

Time / Part	Title	Description and content
Part 1: 9:00 – 12:30	<b>Sentinel-2 and spatial image analysis</b>	1 – Sentinel-2 introduction Exercise 1: „ <i>Introduction into Sentinel-2</i> ”
Part 2: 13:30 – 15:00	<b>Technologies for big EO image analysis</b>	2 – Spatial image analysis 3 – Mission planning with the EO-Compass Exercise 2: „ <i>Mission planning with the EO-Compass</i> ”
Part 3: 15:15 – 17:30	<b>Concepts for time series analysis for land use / land cover</b>	4 – Big Earth observation data analytics - overview 5 – Temporal dimension of EO data 6 – Time series analysis of EO data Exercise 3: „ <i>Investigate forest fires in Andalusia, Spain using a time series of Sentinel-2 images</i> ”

# Sentinel-2 introduction

## Sentinel-2 and spatial image analysis

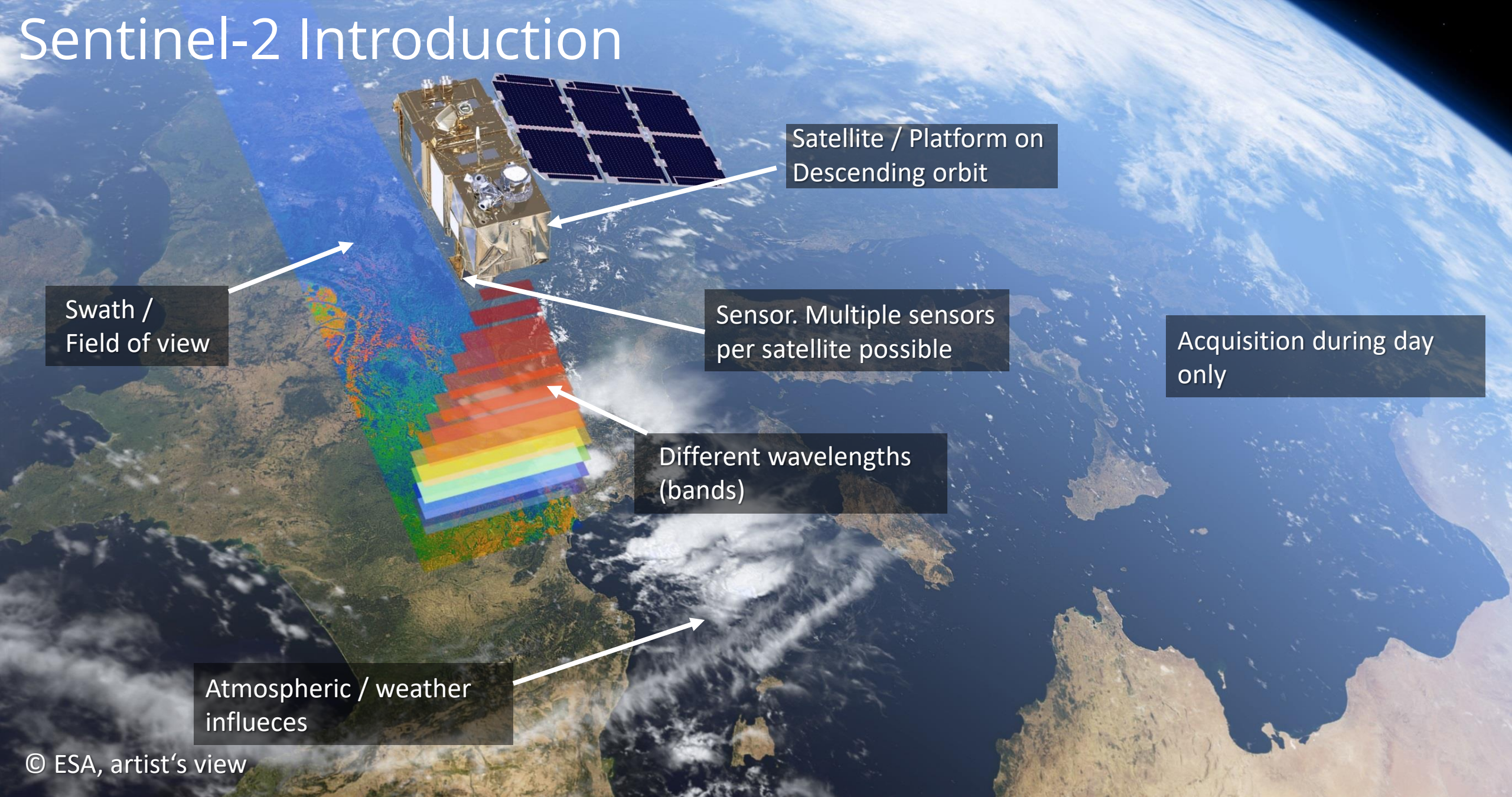
TAT-7 | 21.06.2019 | Martin Sudmanns, Dirk Tiede, Stefan Lang, & contrib.  
Z\_GIS colleagues

Interfaculty Department of Geoinformatics – Z\_GIS, University of Salzburg

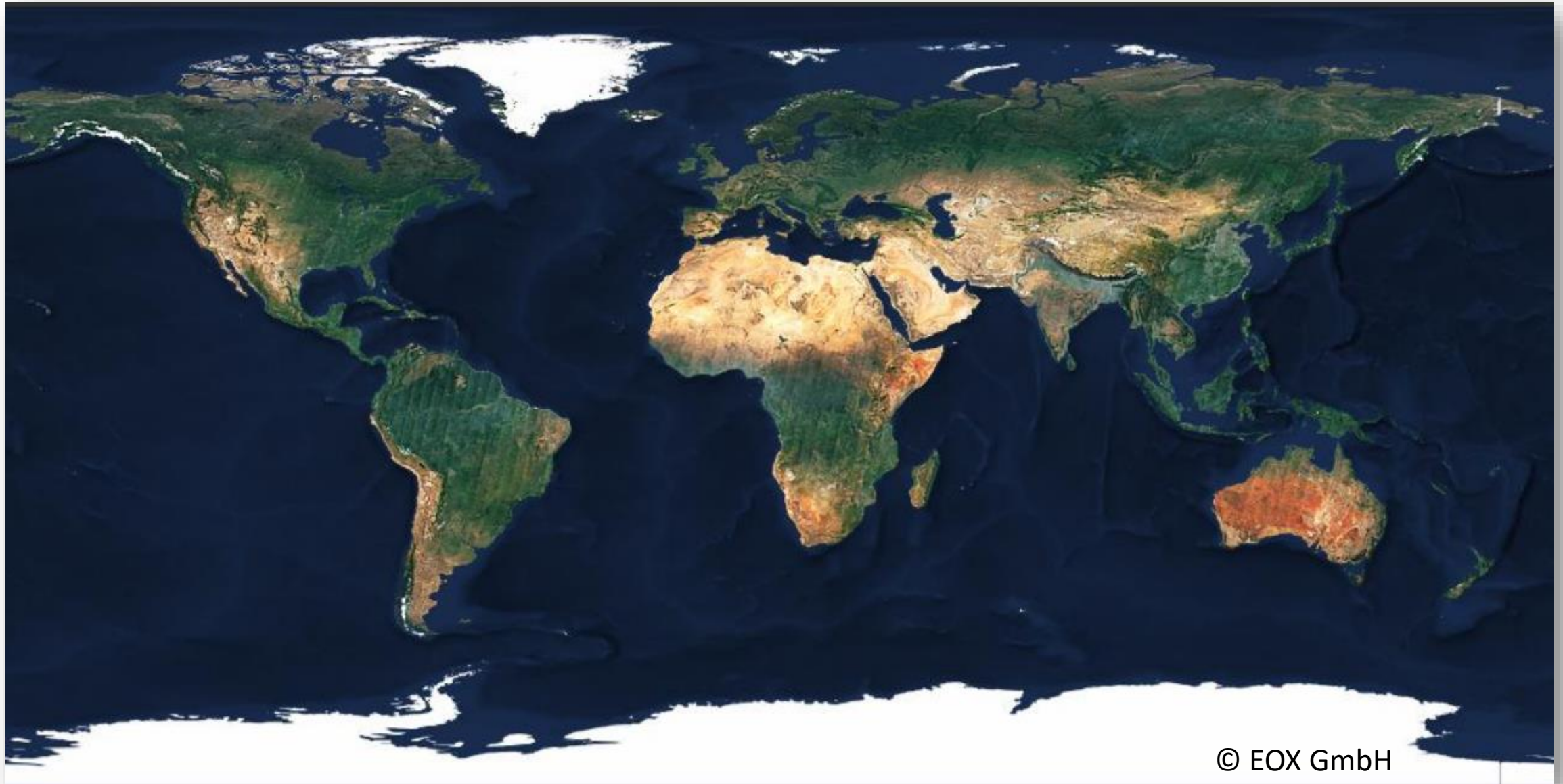
# Sentinel-2 Introduction



# Sentinel-2 Introduction

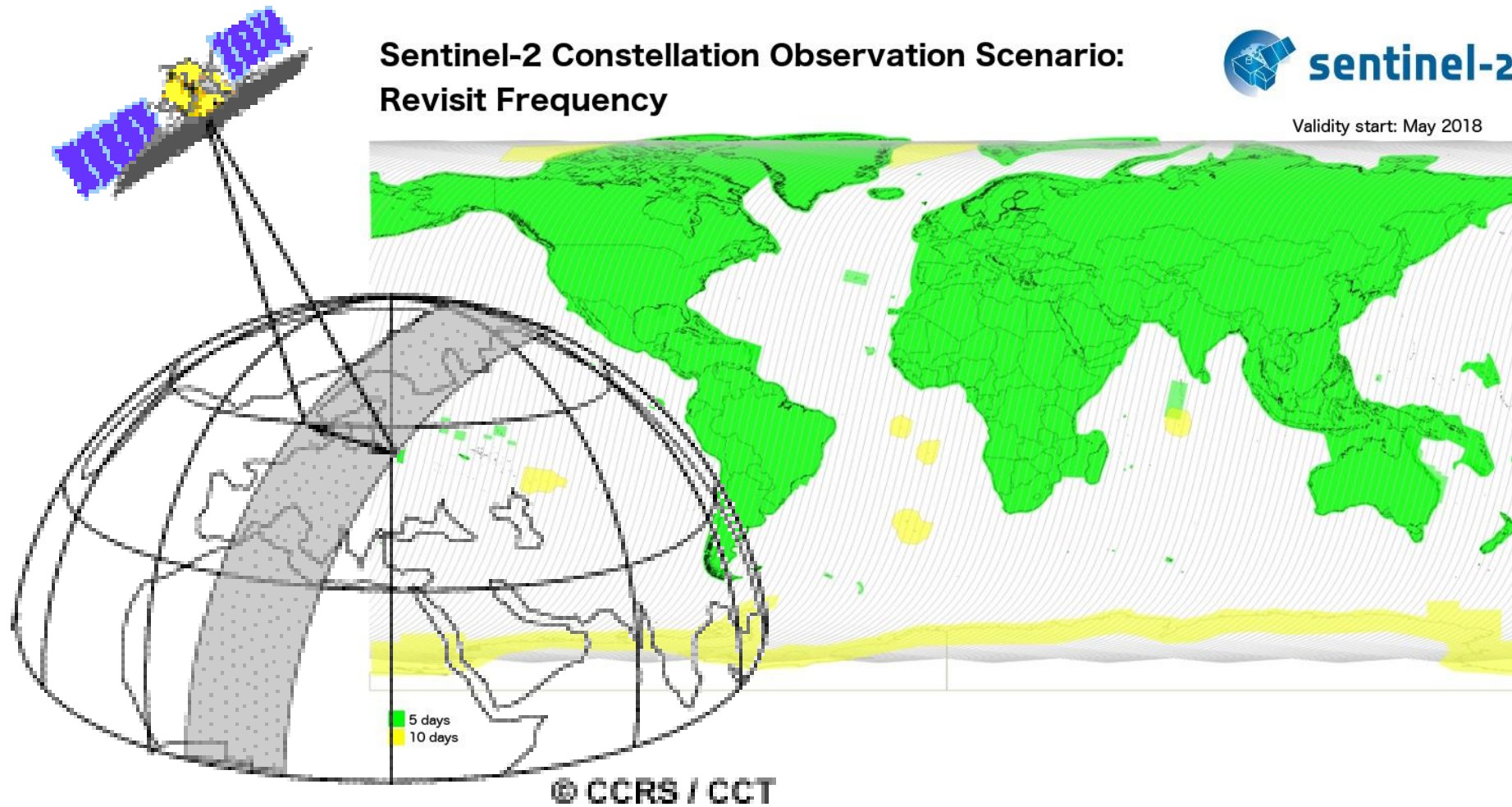


# Sentinel-2 Introduction

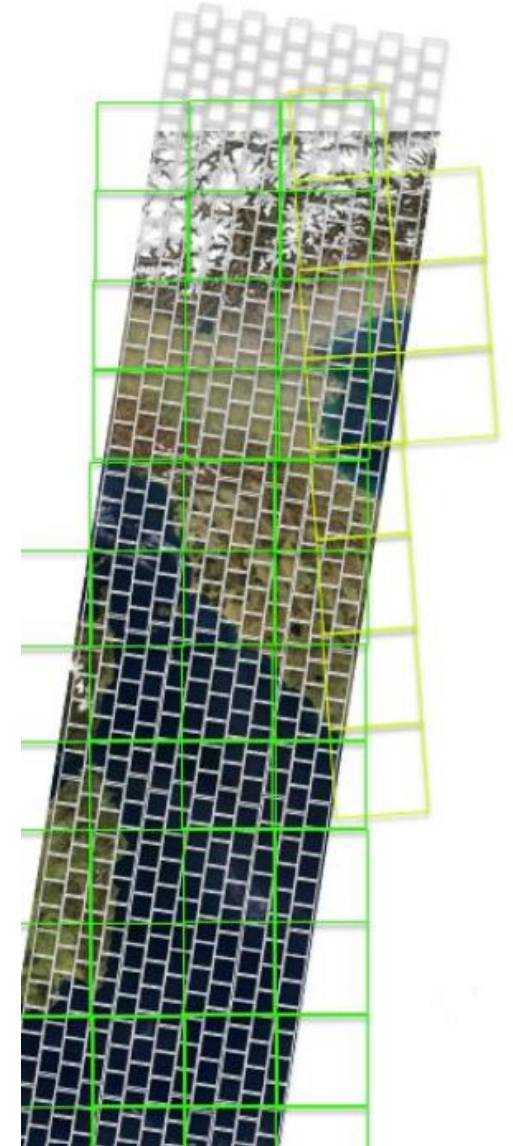


© EOX GmbH

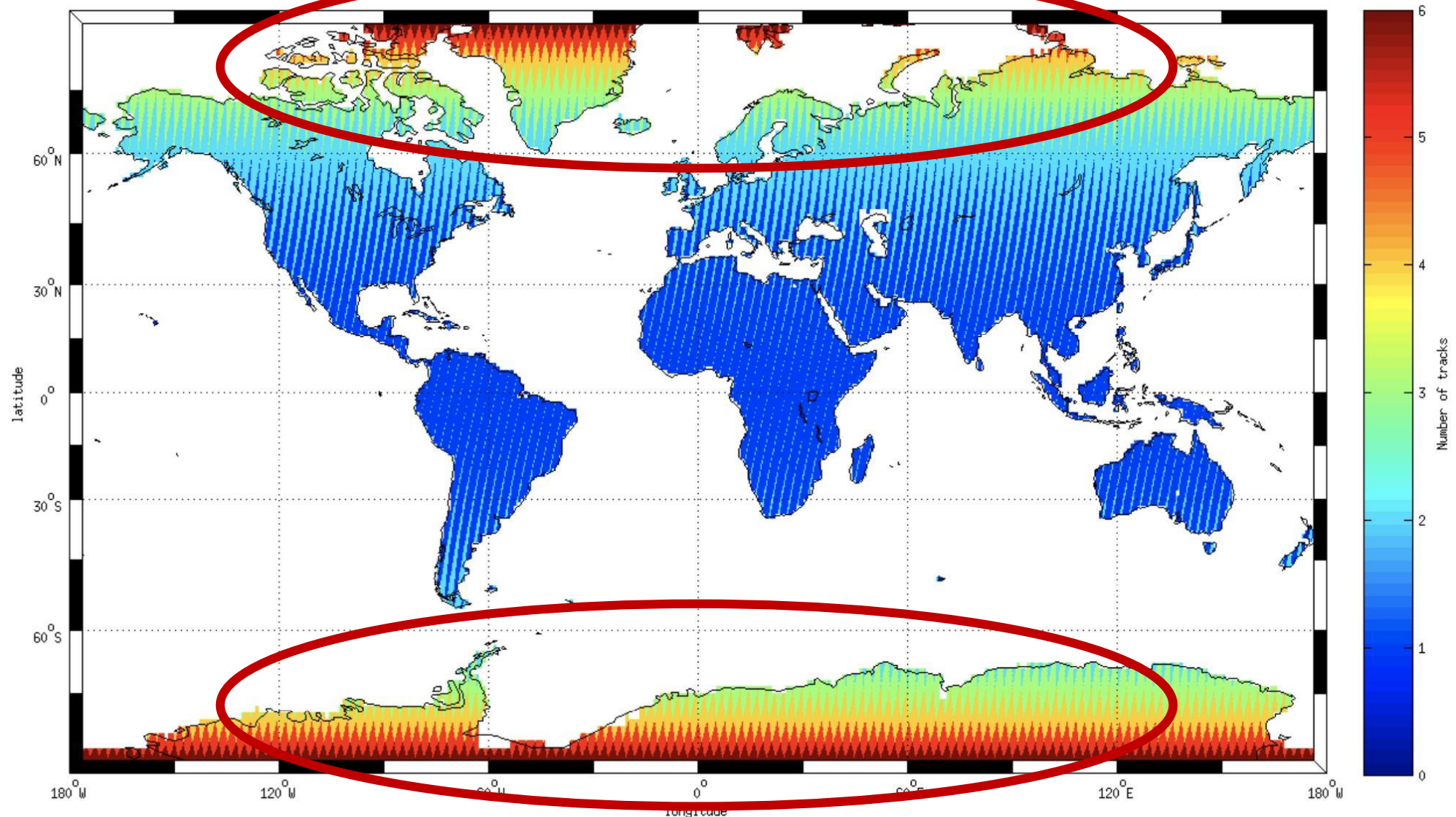
# Sentinel-2 Acquisitions



<https://sentinel.esa.int/web/sentinel/user-guides/sentinel-2-msi/revisit-coverage>

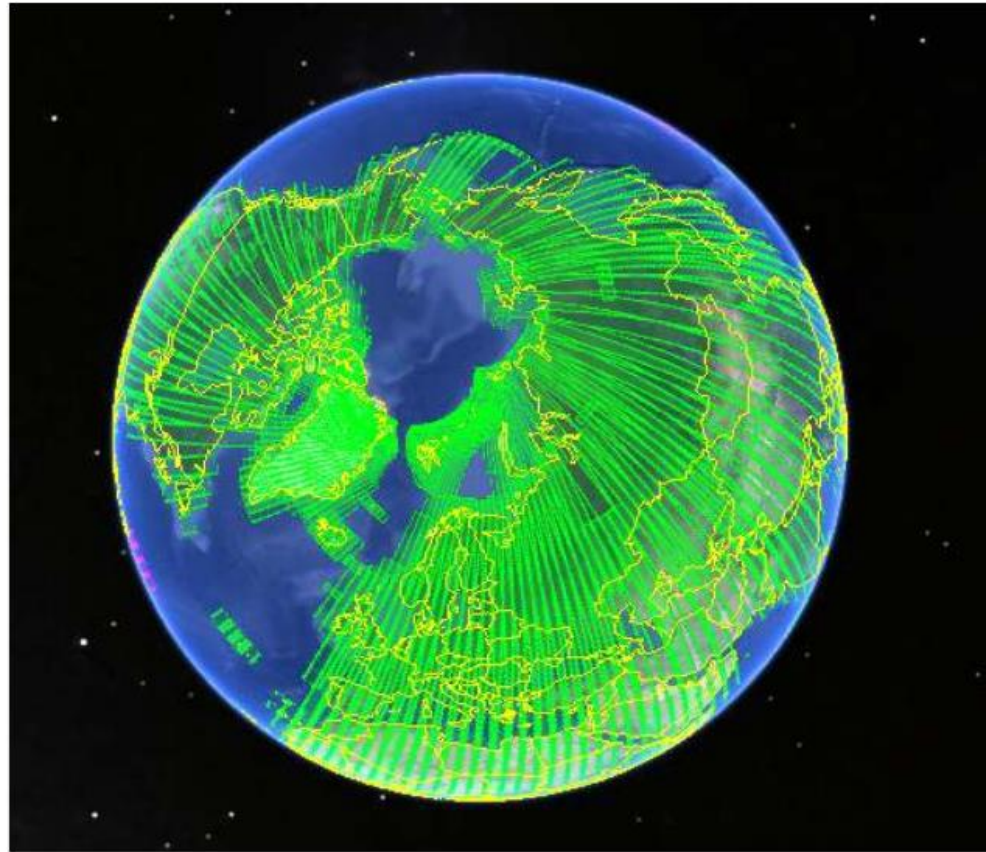


# Sentinel-2 Acquisitions

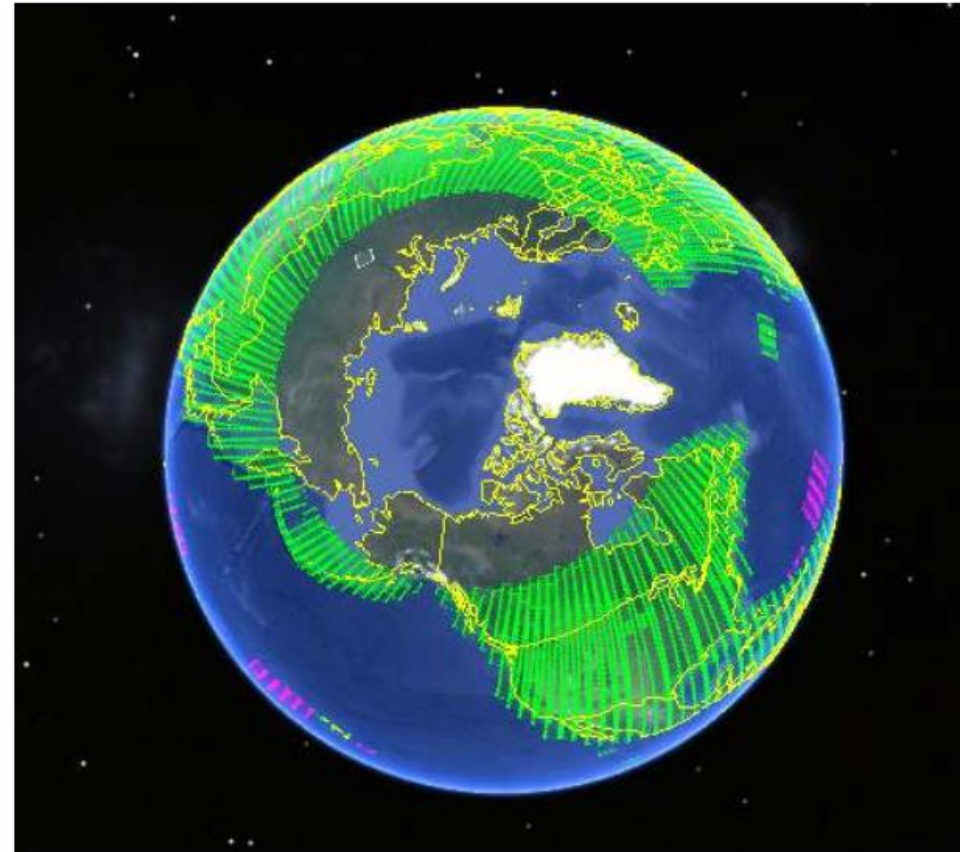


<https://sentinel.esa.int/web/sentinel/user-guides/sentinel-2-msi/revisit-coverage>

# Sentinel-2 Acquisitions



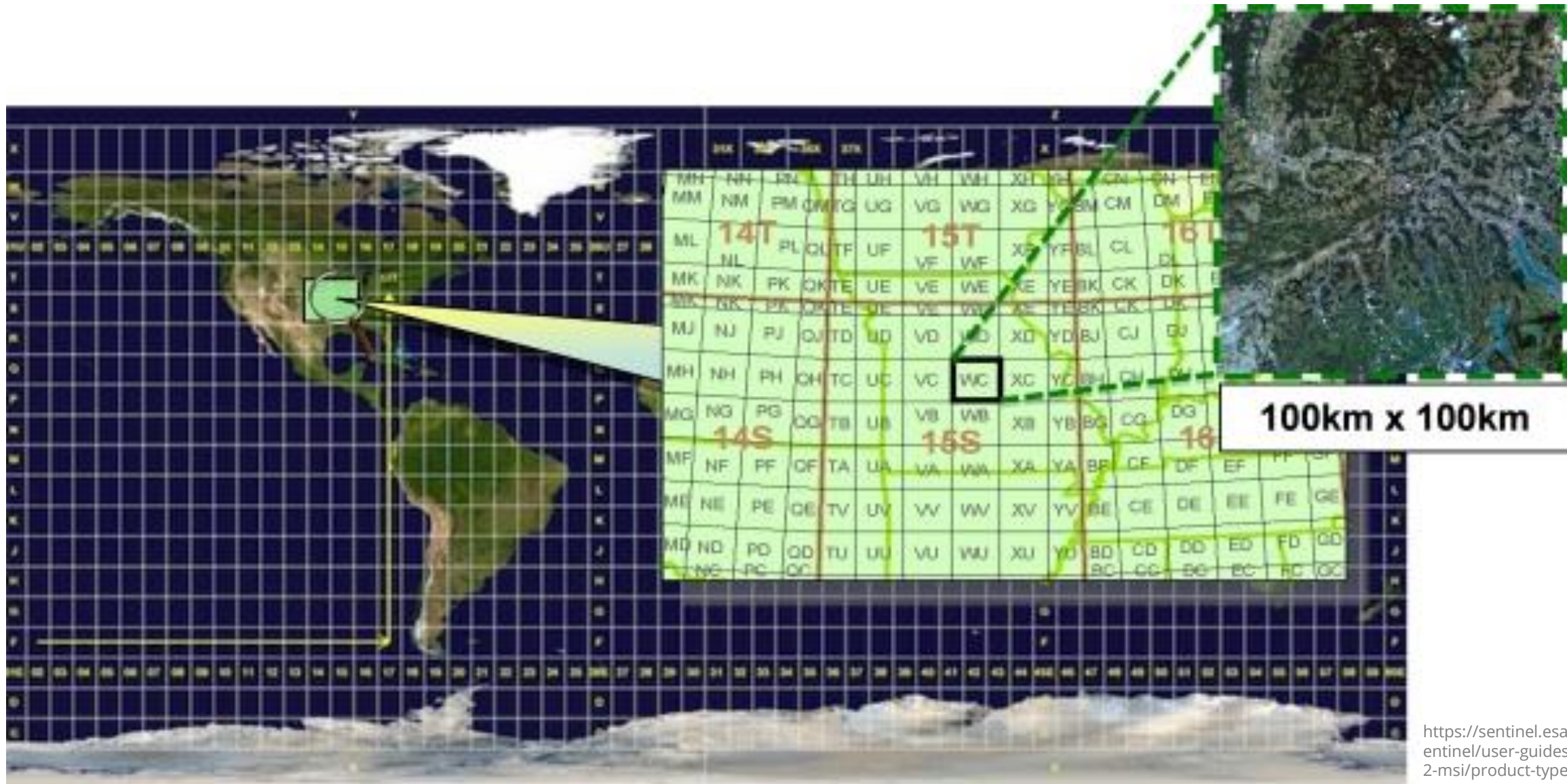
(a)



(b)

[https://scihub.copernicus.eu/twiki/pub/SciHubWebPortal/AnnualReport2017/COPE-SERCO-RP-17-0186\\_-\\_Sentinel\\_Data\\_Access\\_Annual\\_Report\\_2017-Final\\_v1.4.1.pdf](https://scihub.copernicus.eu/twiki/pub/SciHubWebPortal/AnnualReport2017/COPE-SERCO-RP-17-0186_-_Sentinel_Data_Access_Annual_Report_2017-Final_v1.4.1.pdf)

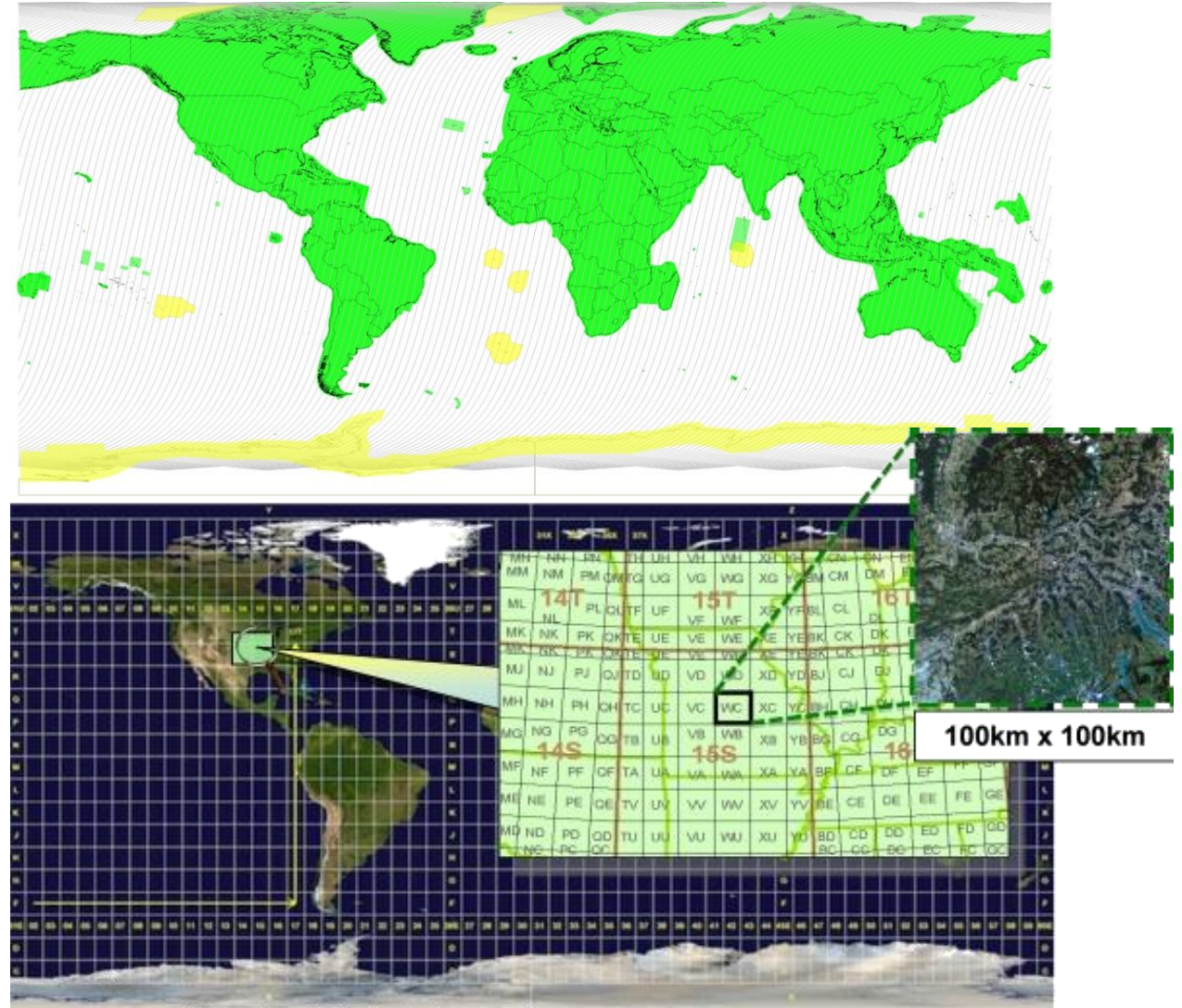
# Sentinel-2 Acquisitions



<https://sentinel.esa.int/web/sentinel/user-guides/sentinel-2-msi/product-types>

# Sentinel-2 Acquisitions

- **Datatake:** The continuous acquisition of an image from one SENTINEL-2 satellite in a given MSI imaging mode is called a "datatake". The maximum length of an imaging datatake is 15,000 km (continuous observation from northern Russia to southern Africa).
- **Granule / Tile:** For Level-1C and Level-2A, the granules, also called tiles, are 10,000 km<sup>2</sup> ortho-images in UTM/WGS84 projection. It is a part of the datatake and has a metadata file.



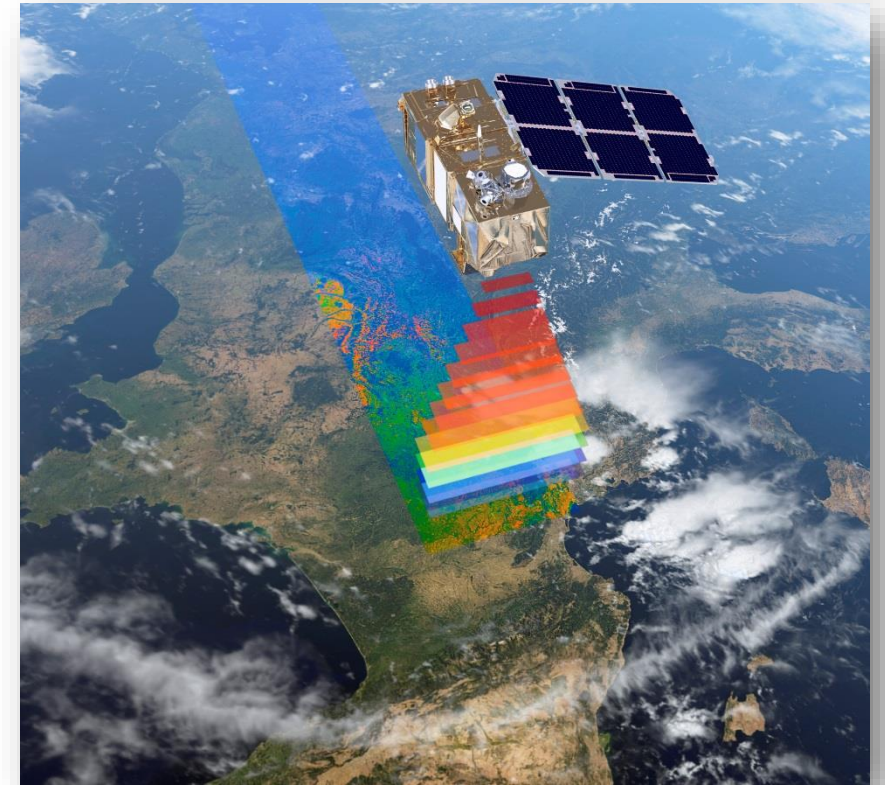
# Sentinel-2 Acquisitions



0 days 00 hours 00 minutes  
Sentinel-2 constellation:  
summer solstice

# Sentinel-2 Facts

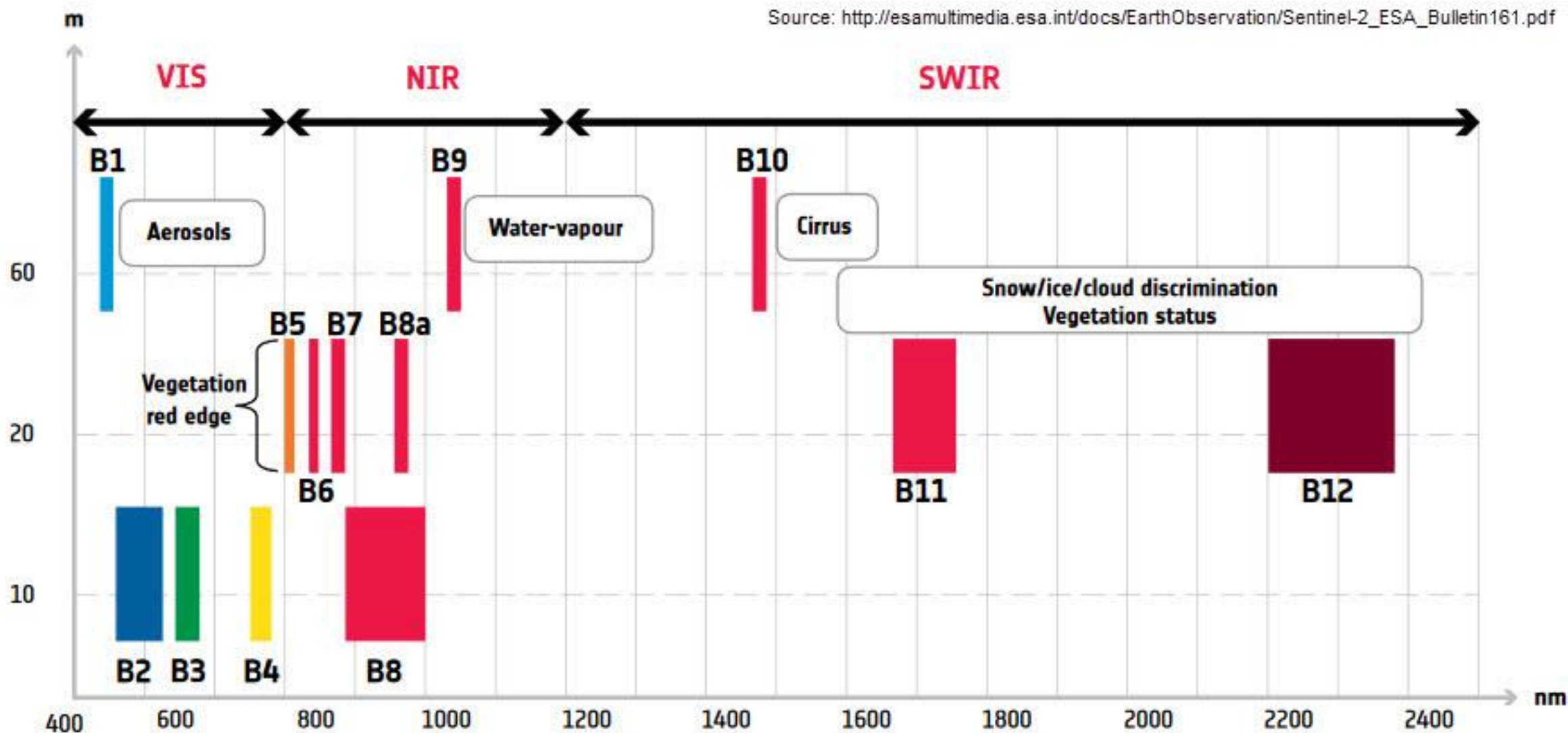
- **Optical instrument MSI (Multi-Spectral Imager)**
  - 290 km swath
  - 13 spectral channels (443 nm - 2190 nm)
  - Spatial resolution: 10, 20 and 60 m
- Sentinel 2 **A + B in orbit**
- Acquisition frequency: **5 days** at least
- Main application areas:
  - Agriculture, forestry
  - Land-use (change)
  - Water bodies
  - Emergency mapping / monitoring

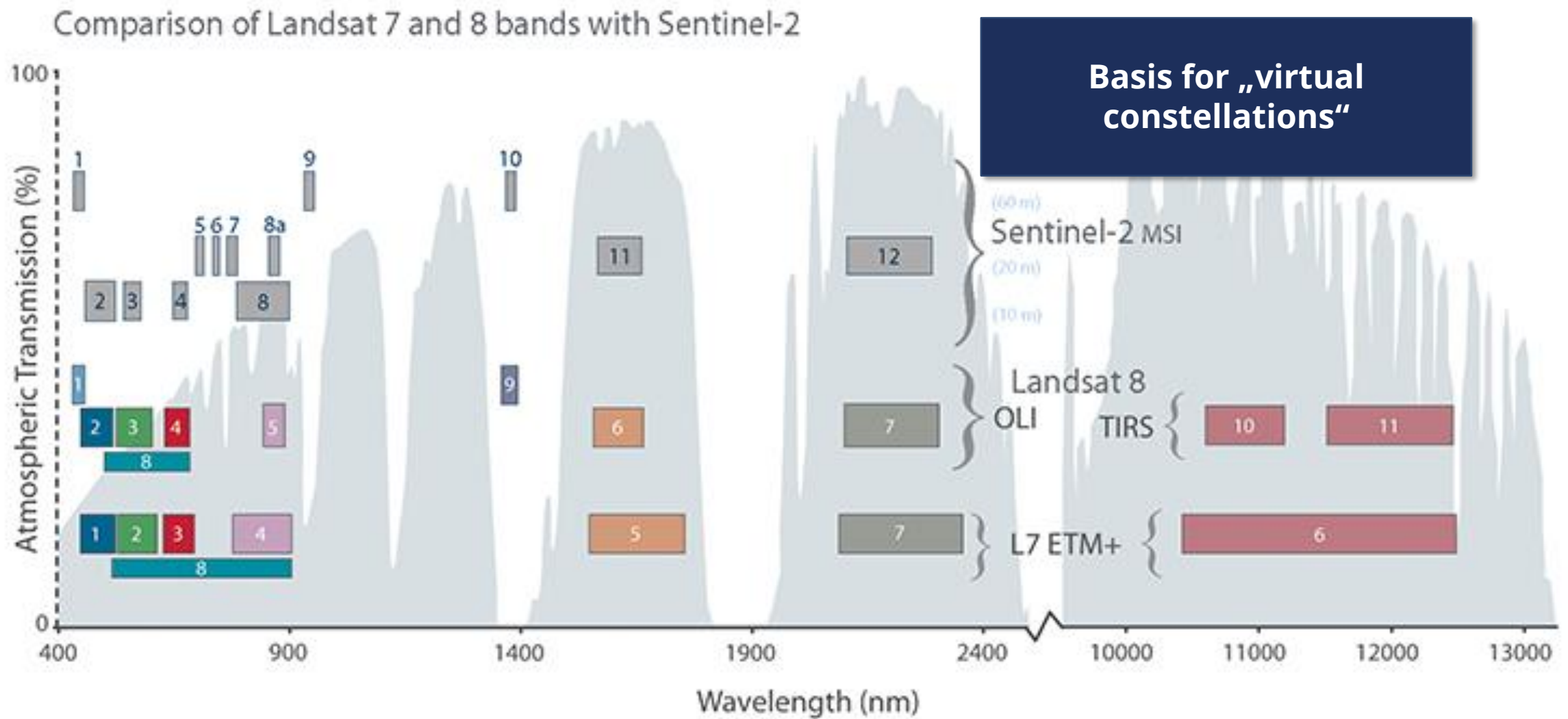


## Sentinel-2 Website

[http://www.esa.int/Our\\_Activities/Observing\\_the\\_Earth/Copernicus/Sentinel-2/](http://www.esa.int/Our_Activities/Observing_the_Earth/Copernicus/Sentinel-2/)

# Sentinel-2 Facts





## Level 2A for optical EO data according ESA definition<sup>1</sup> consists of:

1. **Image corrected** for atmospheric, adjacency and topographic effects
2. **Scene classification map** (pre-requisite for atmospheric correction)
3. **Quality indicators** (e.g. also as masks)

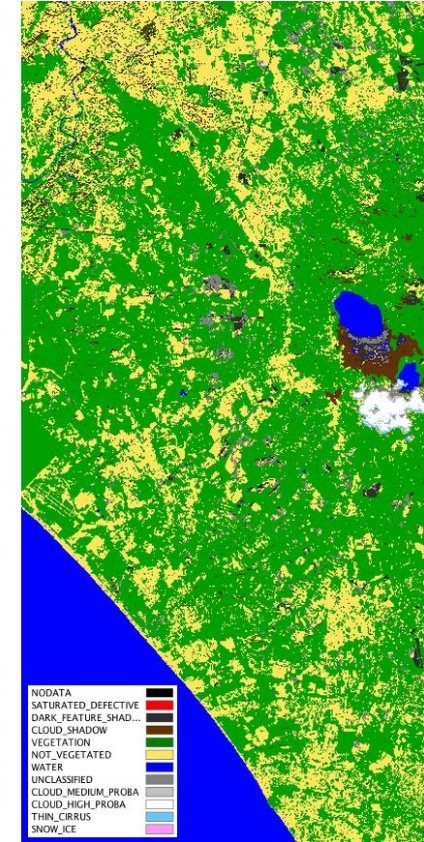
Top of  
Atmosphere  
(TOA) Level 1C



Bottom of  
Atmosphere  
(BOA) Level 2A



Scene classification  
map and quality  
indicators

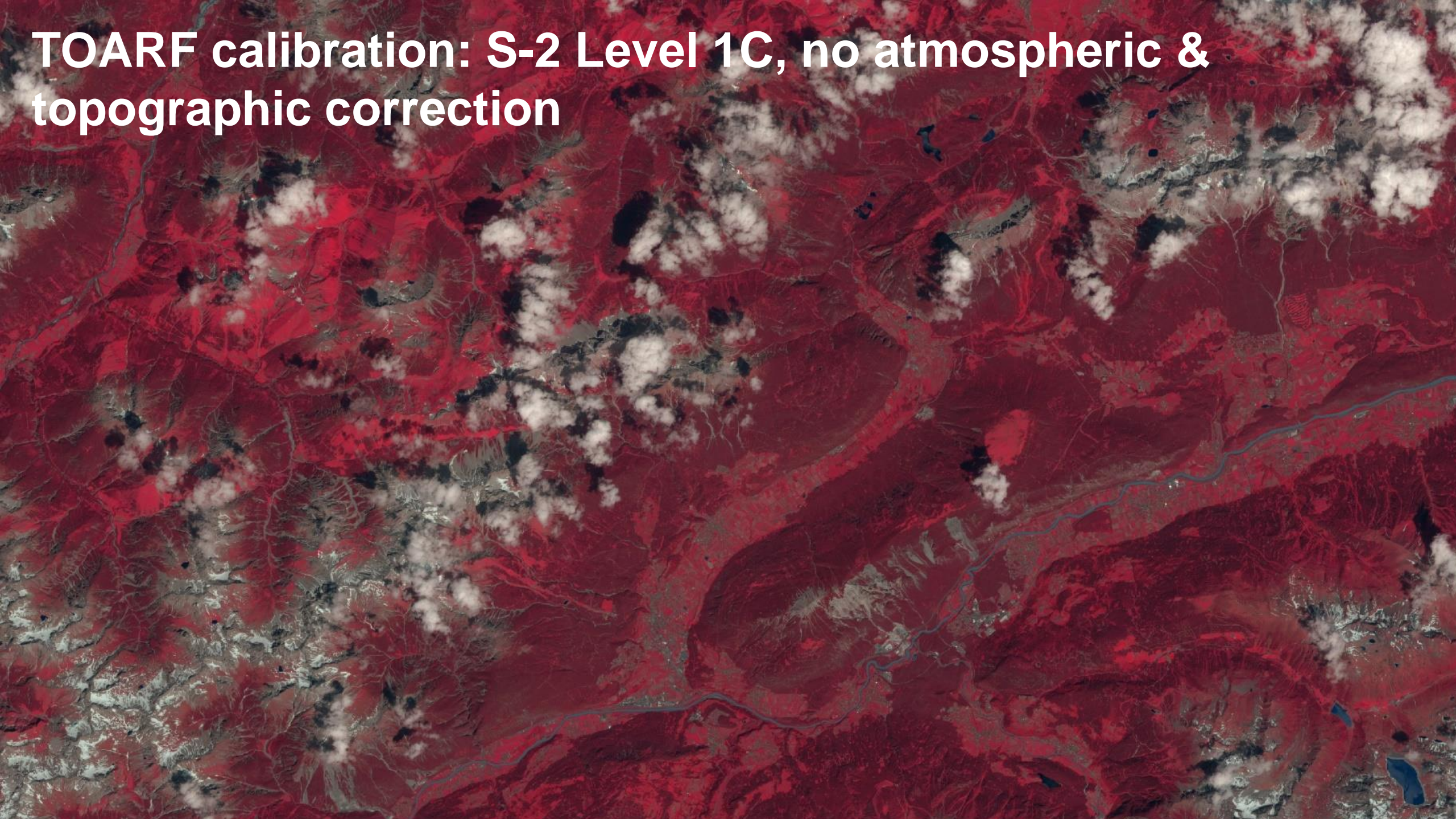


It is not possible to remove clouds completely

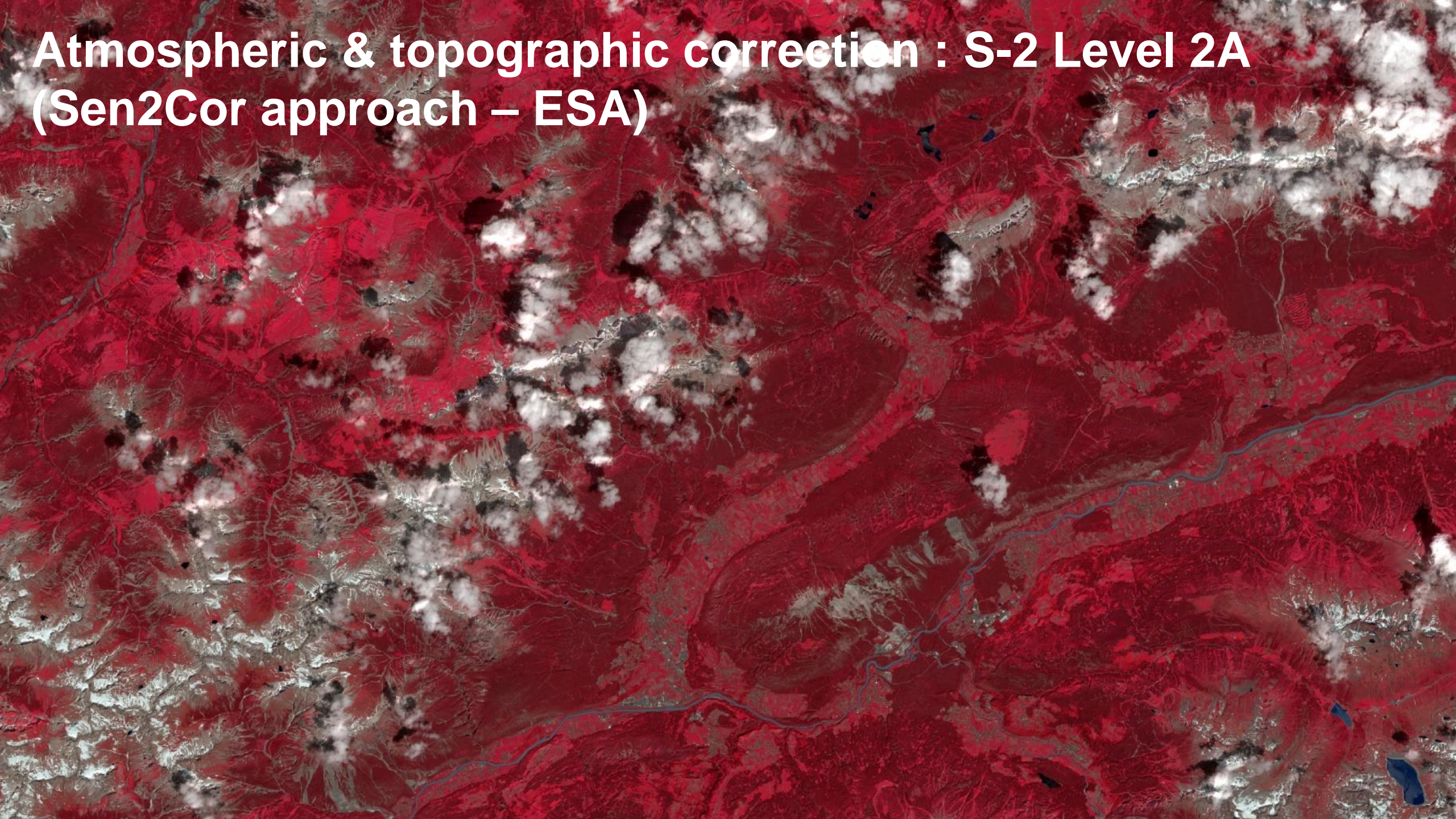
<sup>1</sup> Level 2A Products Algorithm Theoretical Basis Document ([https://earth.esa.int/c/document\\_library/get\\_file?folderId=349490&name=DLFE-4518.pdf](https://earth.esa.int/c/document_library/get_file?folderId=349490&name=DLFE-4518.pdf))

<https://sentinel.esa.int/documents/247904/3681608/Sentinel-2-Level-1C-2A-TOA-processing-full.png>

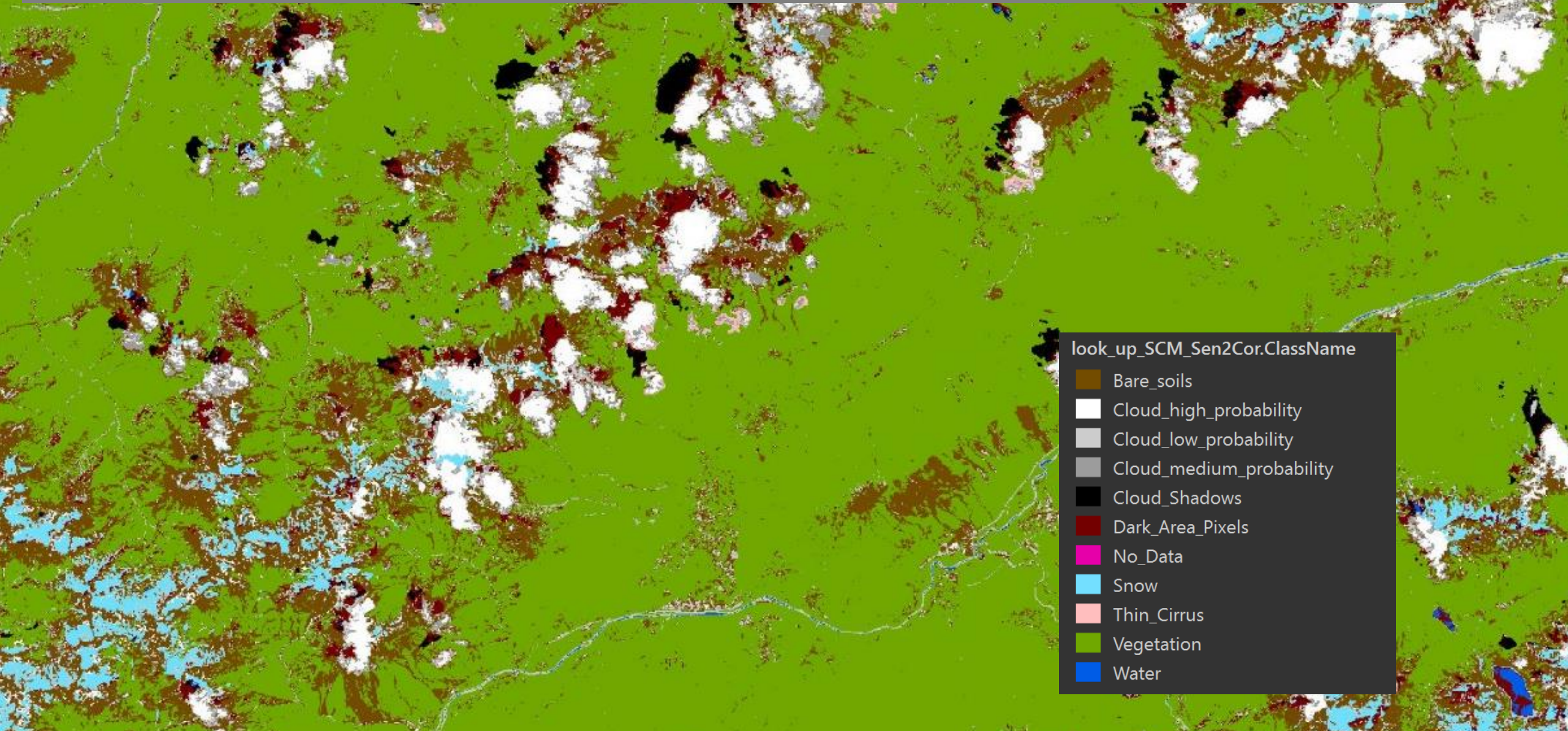
**TOARF calibration: S-2 Level 1C, no atmospheric & topographic correction**



# Atmospheric & topographic correction : S-2 Level 2A (Sen2Cor approach – ESA)



# Atmospheric & topographic correction : S-2 Level 2A (Sen2Cor scene classification map – 20m resolution)



- Processing levels of satellite data are not standardised and depend on the organisation (e.g. ESA, NASA other satellite providers) and the different satellites

Definition by ESA and CNES, compliant with the norms of the Committee on Earth Observation Satellites (CEOS):

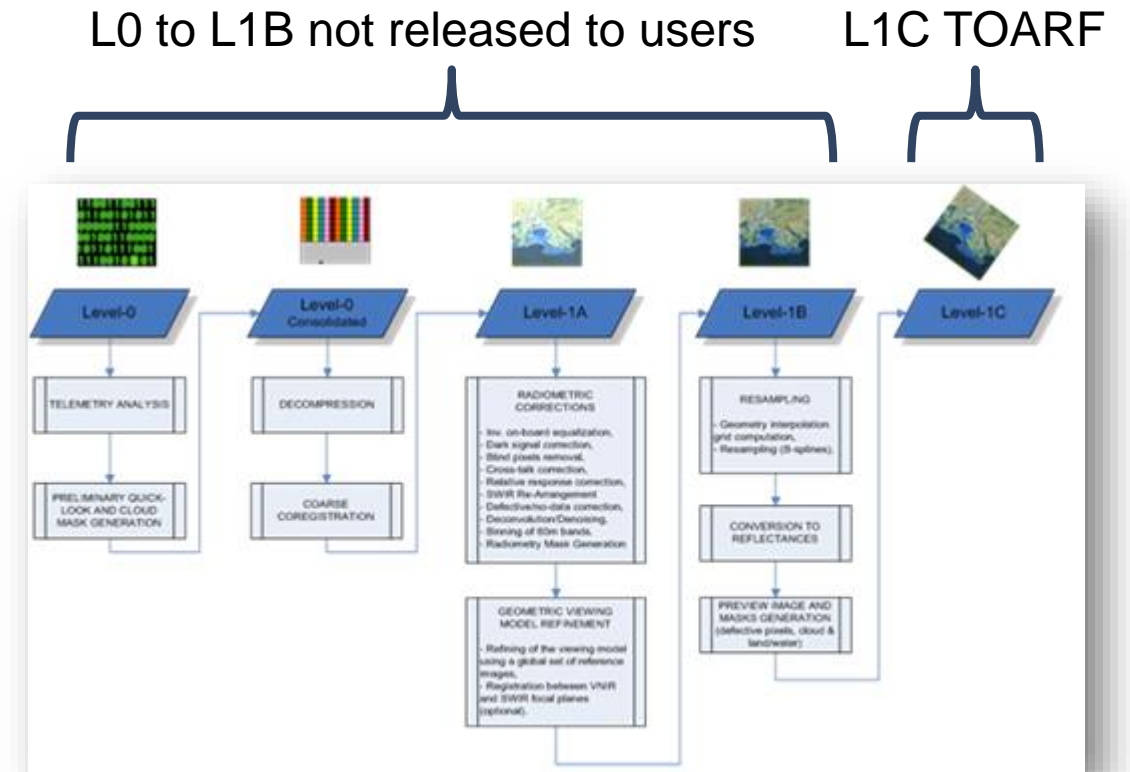
- Level 1C is a monodate ortho-rectified image expressed in TOA reflectance
- Level 2A is a monodate ortho-rectified image expressed in surface reflectance, provided with a cloud/cloud shadow/snow/water mask
- Level 3A is a monthly composite of Level2A Cloud/Cloud-shadow-free pixels

Data Level	NASA-EOSDIS Definition <a href="http://science.nasa.gov/earth-science/earth-science-data/data-processing-levels-for-eosdis-data-products/">http://science.nasa.gov/earth-science/earth-science-data/data-processing-levels-for-eosdis-data-products/</a>
Level 0	Reconstructed, unprocessed instrument and payload data at full resolution, with any and all communications artifacts (e.g., synchronization frames, communications headers, duplicate data) removed.
Level 1A	Reconstructed, unprocessed instrument data at full resolution, time-referenced, and annotated with ancillary information, including radiometric and geometric calibration coefficients and georeferencing parameters (e.g., platform ephemeris) computed and appended but not applied to Level 0 data.
Level 1B	Level 1A data that have been processed to sensor units (not all instruments have Level 1B source data).
Level 2	Derived geophysical variables at the same resolution and location as Level 1 source data.
Level 3	Variables mapped on uniform space-time grid scales, usually with some completeness and consistency.
Level 4	Model output or results from analyses of lower-level data (e.g., variables derived from multiple measurements).

# Sentinel-2 processing levels

## ESA Sentinel-2 processing chain:

- All data acquired by the MSI instrument are systematically processed to Level-1C by the Payload Data Ground Segment (PDGS).
- Only the Level-1C and Level-2A products are released to Users.
- Level-2A products are generated either by the PDGS using the Sen2Cor processor, or on the User side through the Sen2Cor Toolbox (standalone or within SNAP)



A faint, light blue world map is visible in the background of the slide, showing the outlines of continents and oceans. The map is centered on the Atlantic Ocean, with North and South America on the left and Europe, Africa, and Asia on the right.

## **Exercise 1:**

## Introduction into Sentinel-2

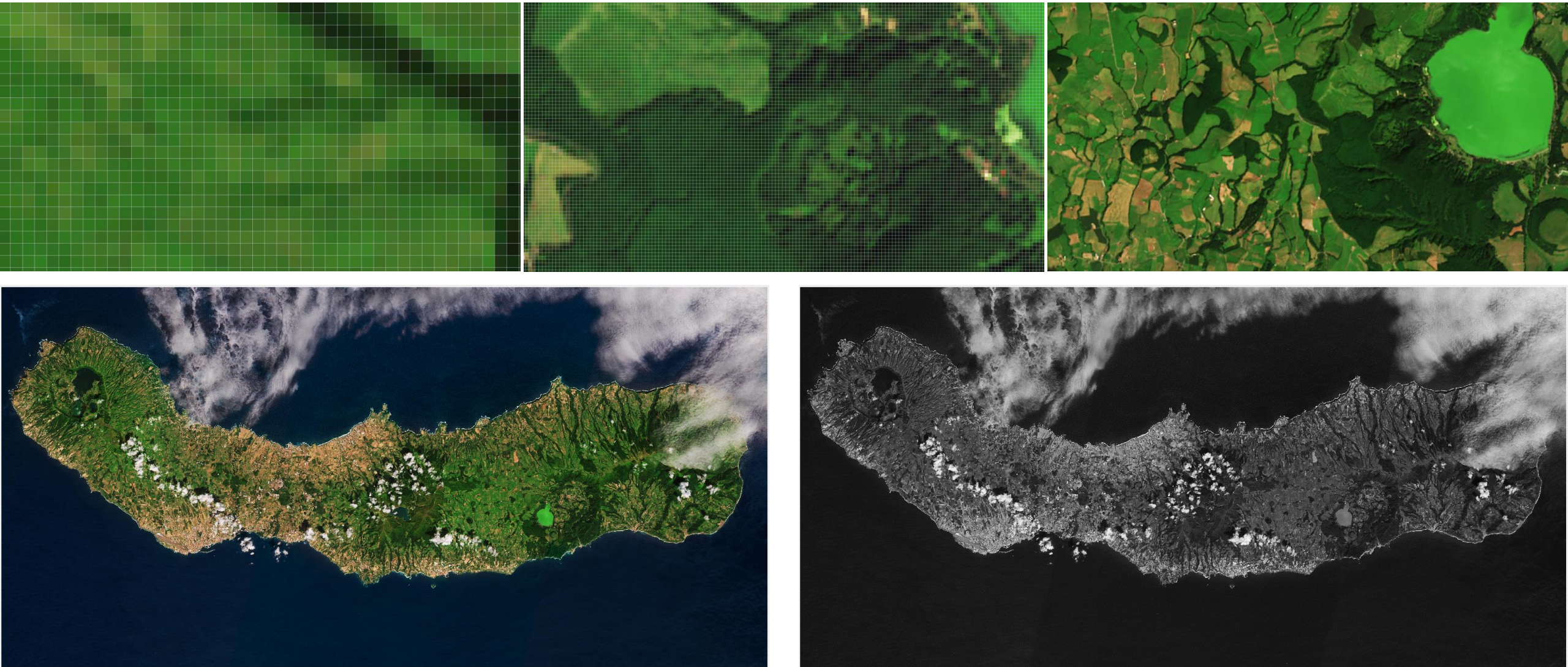
# Spatial image analysis

## Sentinel-2 and spatial image analysis

TAT-7 | 21.06.2019 | Martin Sudmanns, Dirk Tiede, Stefan Lang, & contrib.  
Z\_GIS colleagues

Interfaculty Department of Geoinformatics – Z\_GIS, University of Salzburg

# Where is the *space* in spatial analysis?







?



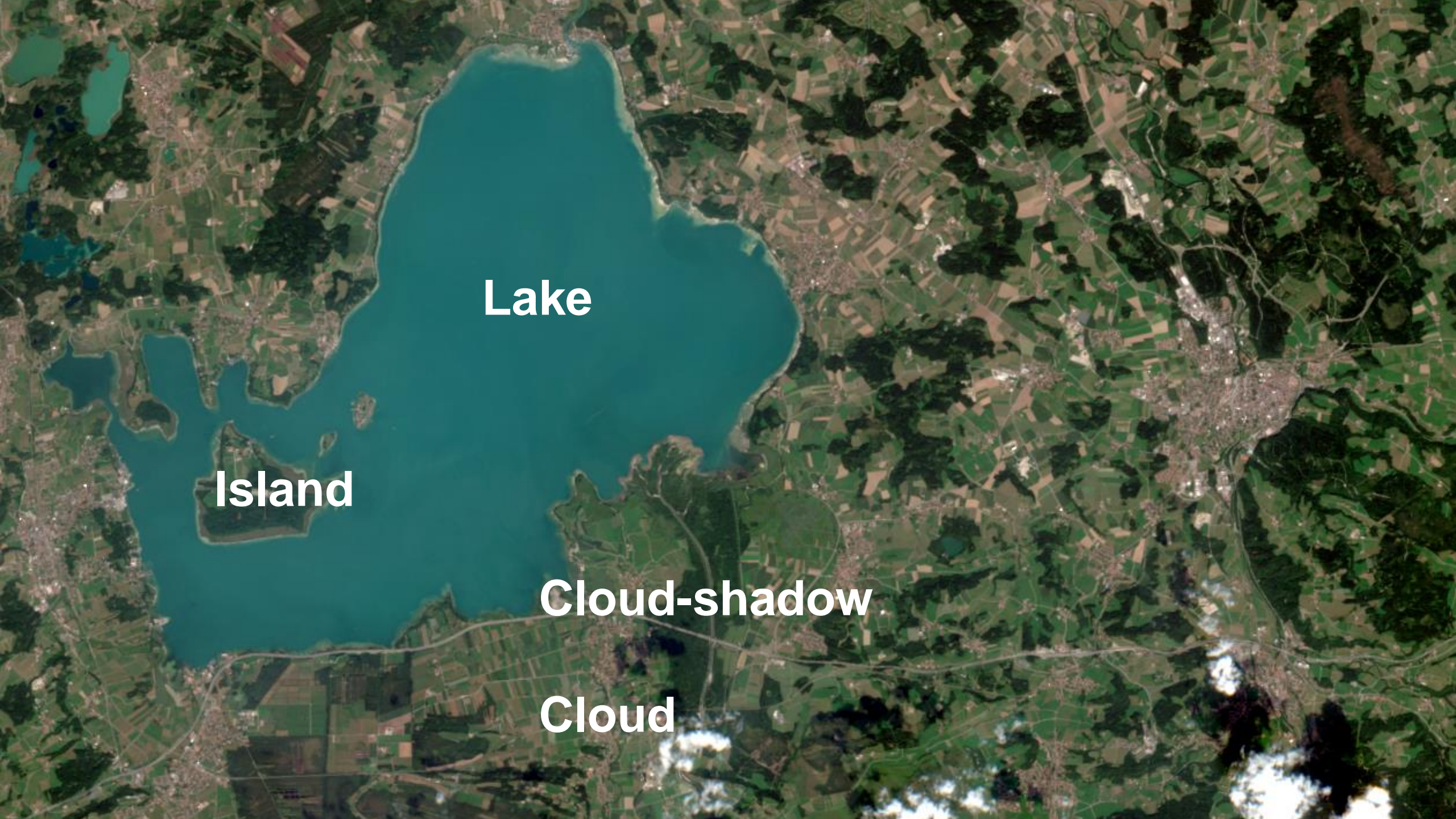


?

?

?





**Lake**

**Island**

**Cloud-shadow**

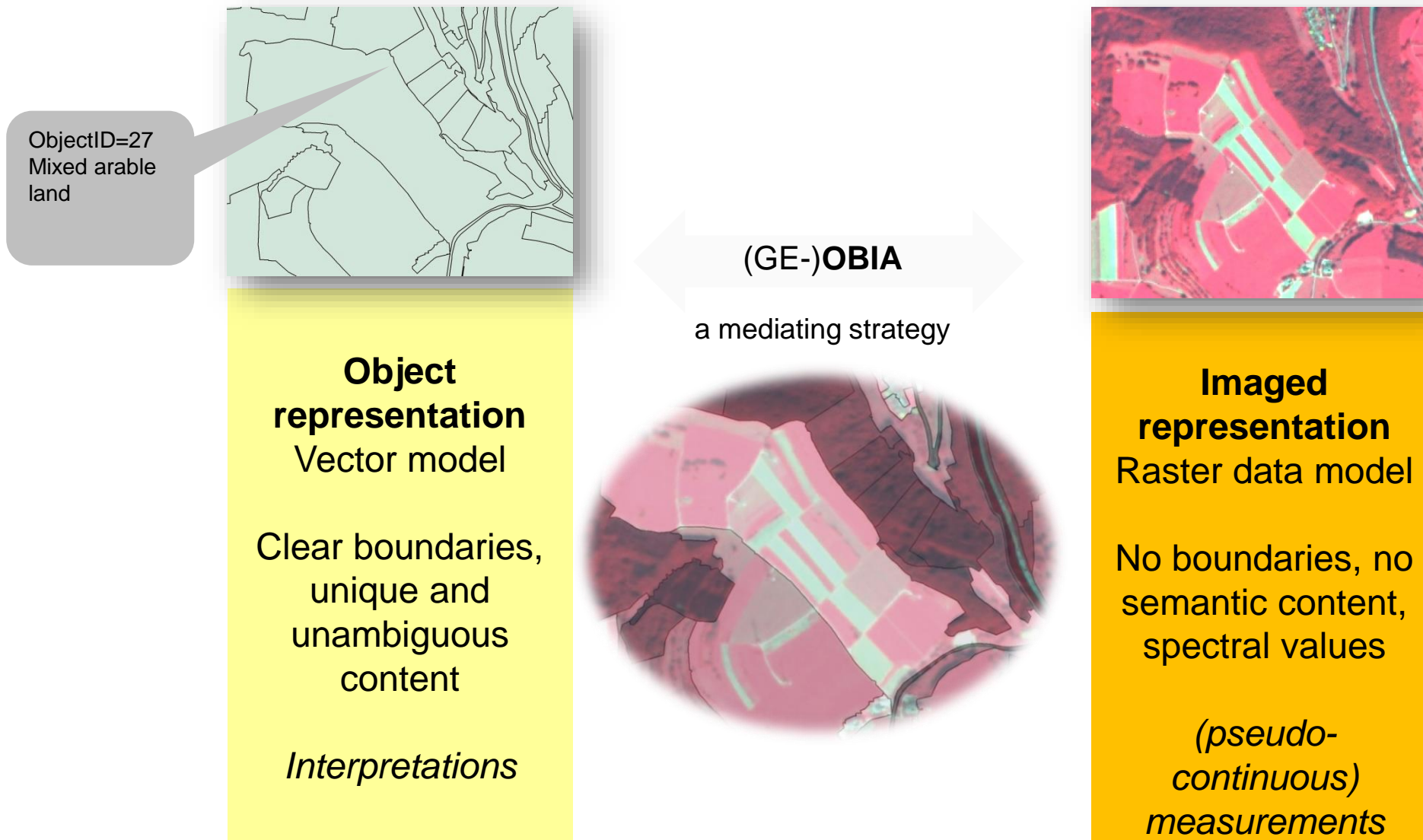
**Cloud**



**Which of the objects  
did you identify by colour only?**

**Would you be able to identify some of the  
objects based on colour through time?**

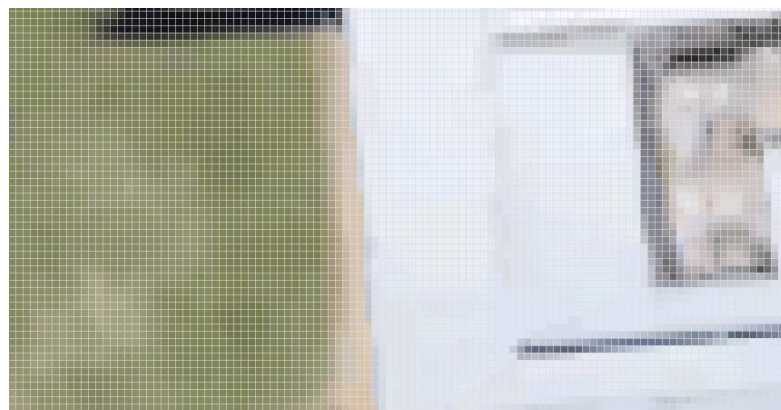
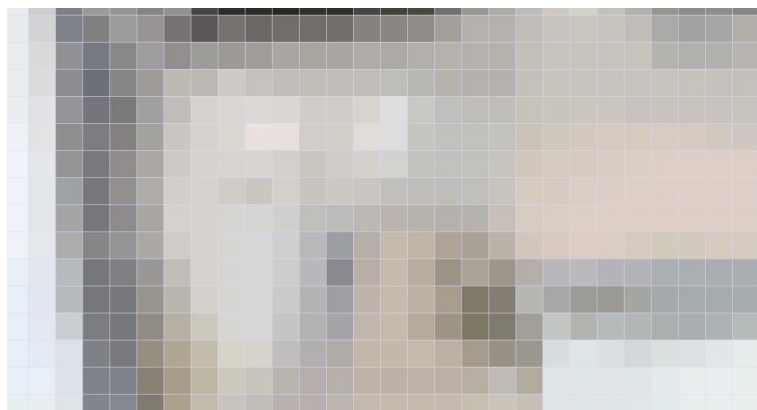
# Object-based image analysis (OBIA)



Stefan Lang et al 2018

# Object-based image analysis (OBIA)

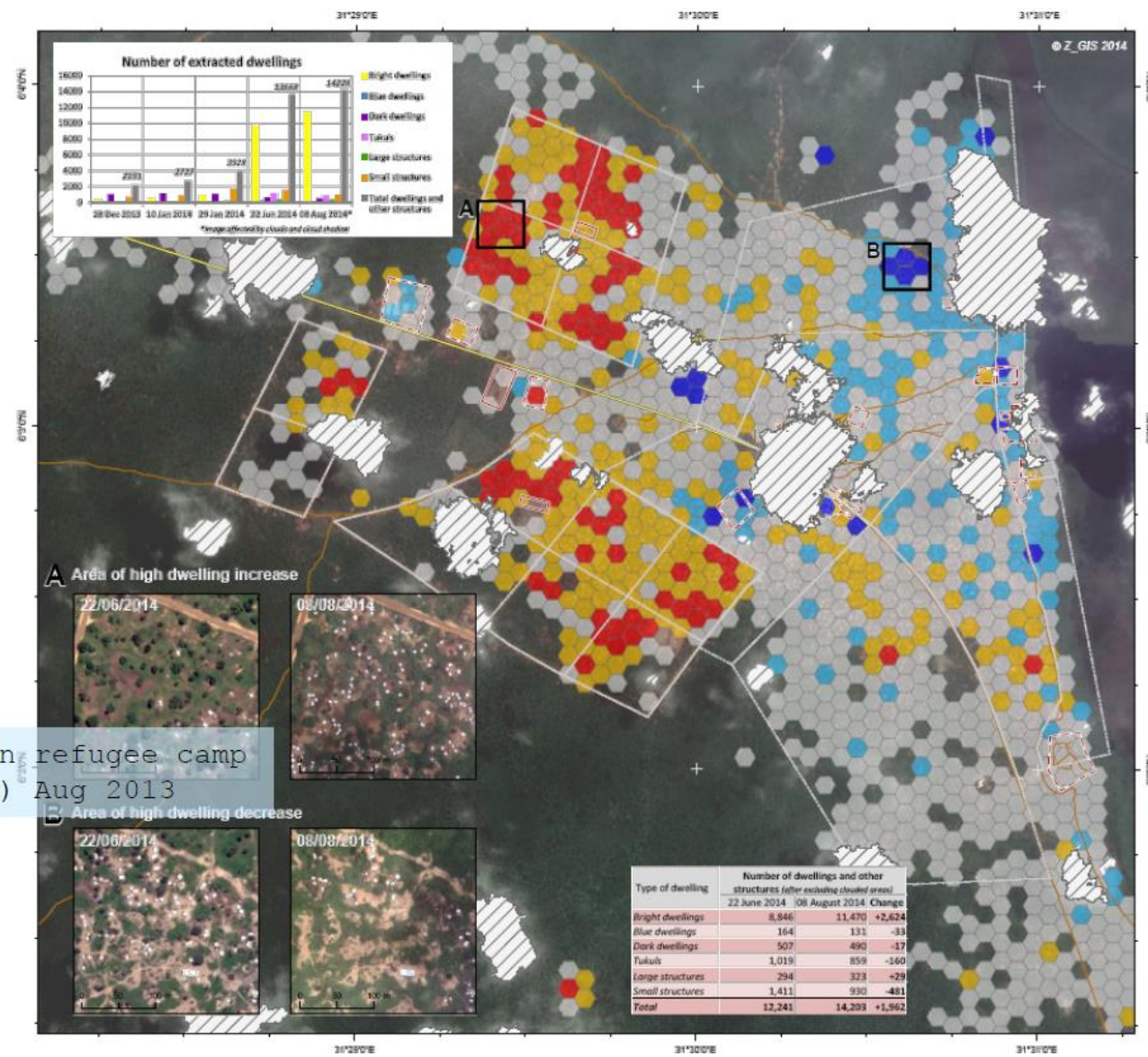
- **Spatial**, temporal and semantic relationships
- Prior **knowledge** about the scene
- Change in **vocabulary** (semantic gap):
  - Pixel values → Semantic concepts
  - Location, amount, size, ... of objects



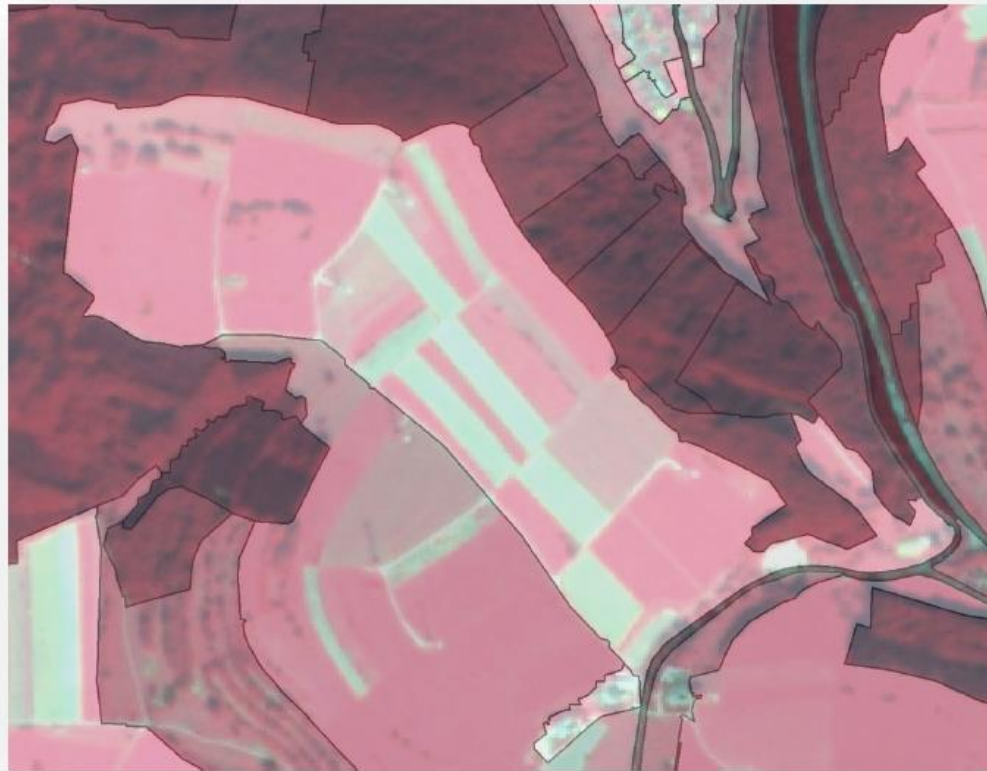
# Object-based image analysis (OBIA)

- Some of the **benefits** leading to a greater expressivity of analyses
  - Location
  - Count
  - Area / size
  - Composition
  - Begin / end
  - ...

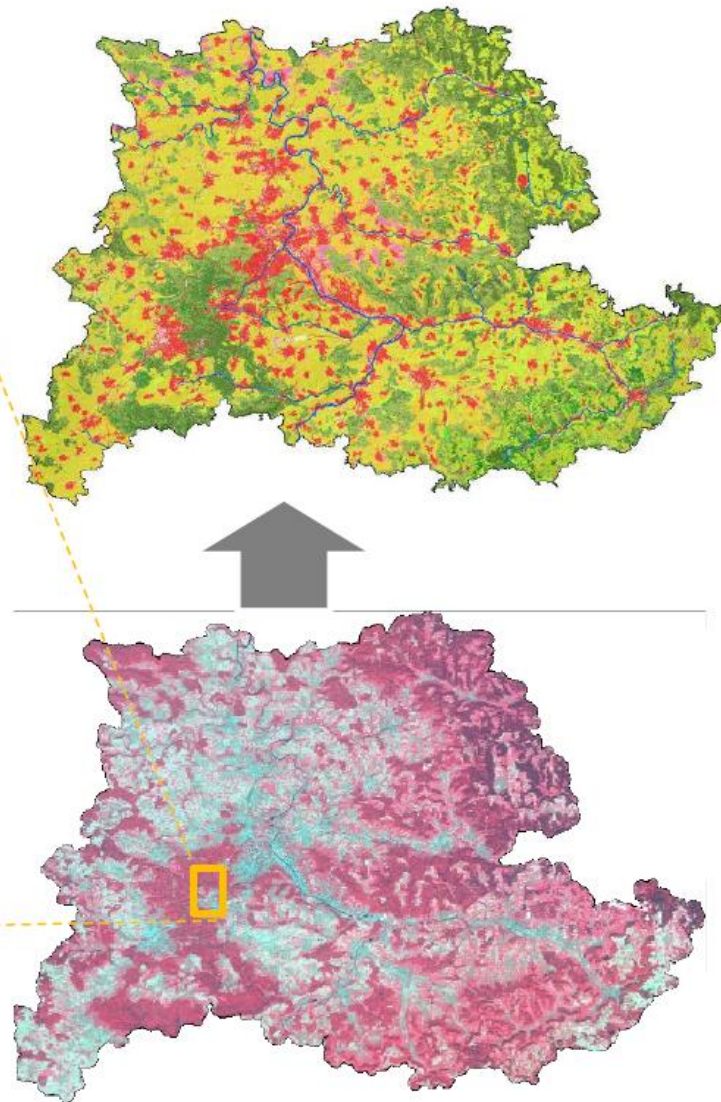
Population density in refugee camp Minkaman (South Sudan) Aug 2013



# Delineating image objects



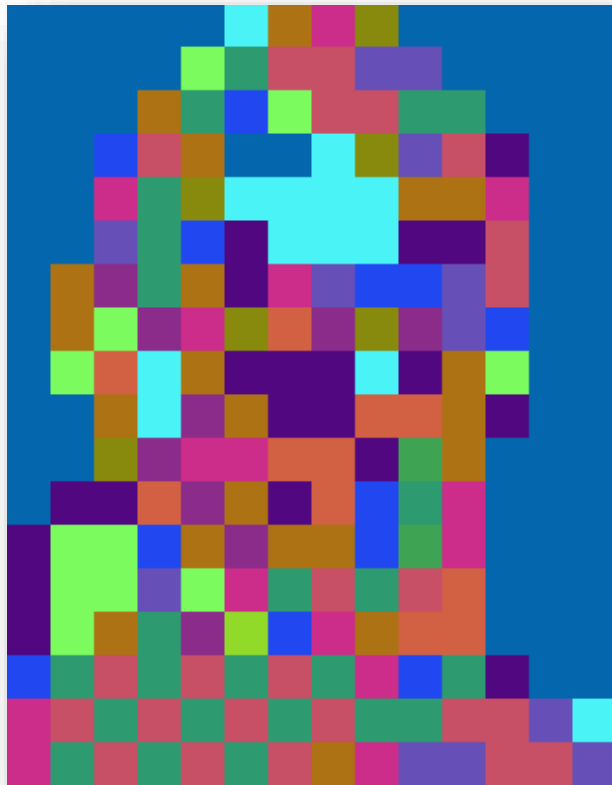
highly aggregated information on  
biotope complexes incorporating  
and refining cadastral boundaries



Lang, 2013  
Lang & Tiede, 2018

# Delineating image objects

- Luckily, there is **spatial auto-correlation** \*...



```
ncols 14
nrows 18
xllcorner 1000
yllcorner 1000
cellsize 10
nodata_value -9999
240 240 240 240 240 210 90 80 140 240 240 240 240 240
240 240 240 240 160 20 10 10 40 240 240 240 240
240 240 240 90 20 110 160 10 10 20 20 240 240 240
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190 160 90 20 70 255 110 80 90 130 130 240 240 240
110 20 10 20 10 20 10 20 80 110 20 190 240 240
80 10 20 10 20 10 20 10 20 10 10 40 210
80 20 10 20 10 20 10 90 80 40 40 10 10 40
```

←  
It's not just about  
grouping the **same**  
values

→  
It's about grouping  
**similar** values!

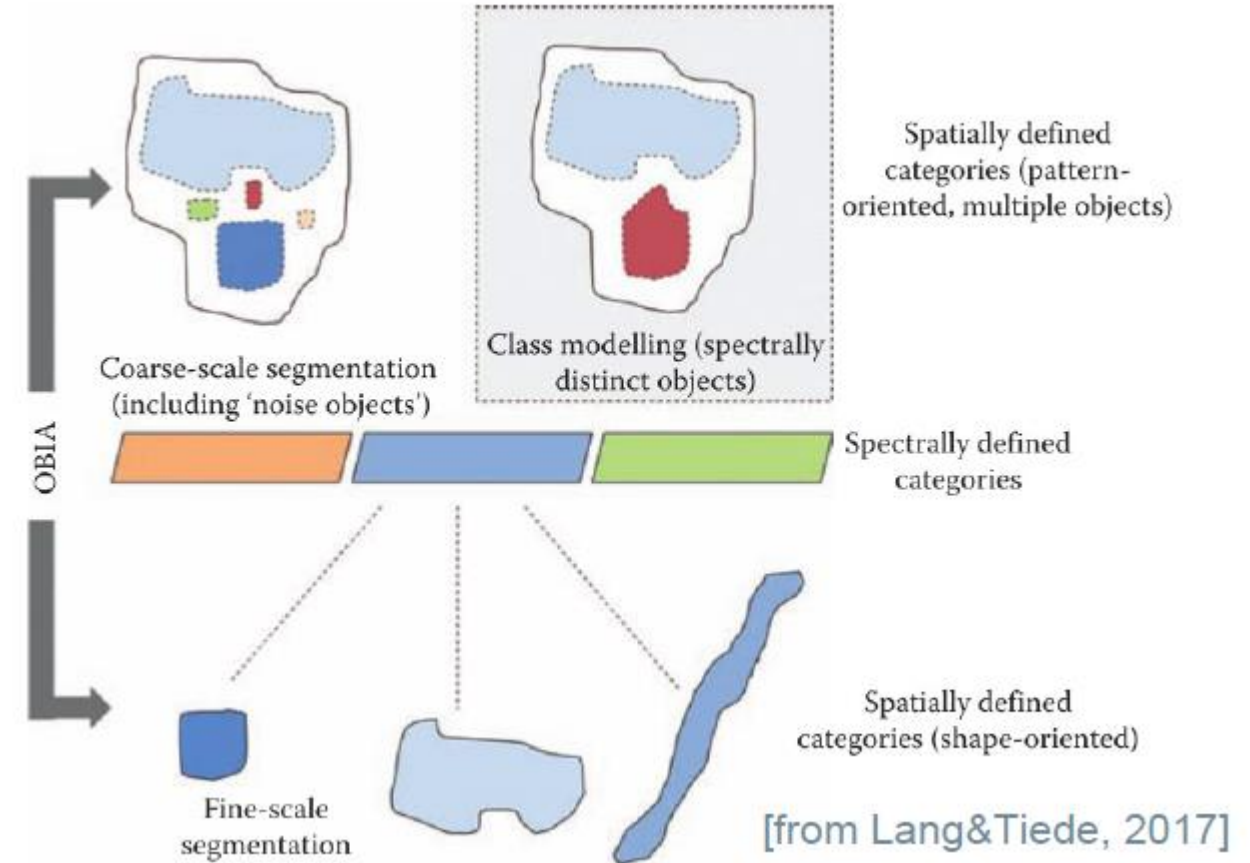


\* *The so-called 1<sup>st</sup> Law of Geography that closer things tend to be more similar than distant ones*

Stefan Lang et al 2018

# General approach

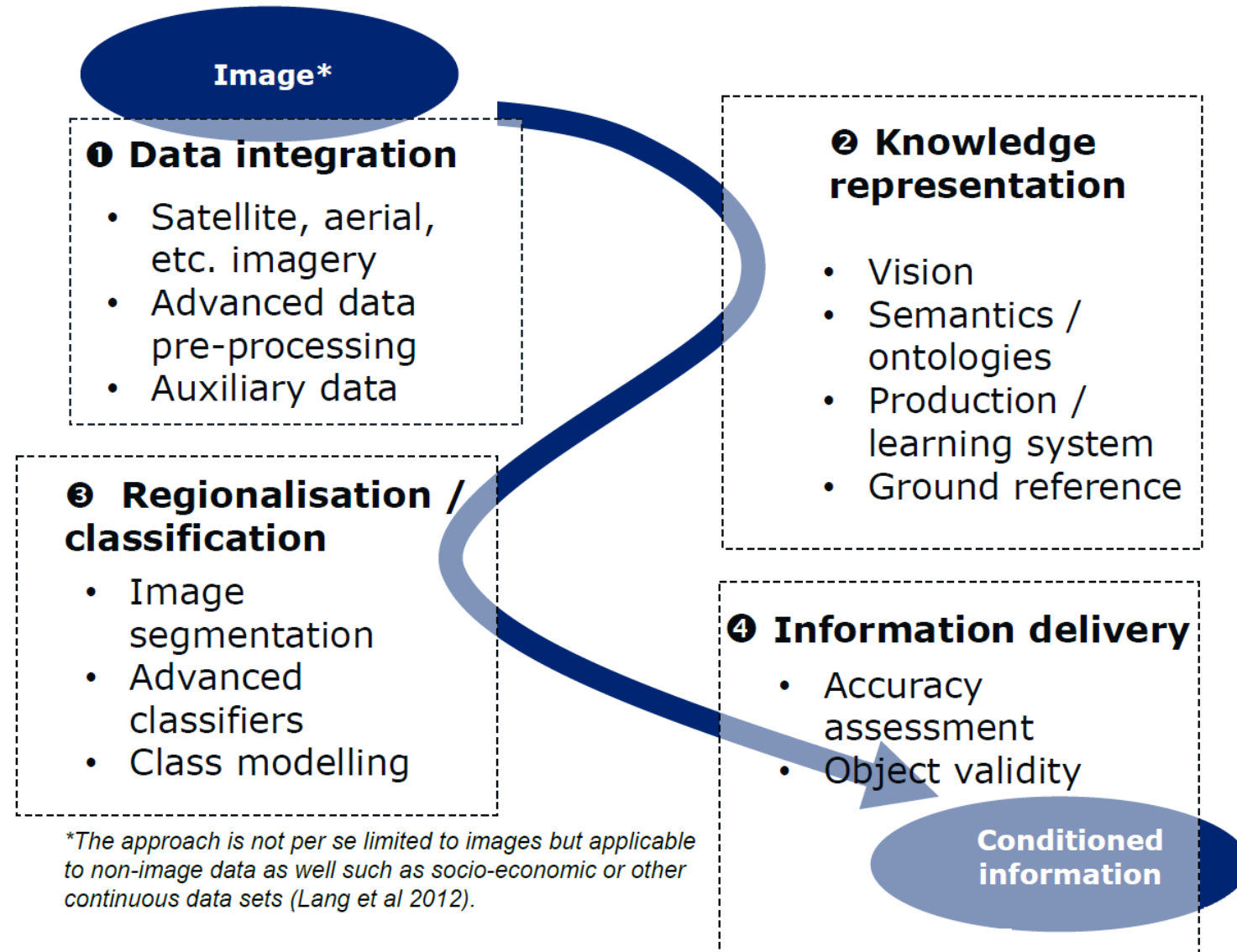
- regionalization techniques for **image segmentation**
  - "a trade-off" between spectral and spatial similarities
  - (scalable) generalization
  - reduction of the so-called salt-and-pepper effect
- explicit **focus on objects and their relationships**
  - address and model new dimensions of target classes
- offers the possibility to **include expert knowledge** in rule-sets or semantic networks



Lang, 2013

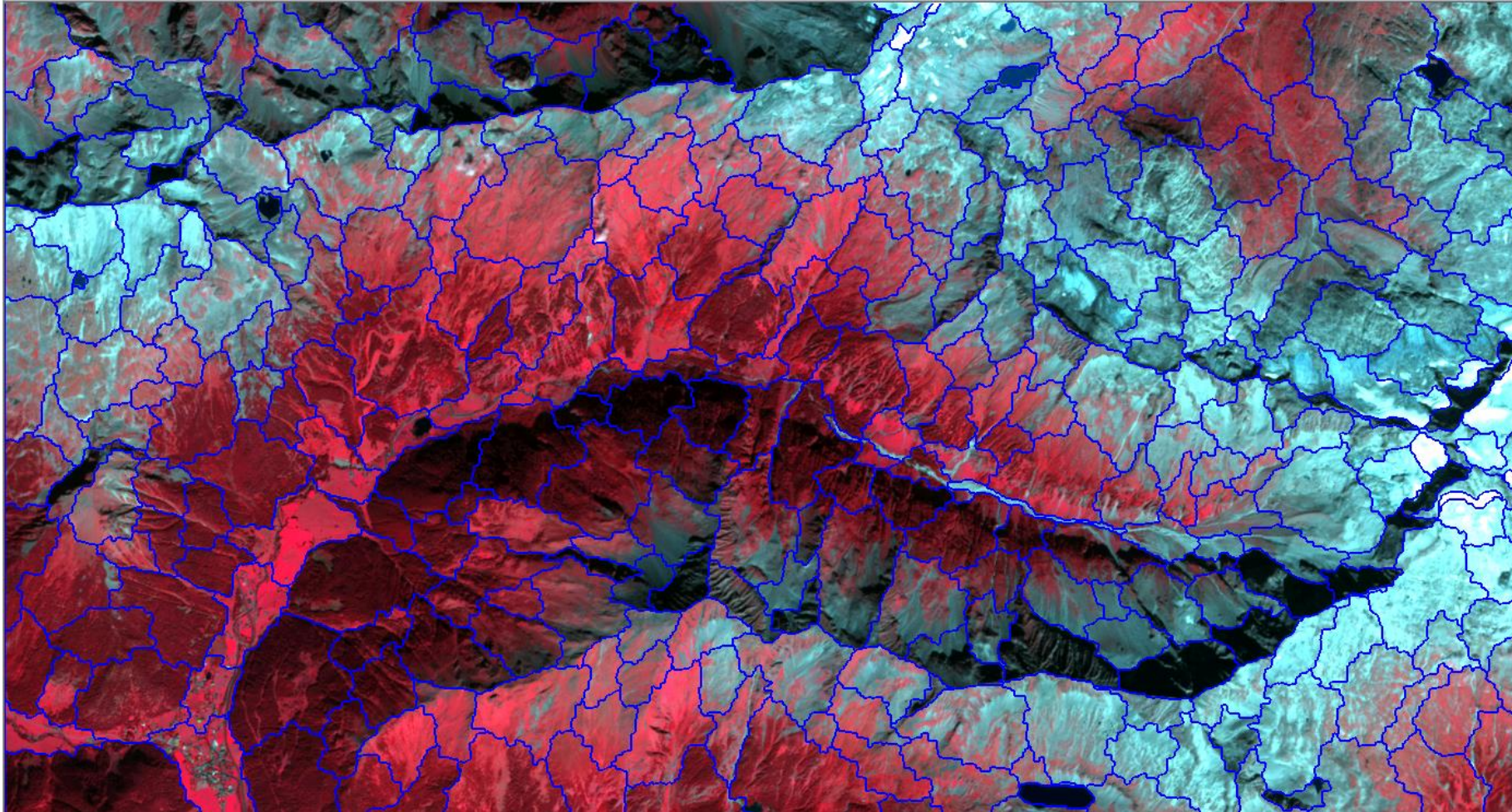
Lang & Tiede, 2018

# Typical workflow



Lang, 2013  
Lang & Tiede, 2018

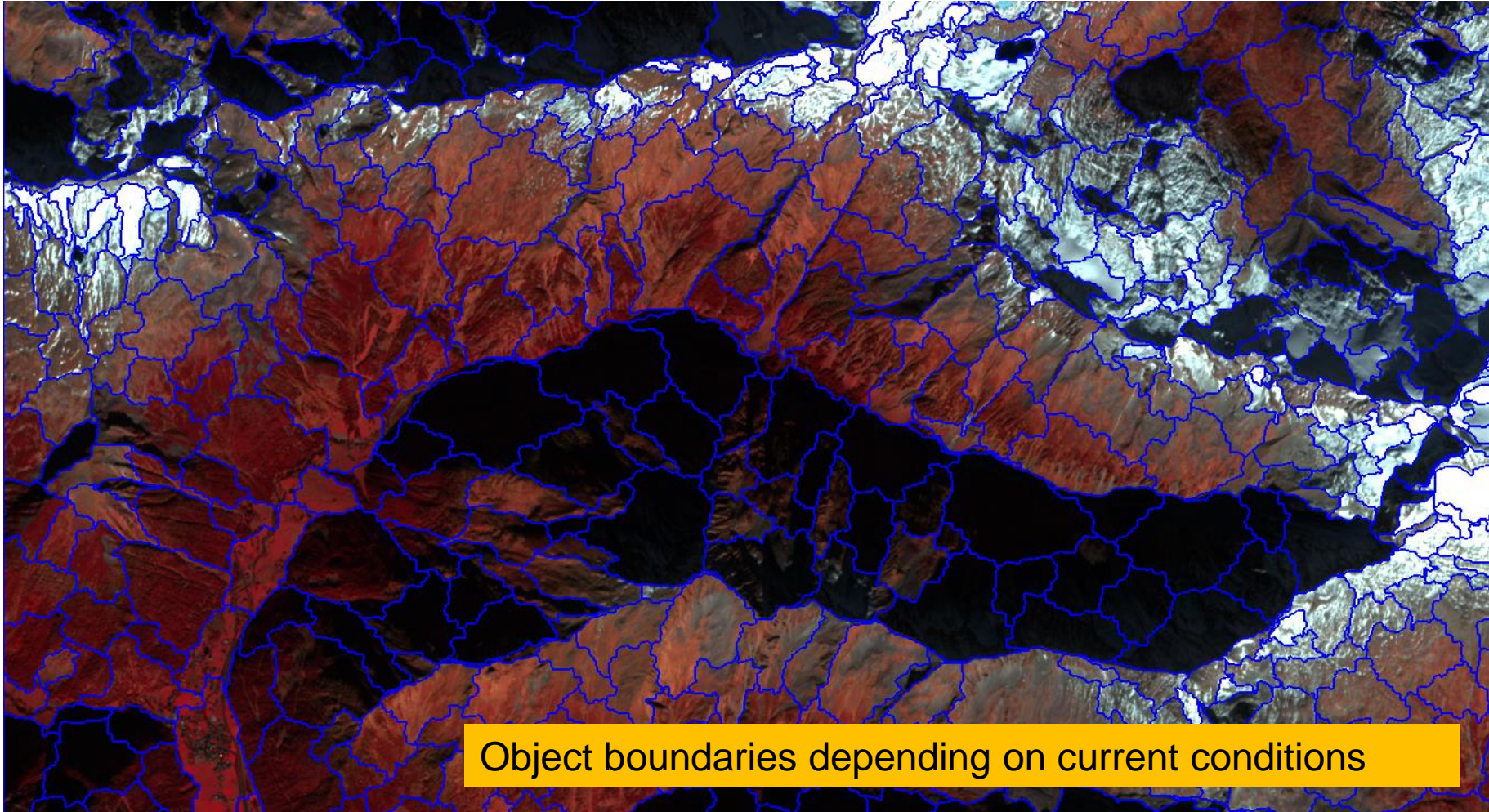
# Object delineation problems



Aug 2017

Stefan Lang et al 2018

# Object delineation problems

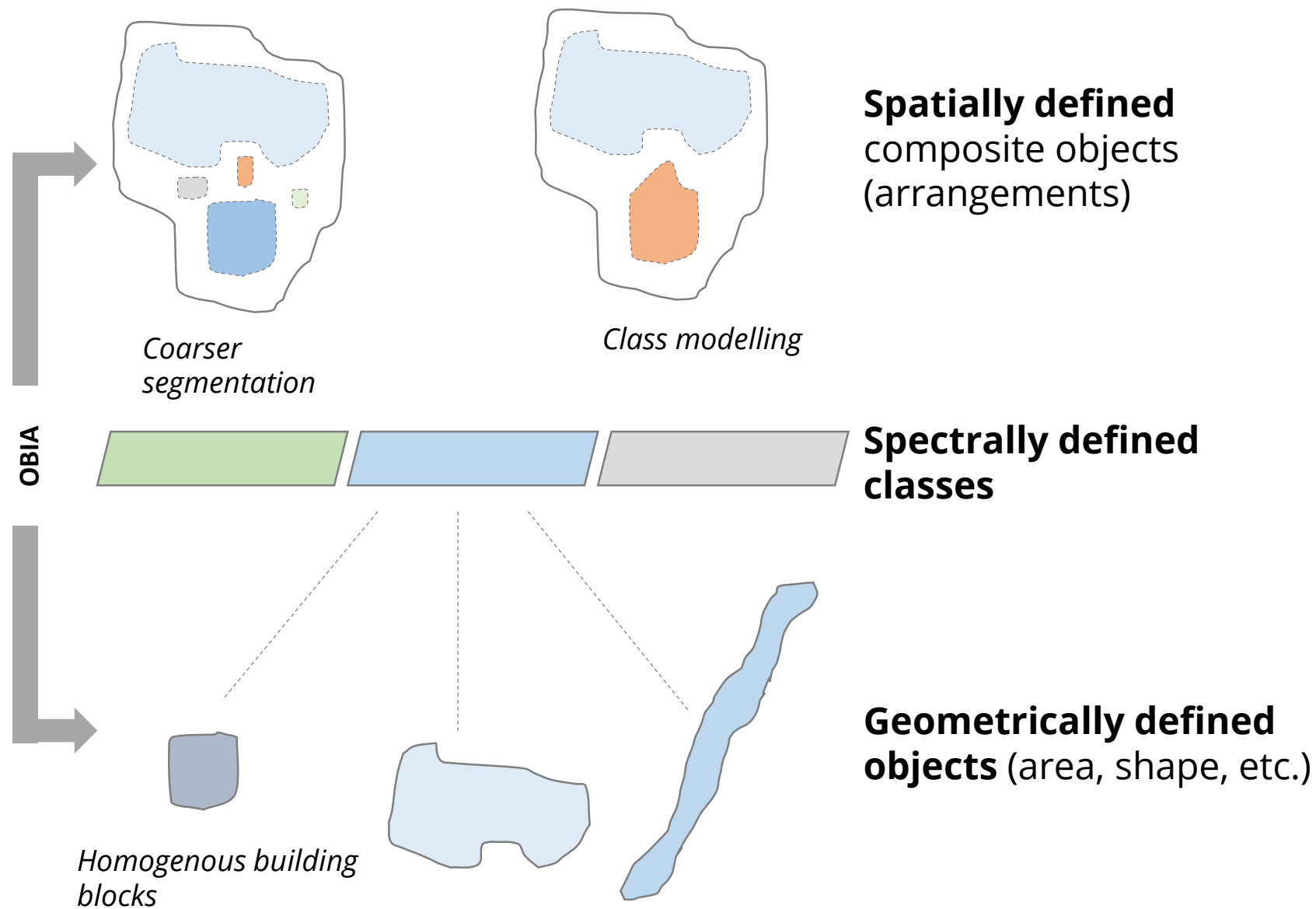


Oct 2017

Object boundaries depending on current conditions

Stefan Lang et al 2018

# Object delineation problems



Stefan Lang et al 2018