sometimes included in the ocean tide
 - the solid earth tide
 - the polar tide
- On continental shelves the global models are not very accurate and local models are needed
- Any residual tidal error is going to be aliased by the sampling pattern of the altimeter



Ifremer Aliasing Periods



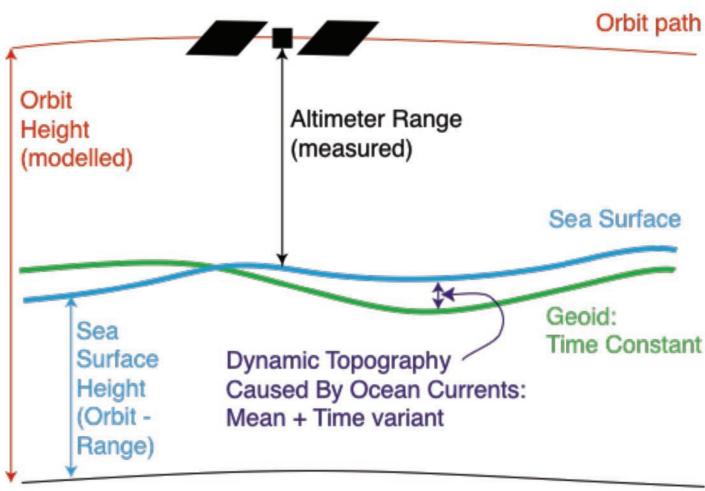
		T/P		ERS	
Tide	Period	Alias	wave	Alias	wave
	(h)	(days)	length	(days)	length
			$(^{\circ})$		$(^{\circ})$
M2	12.42	62	9E	95	9E
S 2	12	59	180W	0	∞
N2	12.65	50	9W	97	4W
K 1	23.93	173	360W	365	360E
O 1	25.82	46	9.23E	75	9E
P1	24.07	89	360W	365	360W





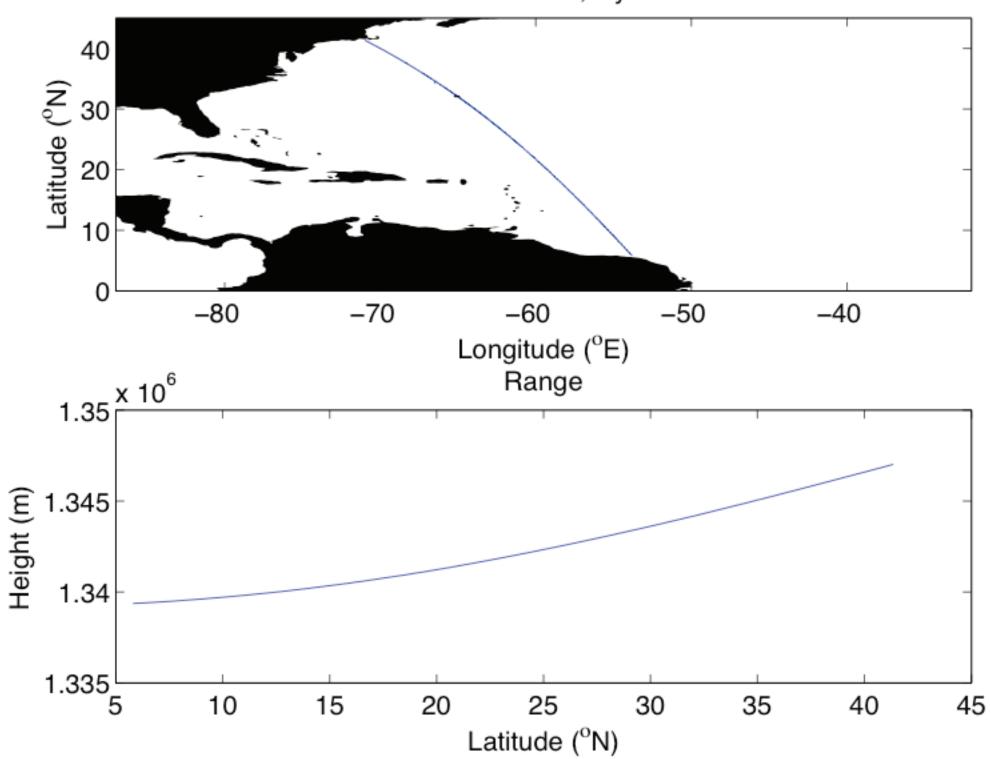
Example over a pass



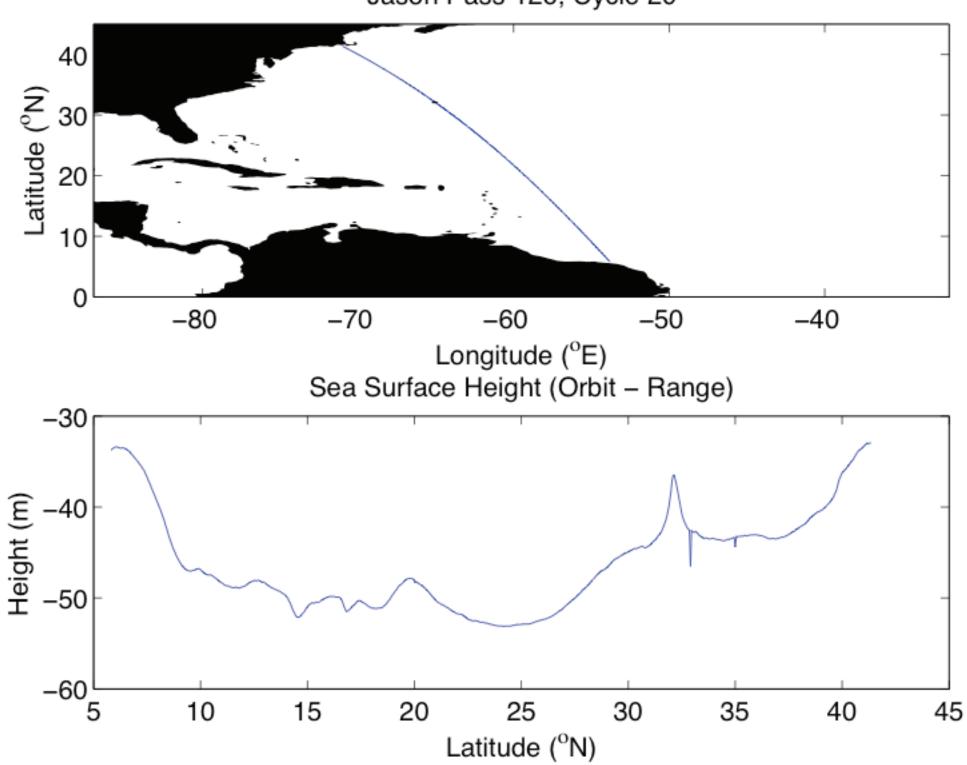




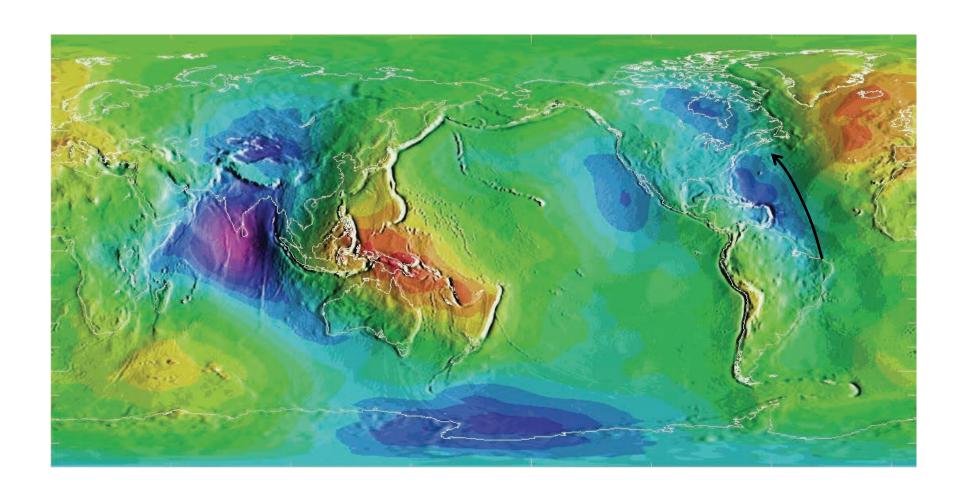
Jason Pass 126, Cycle 20



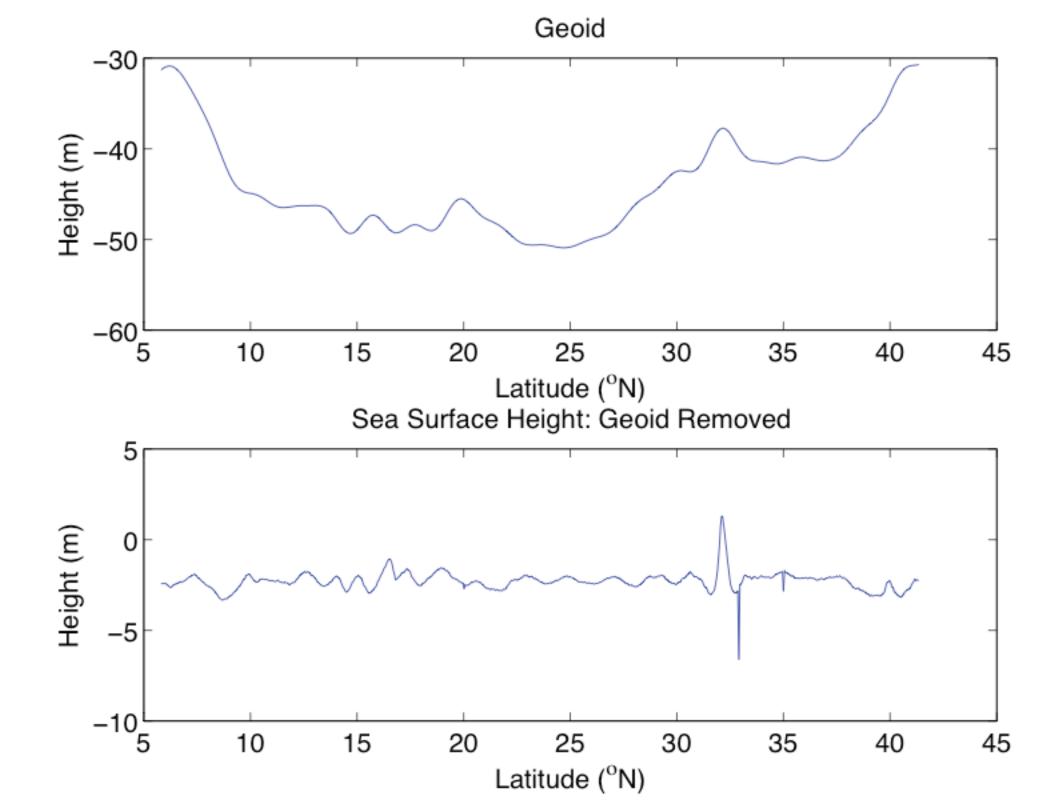
Jason Pass 126, Cycle 20



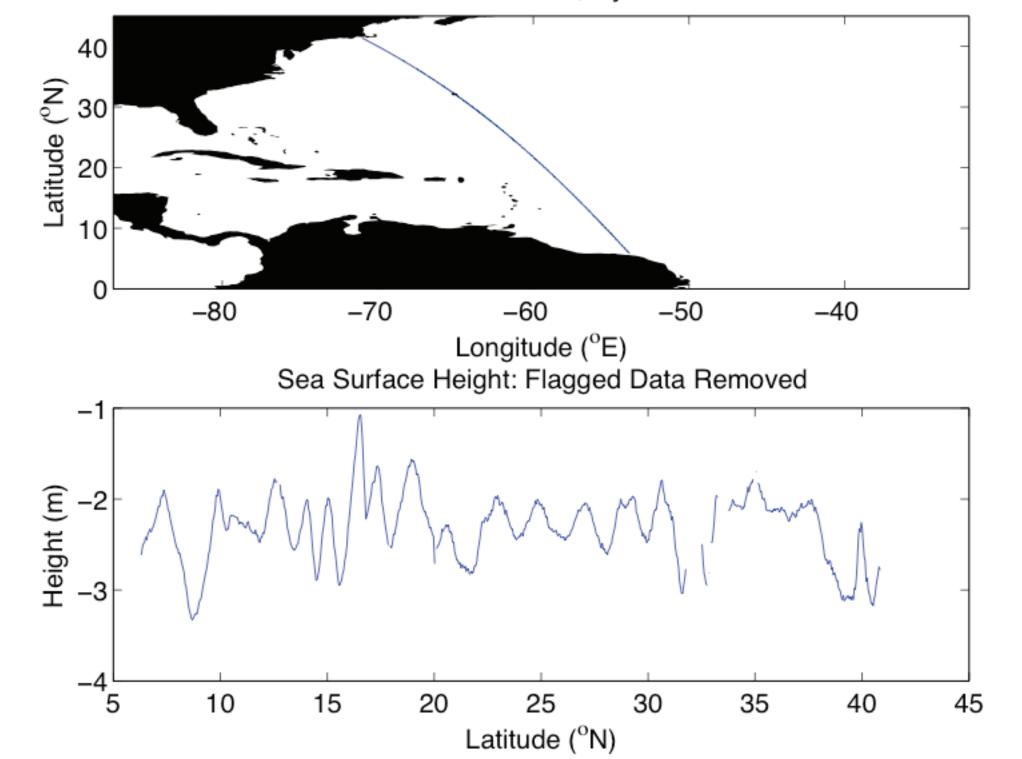
The Geoid

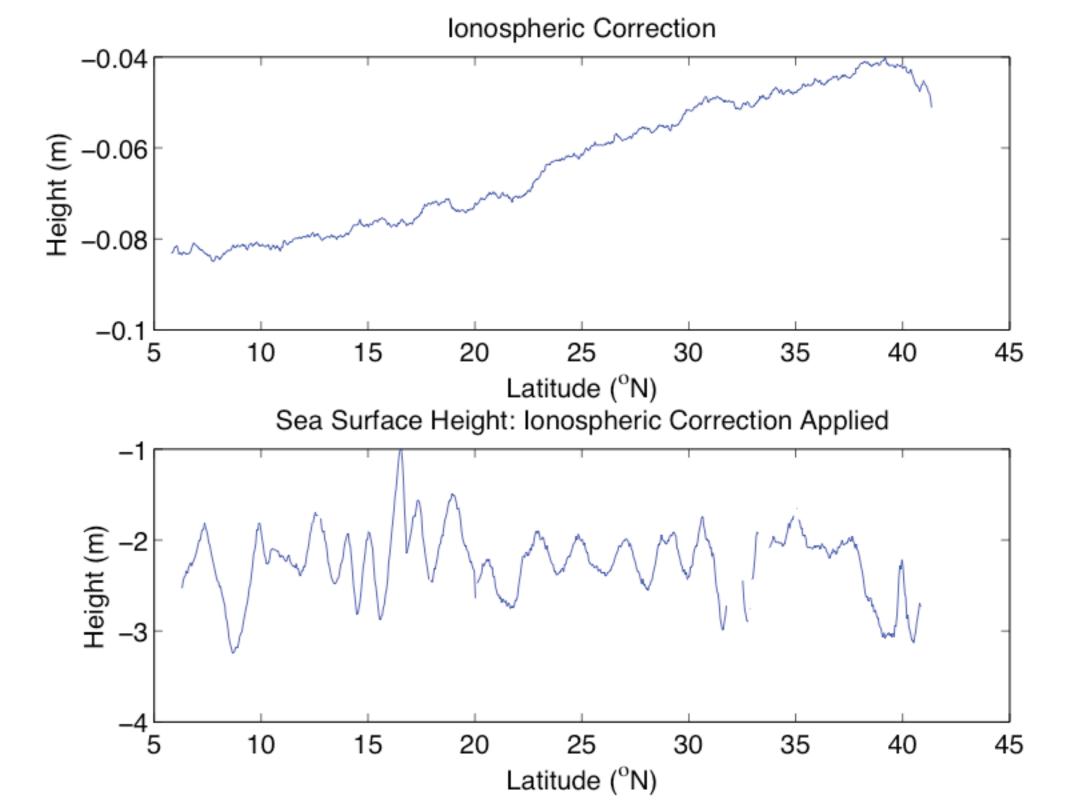


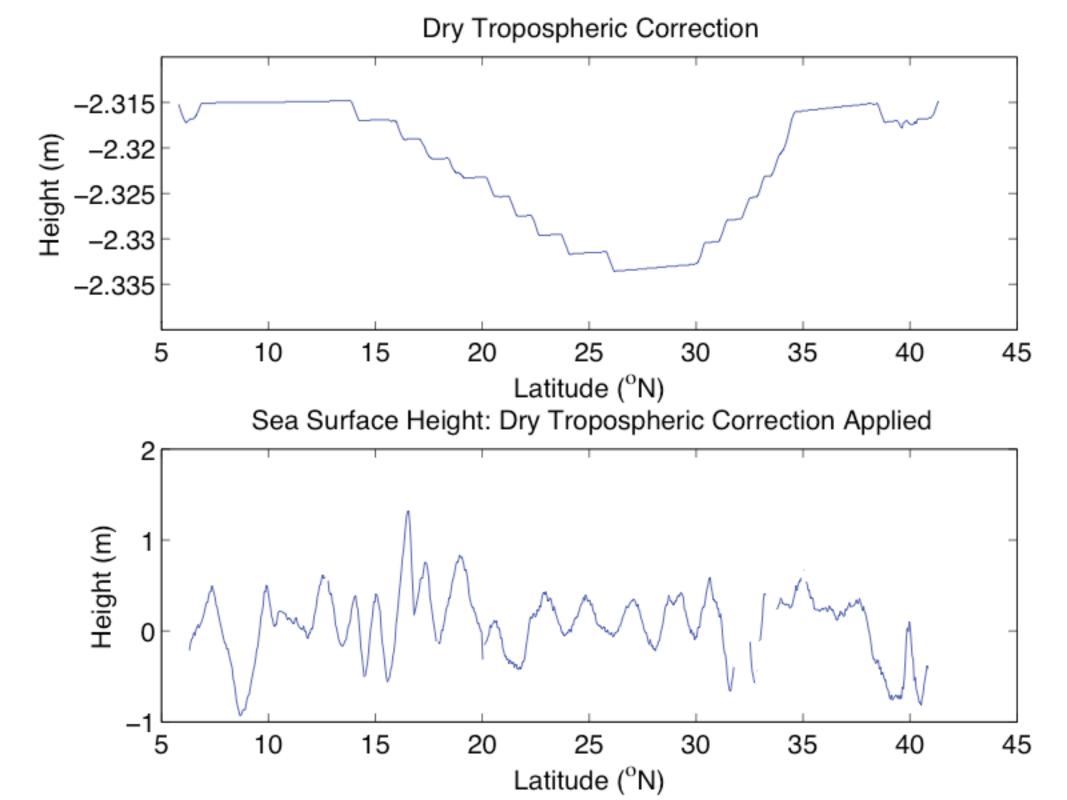
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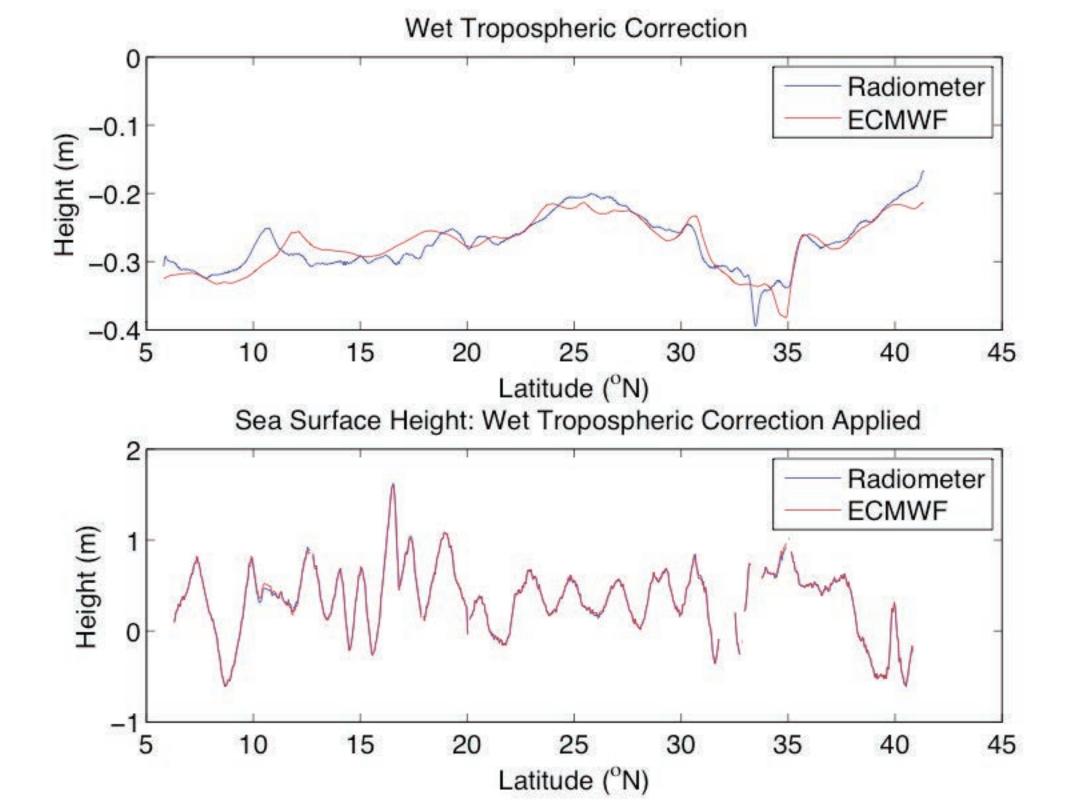


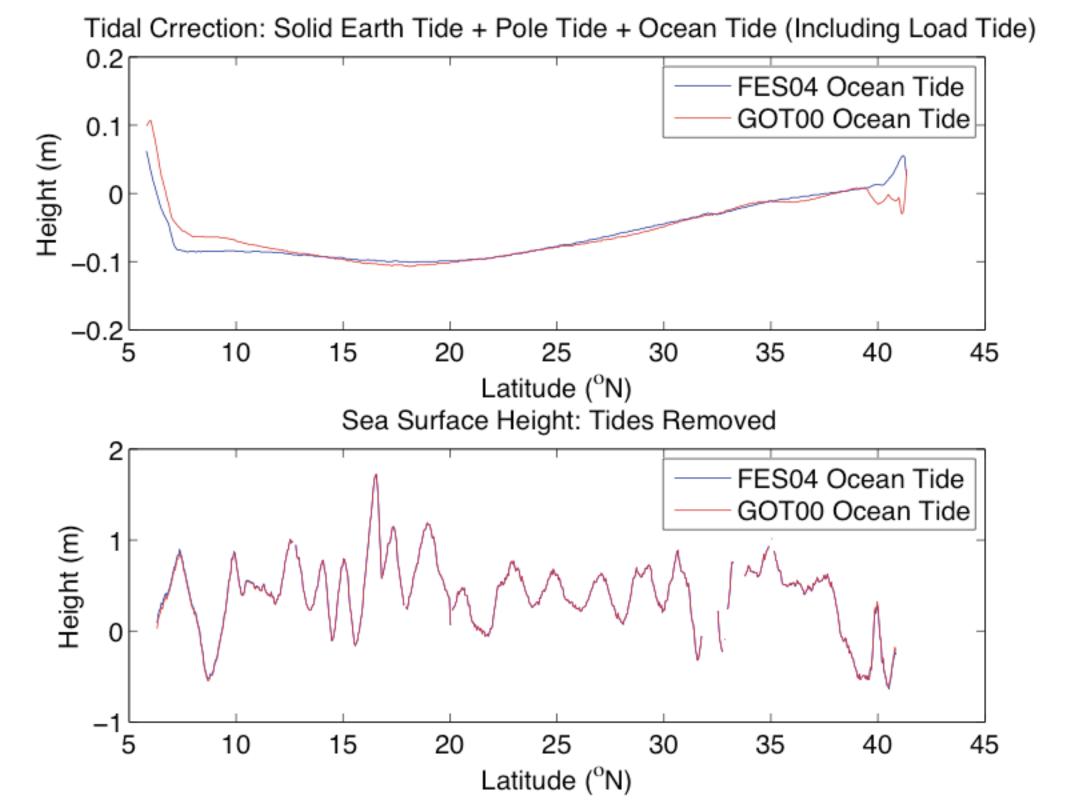
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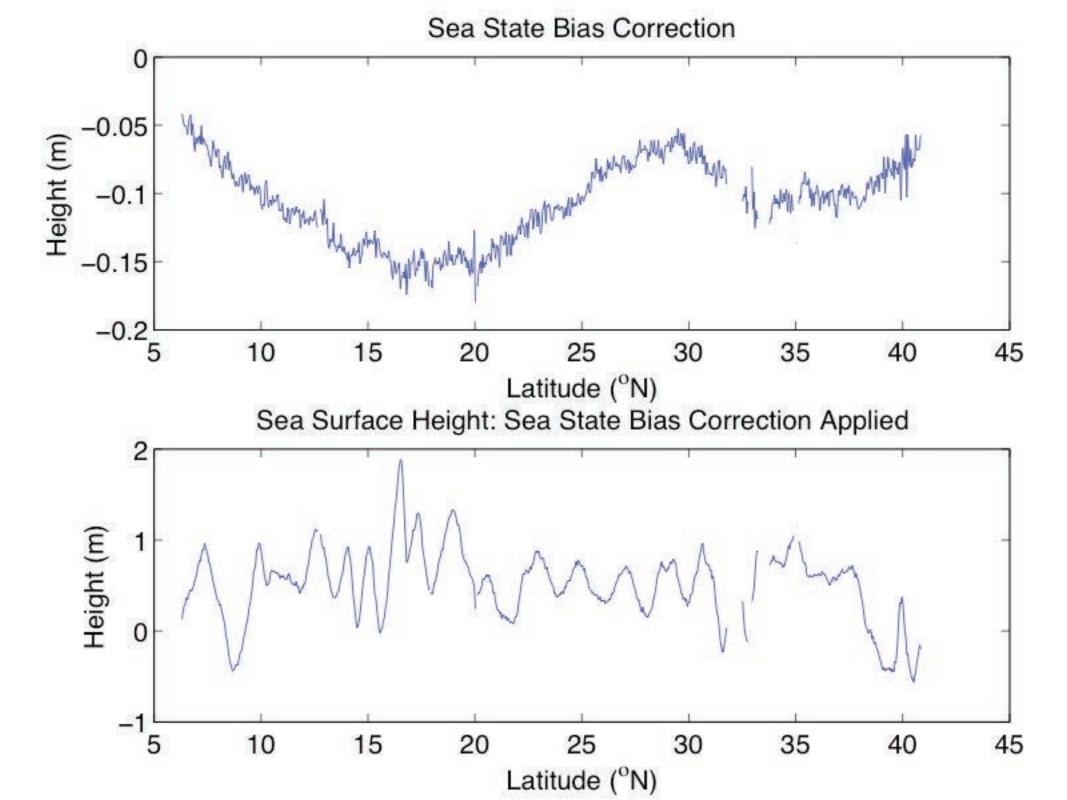


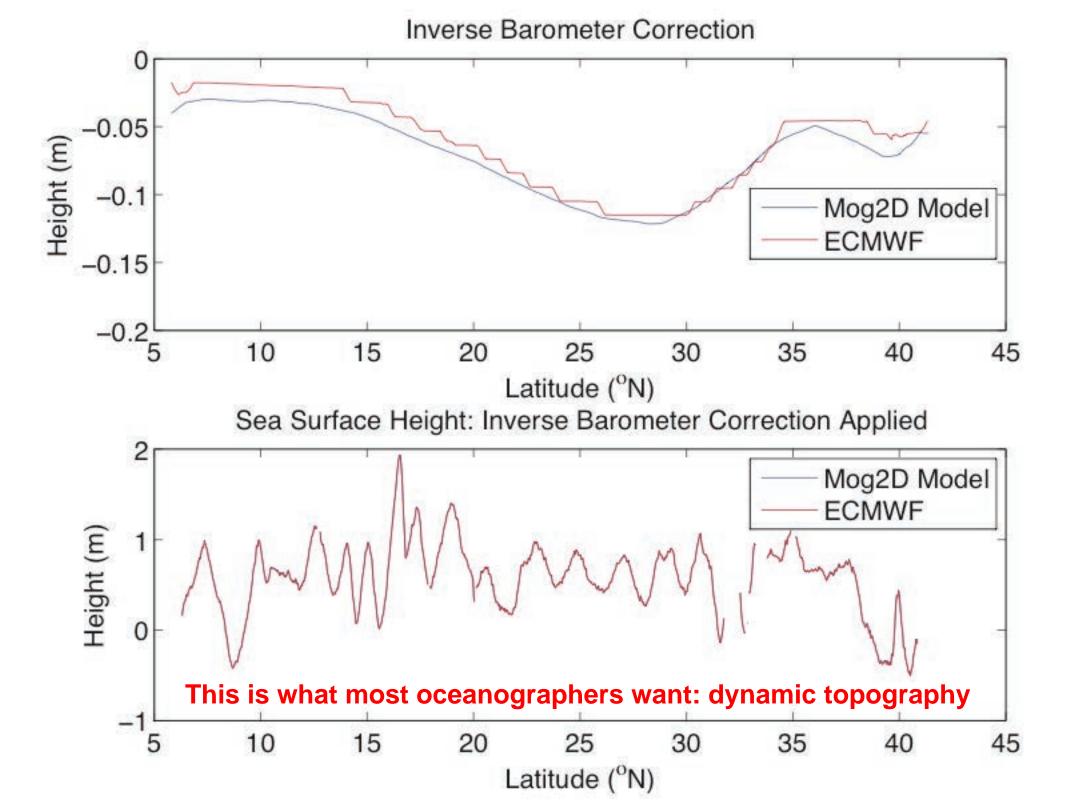






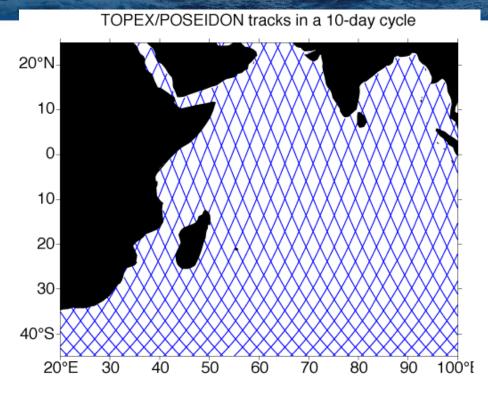






Ifremer .and finally from tracks to map





Example of interpolated data and data in space and time

