

Volcano Monitoring using Deep Learning

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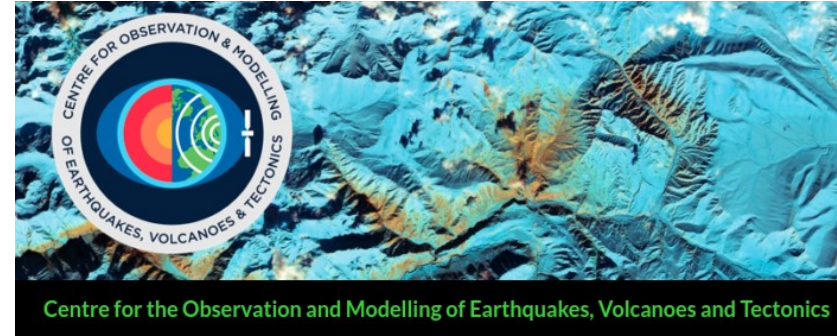


LIVING PLANET FELLOWSHIP
LITHOSPHERE

Acknowledgements



- I've previously worked on similar problems as a PhD student funded by the "Looking Inside the Continents from Space" (LiCS) grant, and as a COMET postdoc:

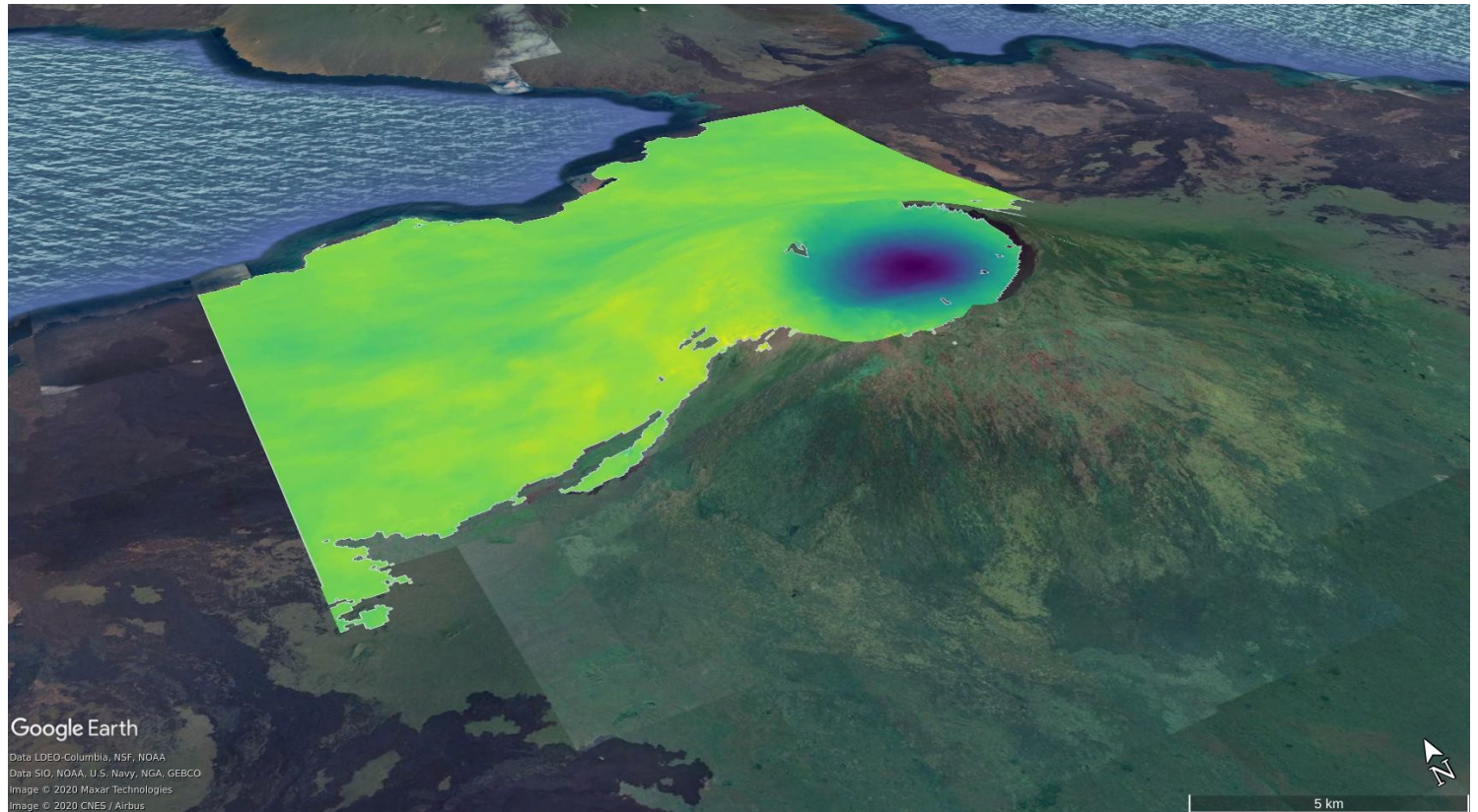


- I've collaborated on this work with Andy Hooper (University of Leeds) and Fabien Albino (University of Bristol):



Project rationale

- Interferograms contain information about ground deformation, and this has strong evidential worth for assessing eruption potential (Biggs et al., 2014).
- Routine acquisition over subaerial volcanoes by the Sentinel-1 satellites could facilitate monitoring of many new volcanoes.
- An example of a deformation signal captured by the Sentinel-1 satellites: uplift of the caldera floor of Sierra Negra (Galapagos Archipelago, Ecuador), prior to the 2018 eruption.





- However, with ~1500 active subaerial volcanoes and new interferograms being created every 6 or 12 days, searching for these signals manually is an onerous task.
- E.g. Consider Isabella Island in the Galapagos Archipelago:

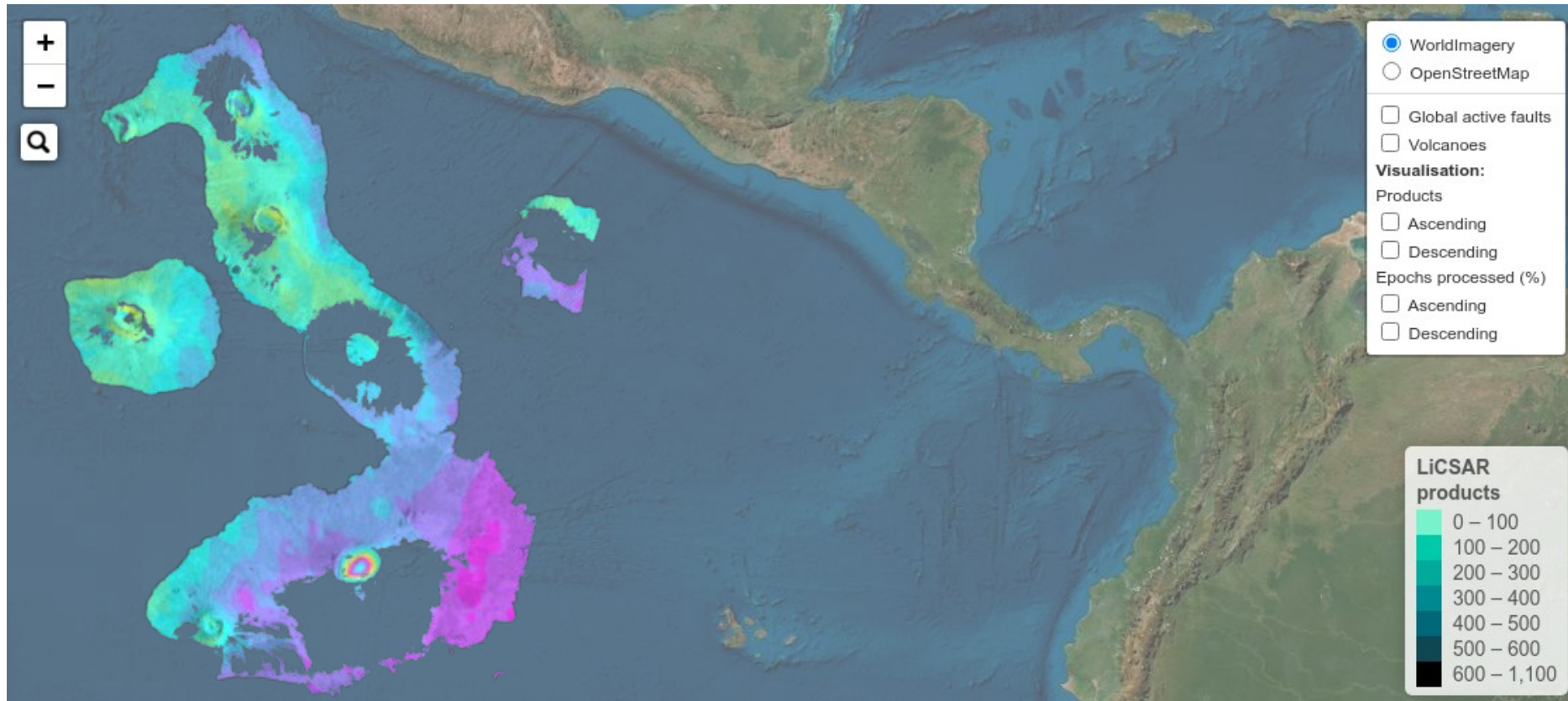


Figure: COMET LiCS portal

- However, with ~1500 active subaerial volcanoes and new interferograms being created every 6 or 12 days, searching for these signals manually is an onerous task.
- E.g. Consider Isabella Island in the Galapagos, within the Eastern Pacific:

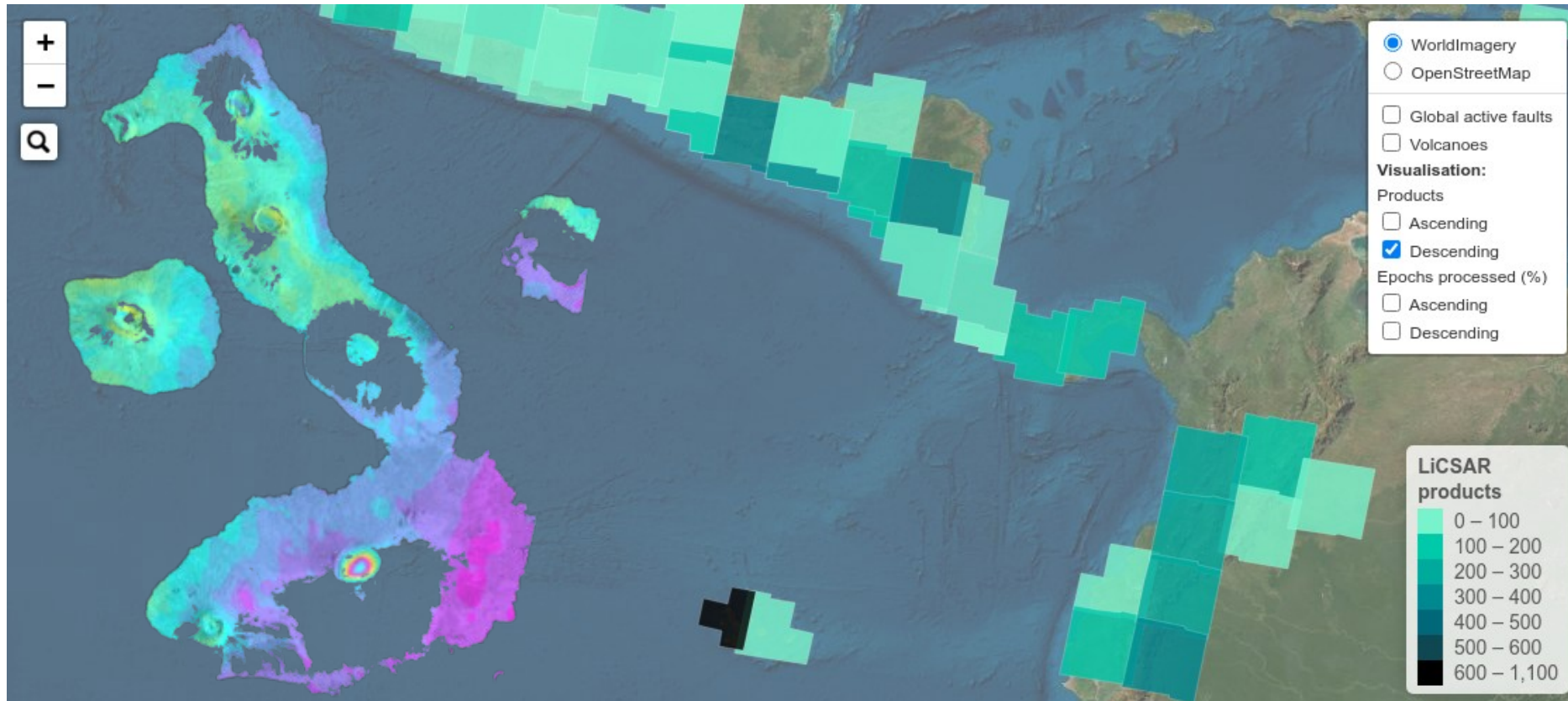


Figure: COMET LiCS portal



- However, with ~1500 active subaerial volcanoes and new interferograms being created every 6 or 12 days, searching for these signals manually is an onerous task.
- E.g. Consider Isabella Island in the Galapagos, within the Eastern Pacific, and within the globe:

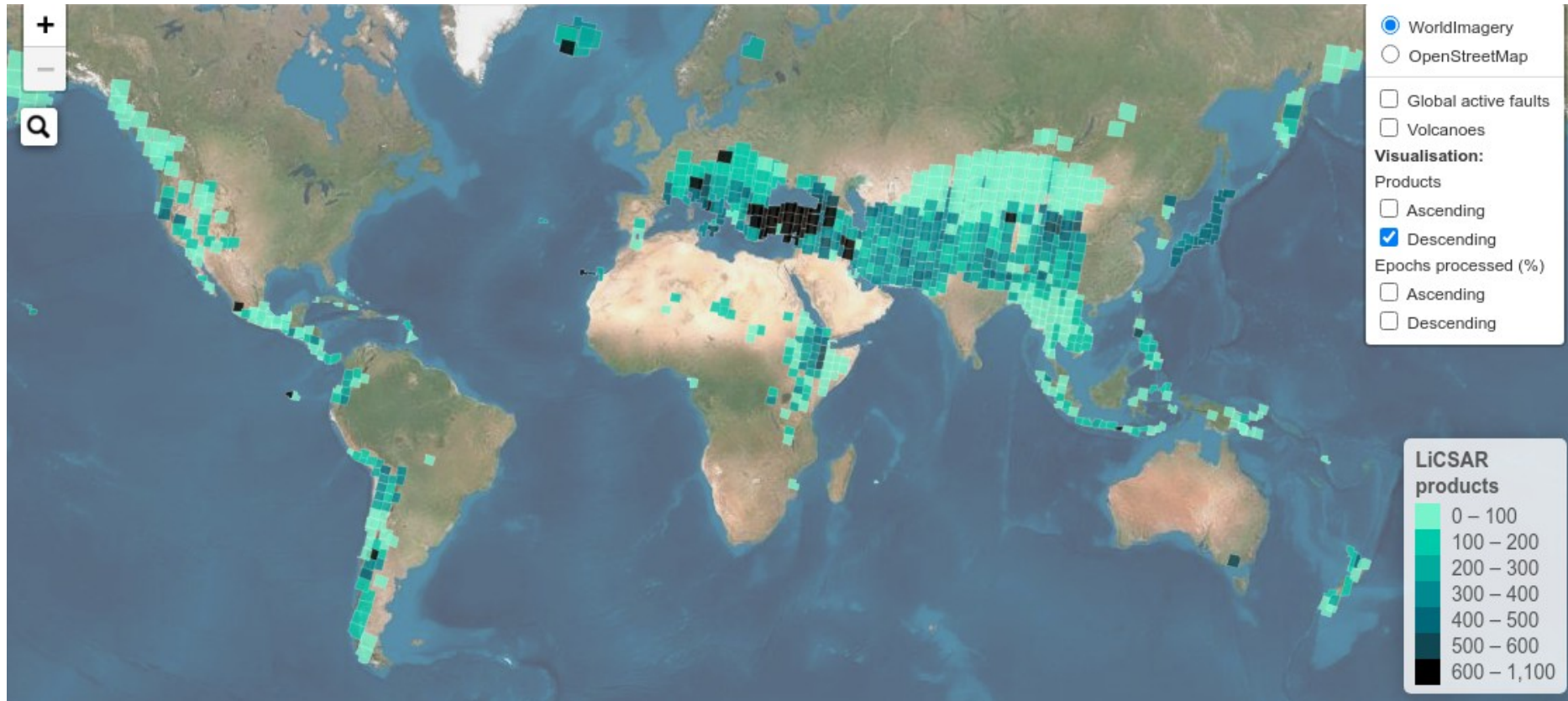


Figure: COMET LiCS portal

InSAR for volcano monitoring: examples (1/2)

- Deformation / no deformation flag on wrapped interferograms (localisation is just nested classification + Gaussian smoothing).

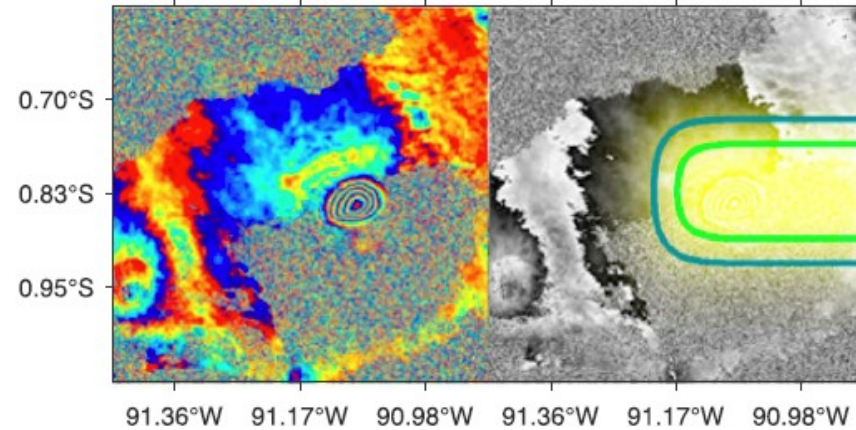


Figure: Anantrasirichai et. al., 2018

- Considering pixels in time series with atmospheric corrections applied:

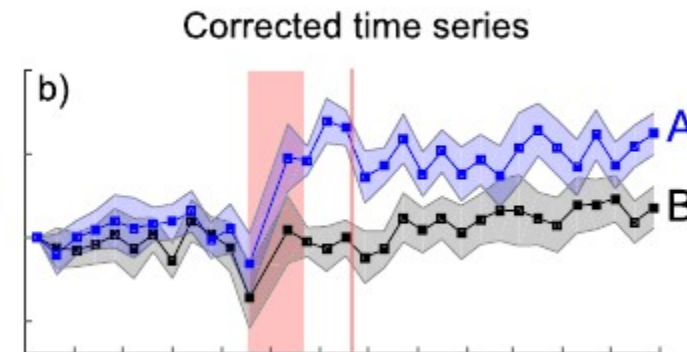
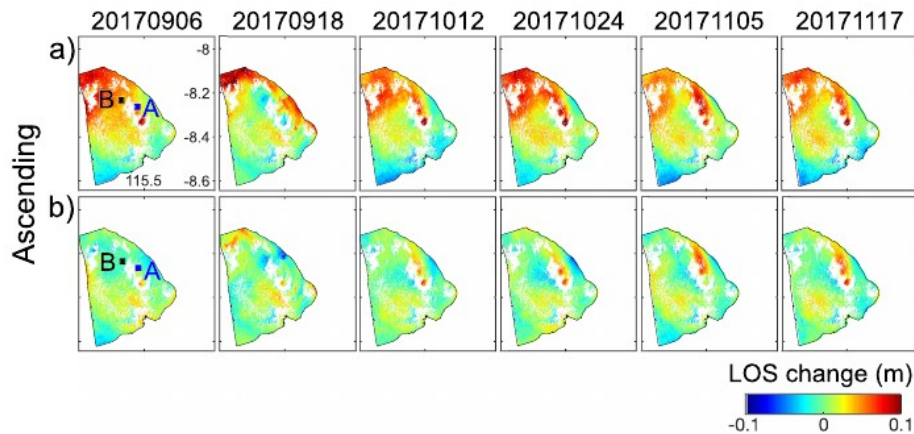
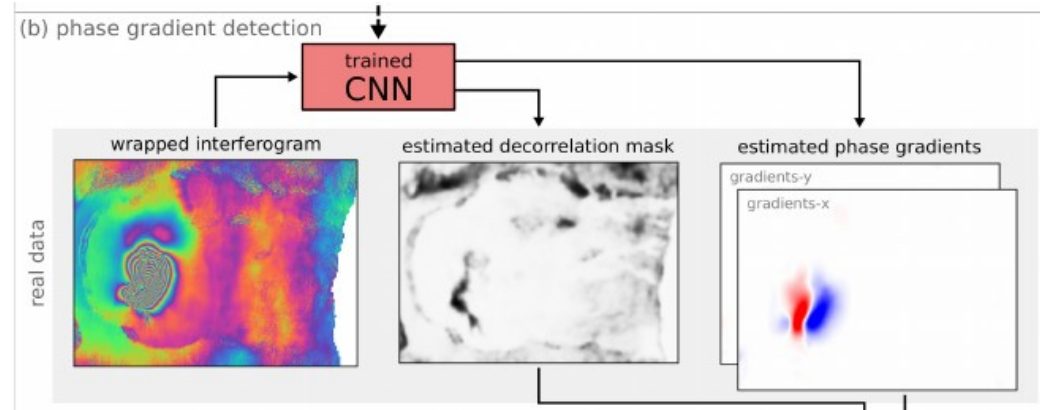


Figure: Albino et. al., 2020

InSAR for volcano monitoring: examples (2/2)

- “Monitoring Unrest from Space” (MOUNTS), Sentinel-1 (InSAR), Sentinel-2 (InfaRed), Sentinel-5 (SO₂), and seismic data.



- LiCSAlert, Time series method that detects deviations from baseline behaviour.

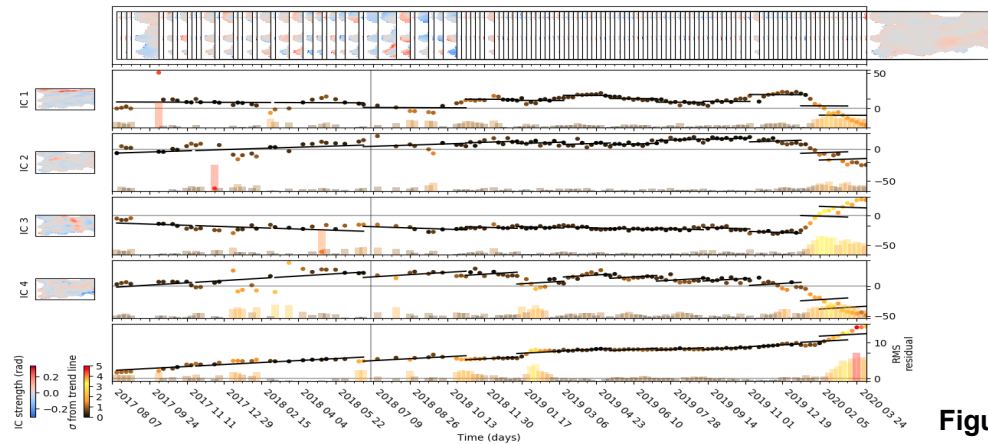


Figure: Gaddes et al., in prep.

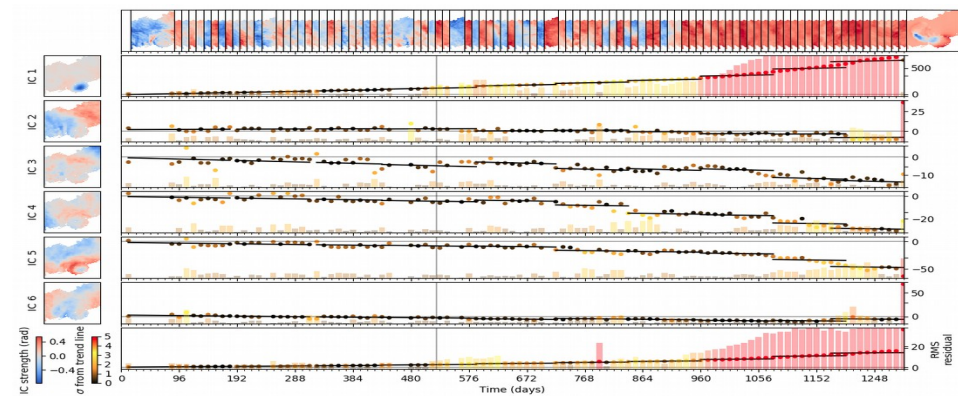


Figure: Gaddes et al., 2019

Objective 1: deep learning with single interferograms

- Advancing the state of the art up the hierarchy of computer vision:
- Convolutional neural networks (CNNs) have revolutionised the field and are ideal for this task.

E.g. Anantrasirichai et. al., 2018, 2019

This work

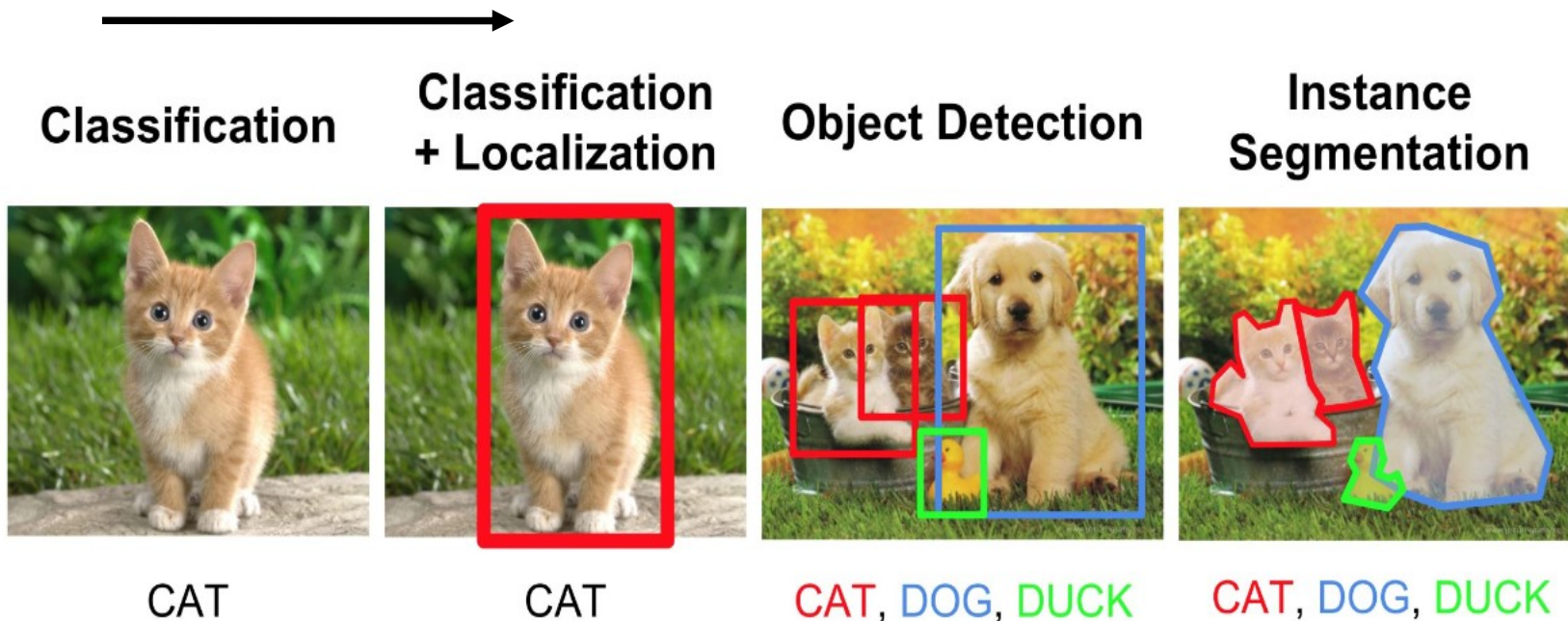
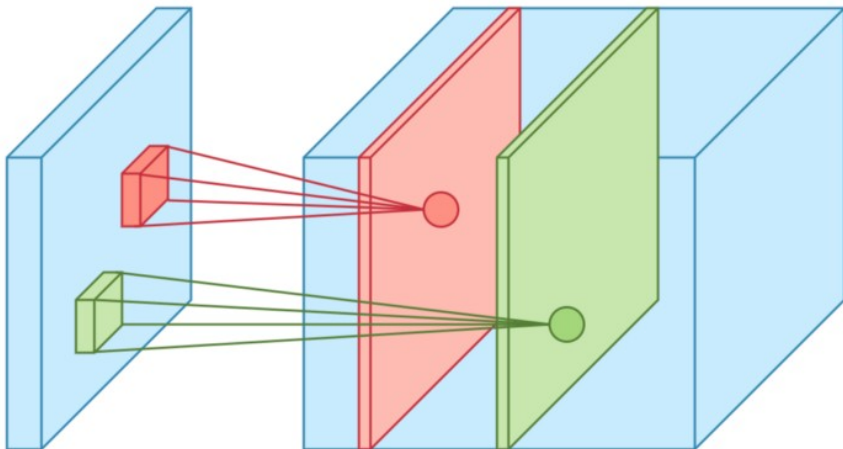
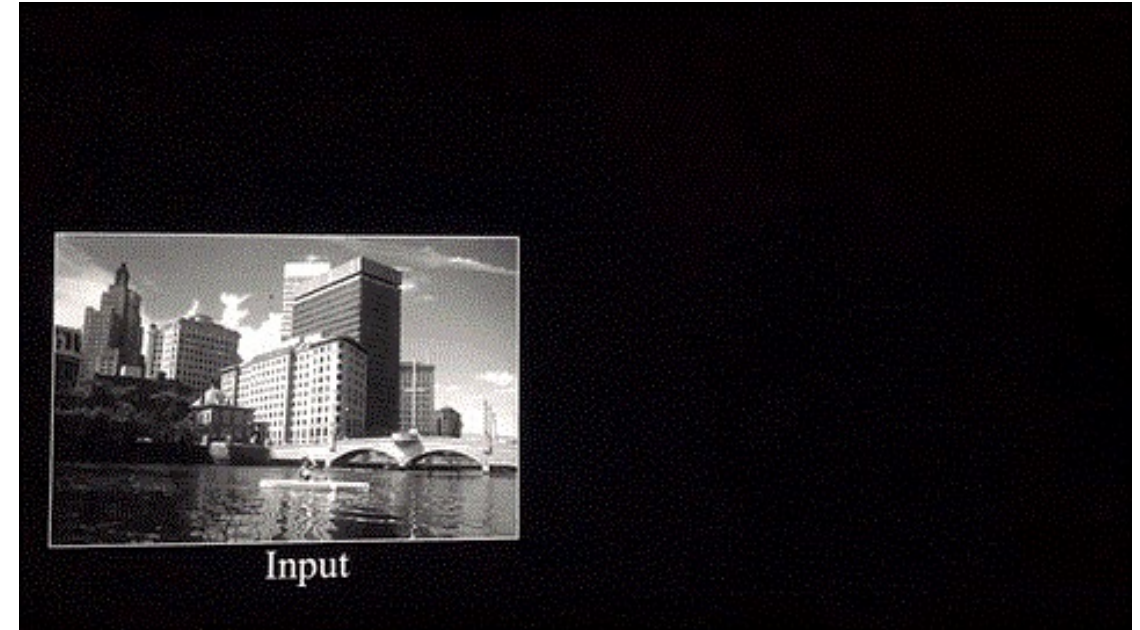


Figure: Stanford CS231 notes

Convolutional neural networks (very briefly)

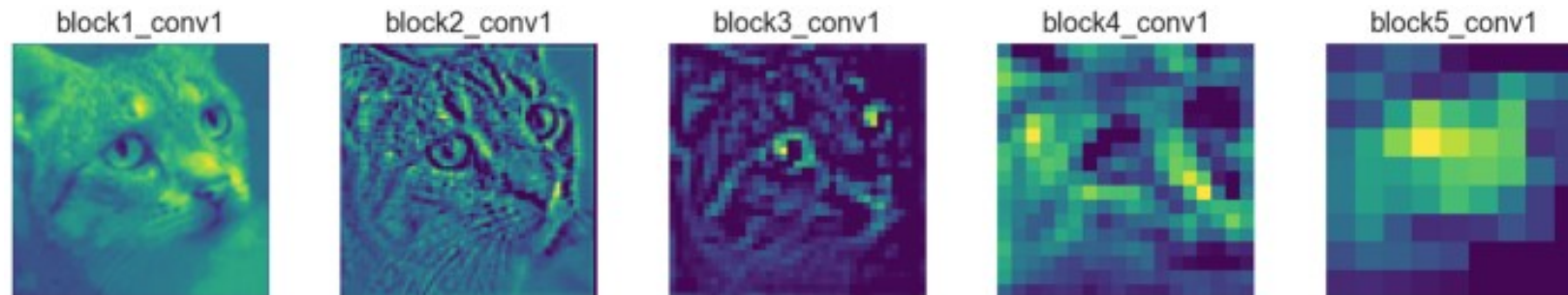
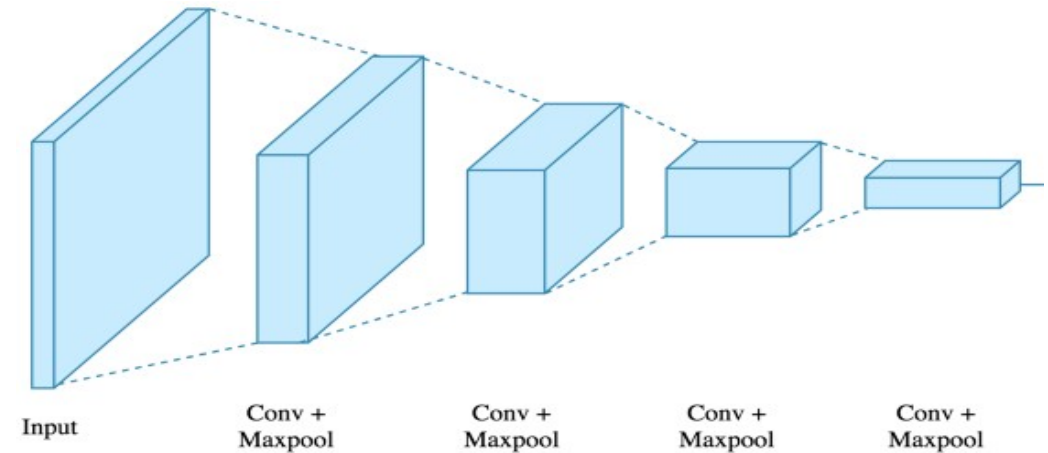
- Working with images so can slide (convolve) filters over an image.
- We don't design the filters, the network learns them.
- An example of two filters (right):
- And how to record their output as layers of a tensor (below):



Animation: Deep learning methods for vision, CVPR 2012 Tutorial. **Diagram:** towardsdatascience.com

Convolutional neural networks (very briefly)

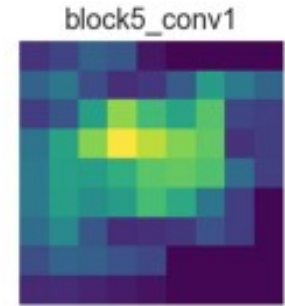
- We can then apply filters to the results of the previous filters (and spatially downsample to allow our representations to get deeper without becoming too large):
- The first filters are usually edge detectors.
- The second filters only see edges, and perhaps detect shapes.
- The third filters only see shapes, and perhaps detect objects.
- Some randomly chosen filter results from a trained model (below):



Diagrams: towardsdatascience.com

Convolutional neural networks (very briefly)

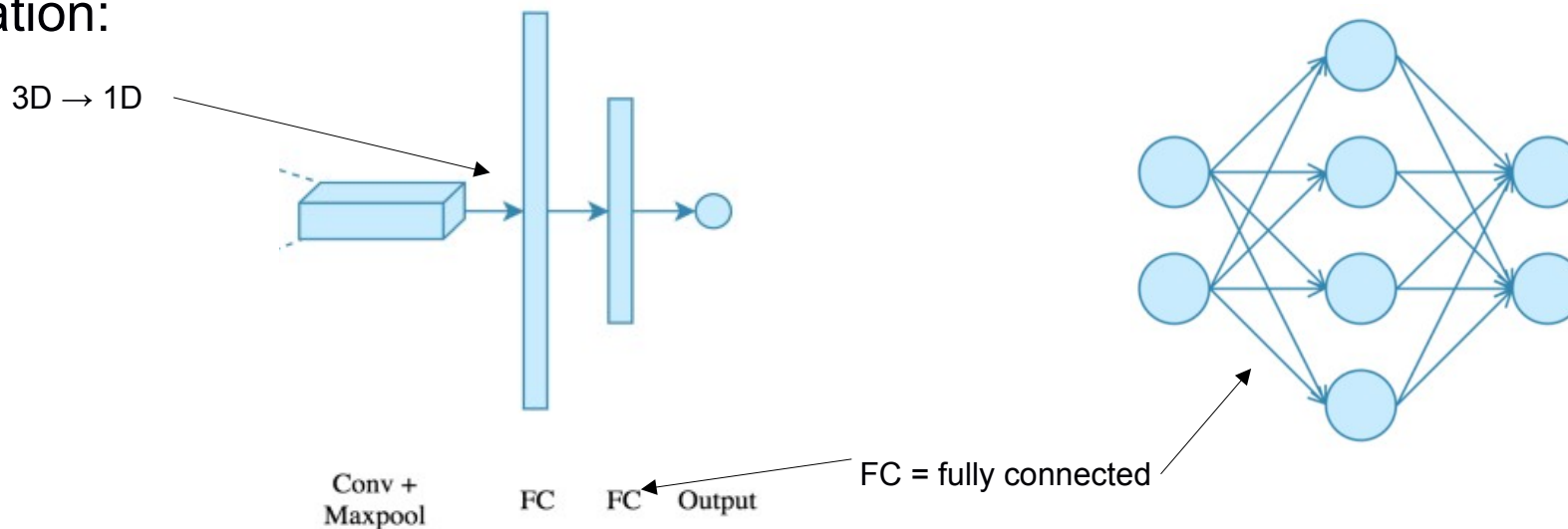
- What to do with the spatially downsampled (but deep) representations?
- Pixels probably represent things like “has a nose”, “has whiskers” etc. Visualising one of these layers in our model’s deep representation (right):



(one slice of the 3D representation)

- How to use this?

A common approach is to just connect a simple neural network to each pixel of the final deep representation:



Using CNNs with interferograms

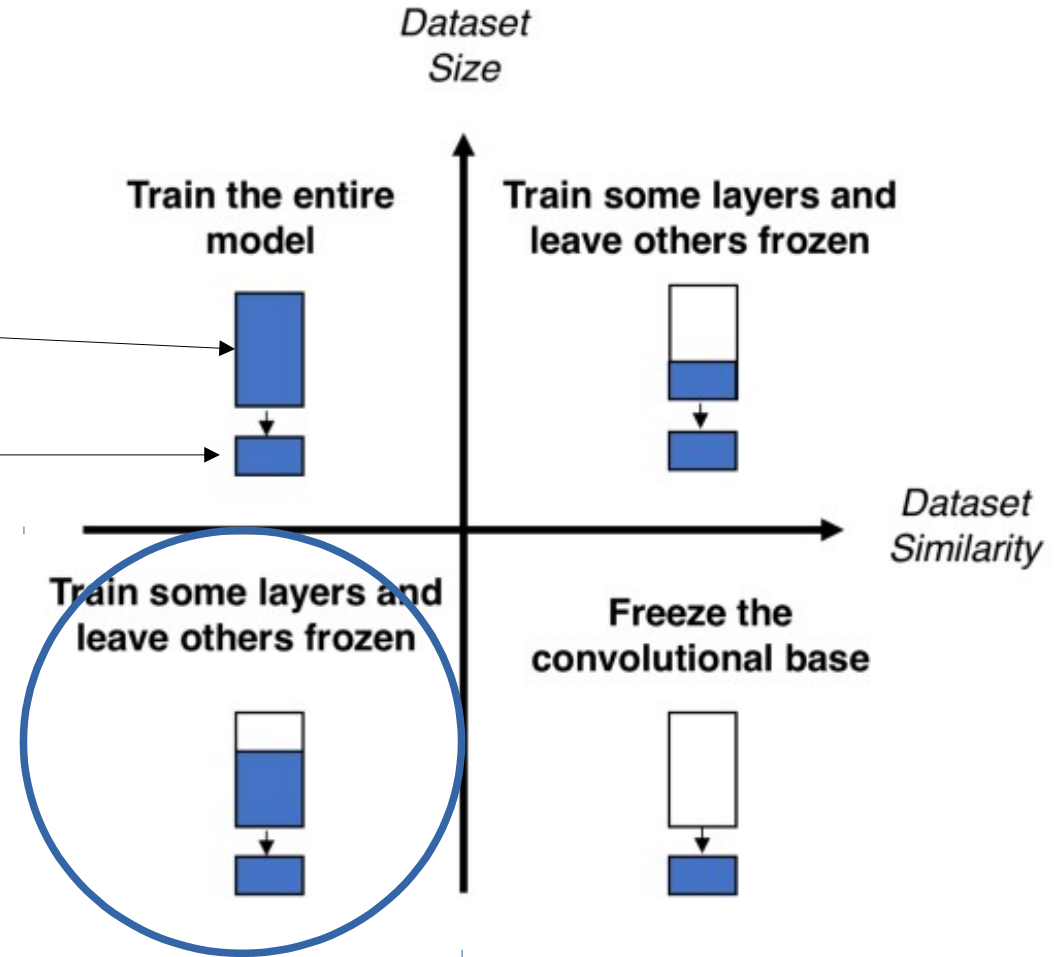


- Design a new model?
- Train an existing one?

convolving filters to make a deep representation

deep representation used by fully connected part

- “Lots of data” = $10^6 - 10^8$, in deep learning, so InSAR is low in that dimension.
- Similarity is harder to gauge. It could be worse!



VGG16 for classification and localisation



- VGG16 was a state of the art model several years ago and weights (filters) are freely available.
- We modify it to have two fully connected heads:
 - **Classification**, to determine the type/class of deformation (e.g. sill, dyke).
 - **Localisation**, to determine the position of size of the deformation signal.

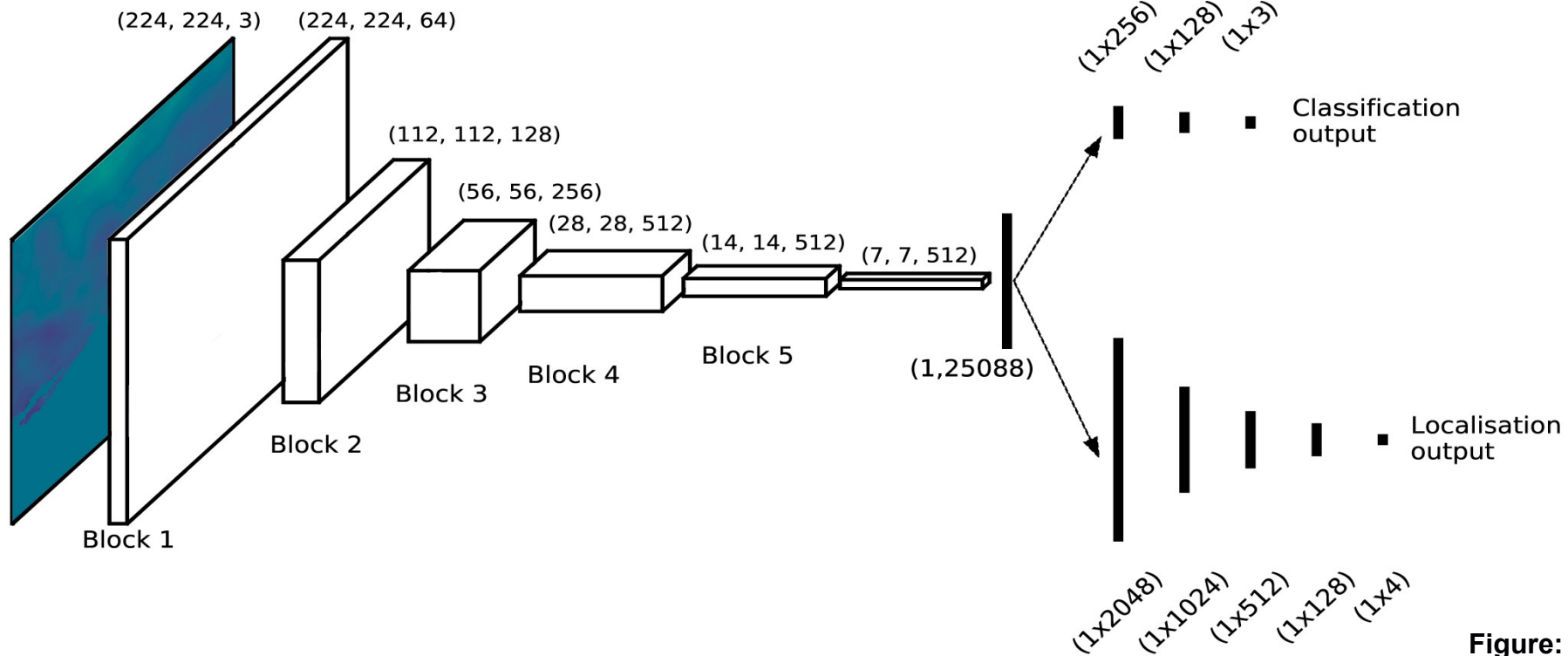
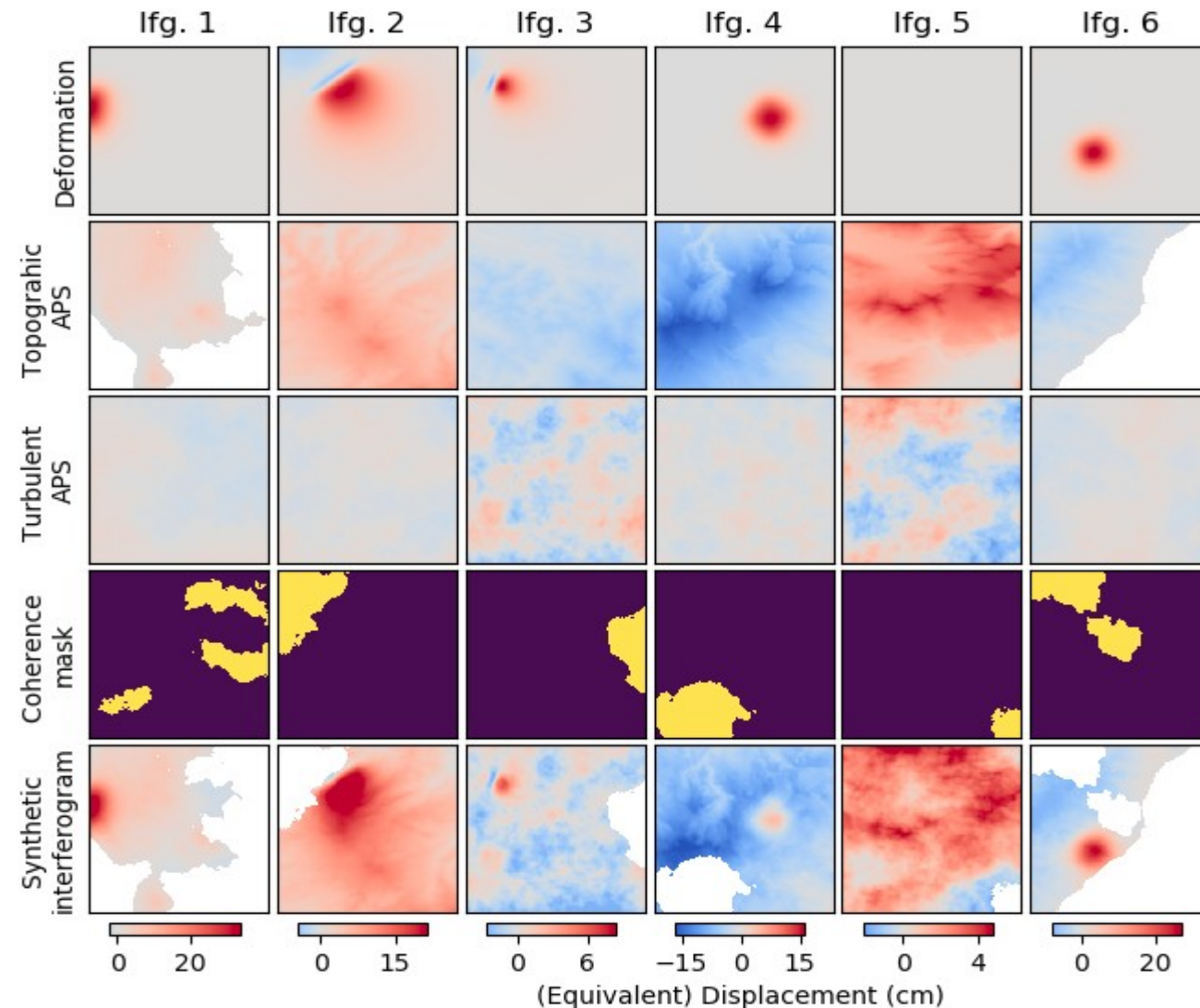


Figure: Gaddes et al., (in prep.)

Training the modified model

- 10^2 real data is challenging, so we try to use synthetic data to train the new fully connected classification and localisation heads.
- **Deformation** from dykes, sills, and point (Mogi) sources.
- **Topographically correlated APS** (atmospheric phase screen) for all subaerial volcanoes.
- **Turbulent APS.** (spatially correlated noise).

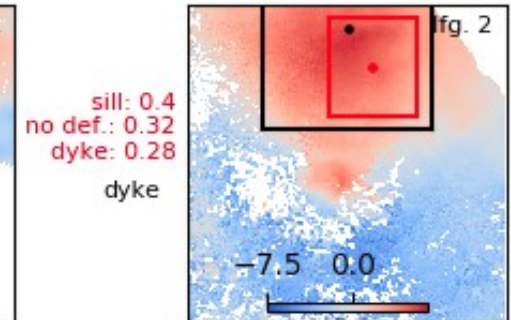
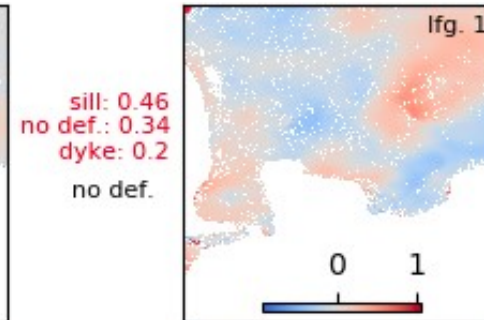
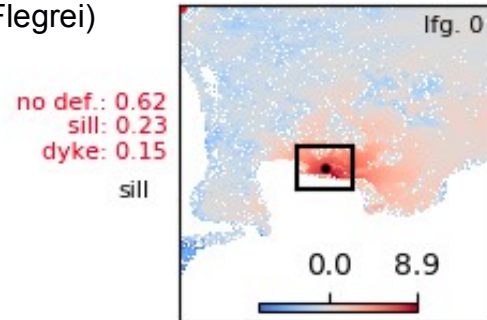


Results

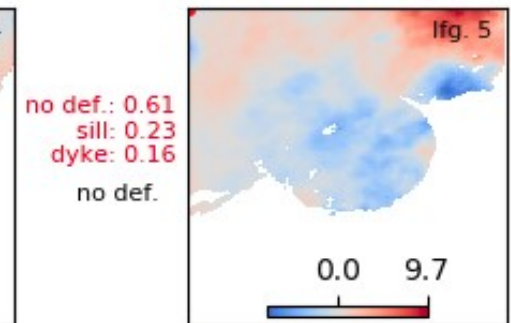
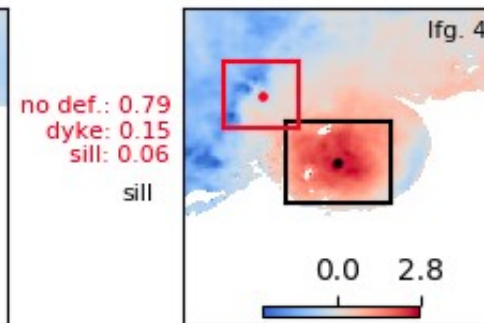
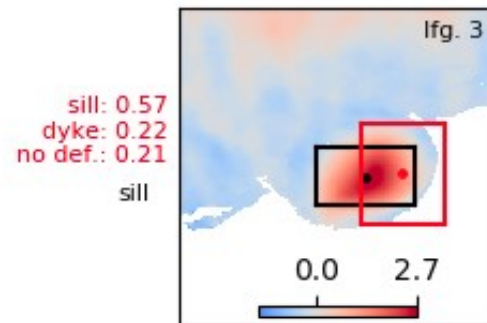


- Results with real data:
 - units = cm
- Black = human added labels (for classification and localisation).
- Red = model predictions. Classification has a probabilistic output, and is expressed as a decimal.

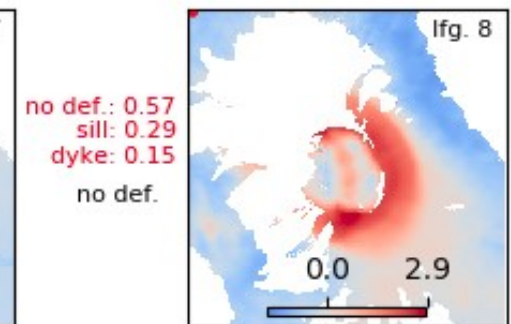
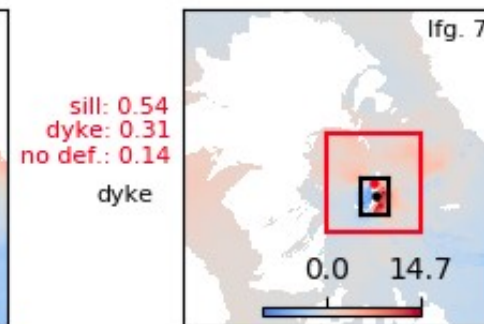
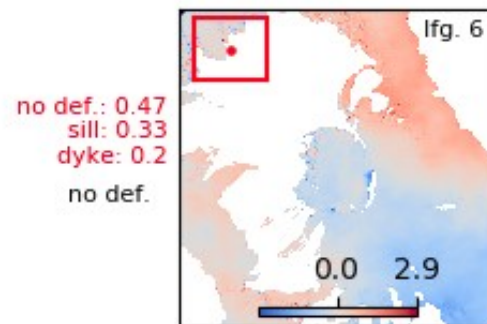
(Campi Flegrei)



(Agung)



(Sierra Negra)

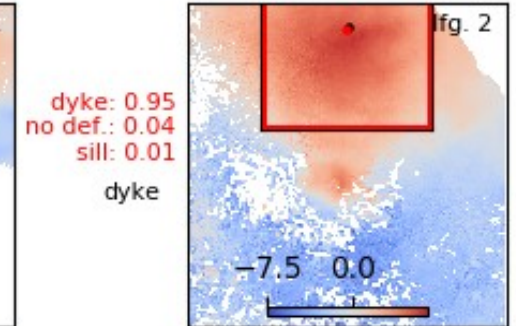
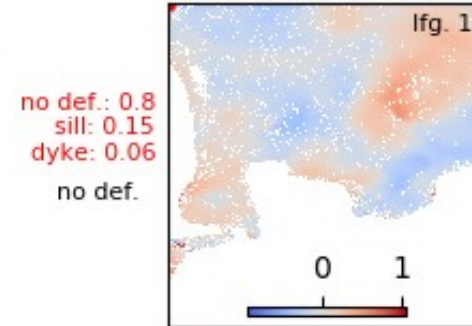
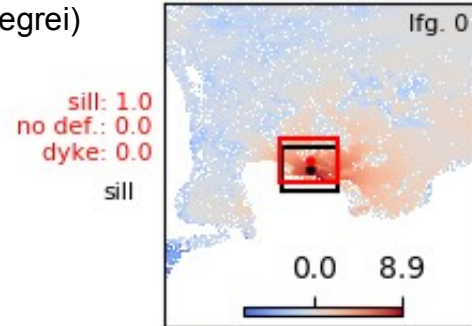


(Wolf)

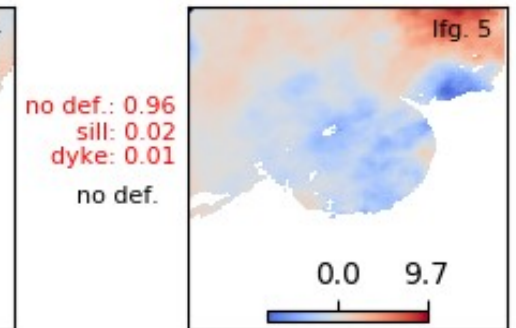
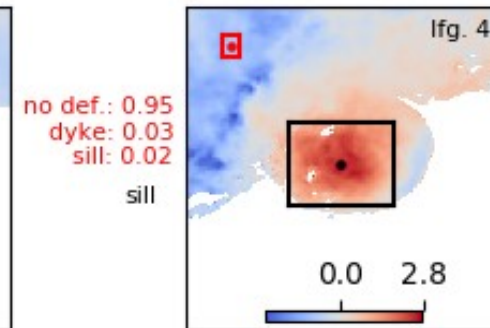
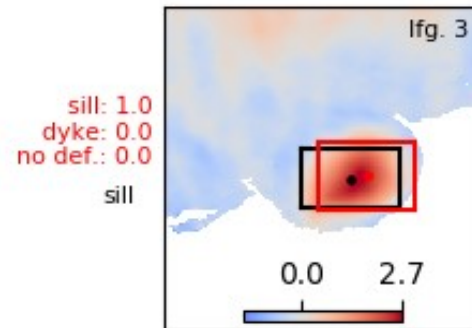


- Results with real data:
 - units = cm
- Black = human added labels (for classification and localisation).
- Red = model predictions. Classification has a probabilistic output, and is expressed as a decimal.
- Training with a small amount of real data improves performance.

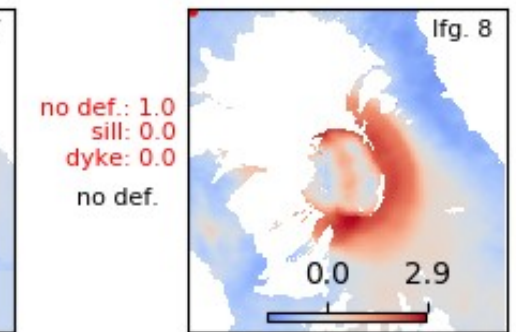
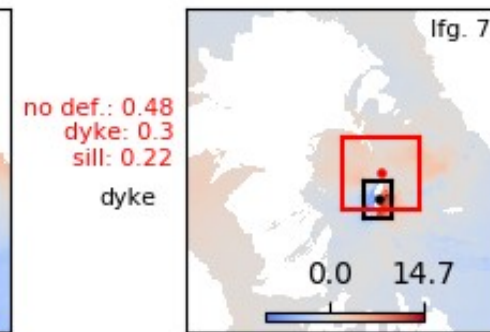
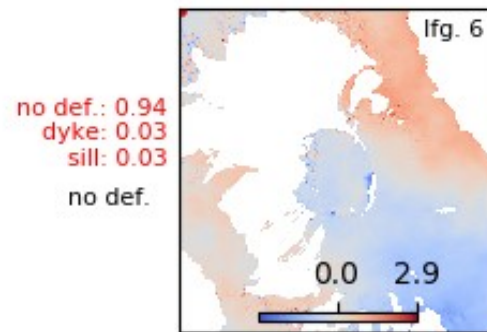
(Campi Flegrei)



(Agung)



(Sierra Negra)



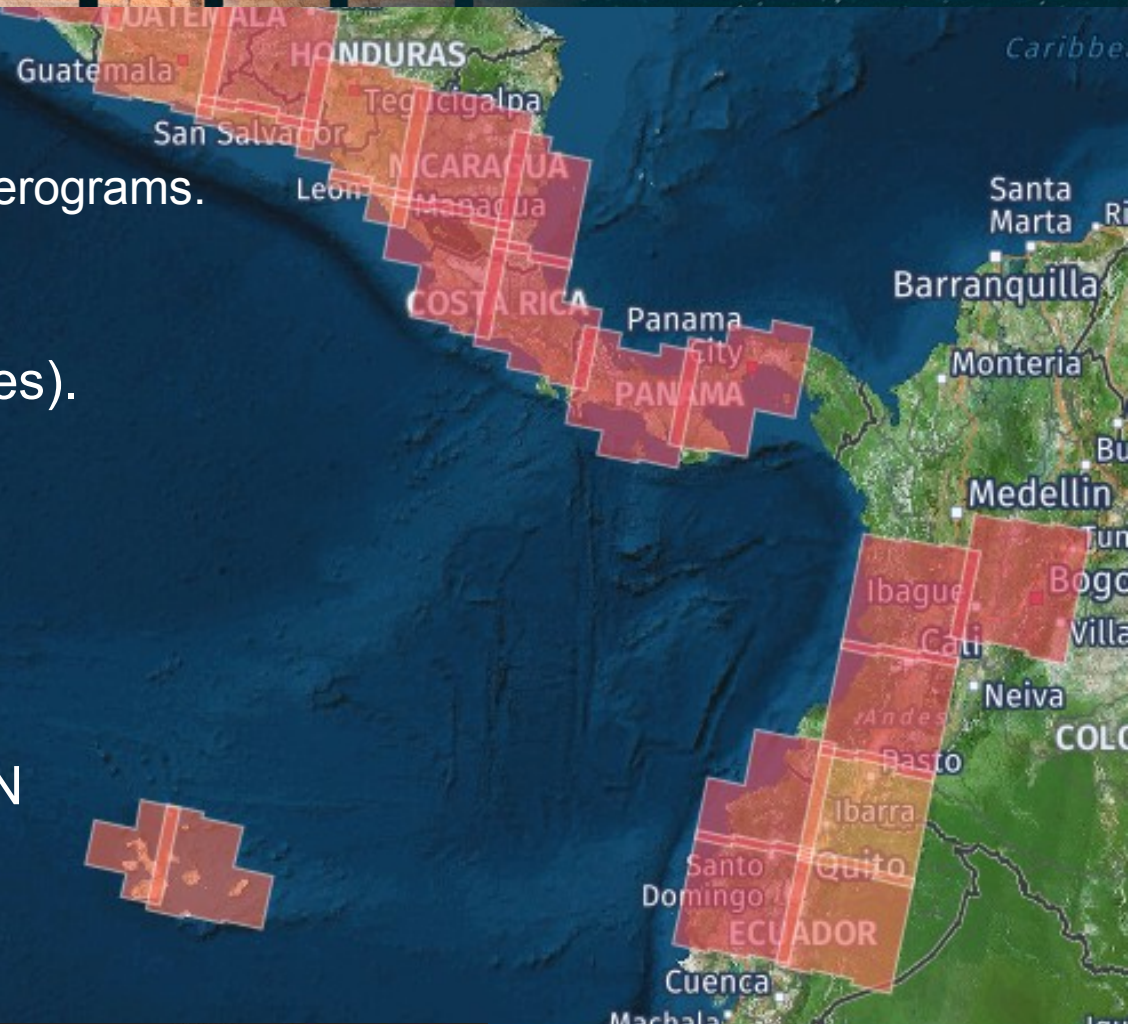
(Wolf)

Gaddes et al., (in prep.)

Conclusions



- The filters contained within convolutional neural networks that were trained on natural images can be used as starting points for models used with unwrapped interferograms.
- Our model can determine the location (and size) of a deformation pattern, and classify it (within three classes).
- Want to try the code?
Synthetic interferograms:
<https://github.com/matthew-gaddes/SyInterferoPy>
Train CNNs:
<https://github.com/matthew-gaddes/Detect-Locate-CNN>



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