

10TH ADVANCED TRAINING COURSE ON LAND REMOTE SENSING



UAV - Microdrones and Multispectral sensing
Matjaž Čater, Slovenian Forestry Institute

ESA UNCLASSIFIED – For ESA Official Use Only



→ THE EUROPEAN SPACE AGENCY

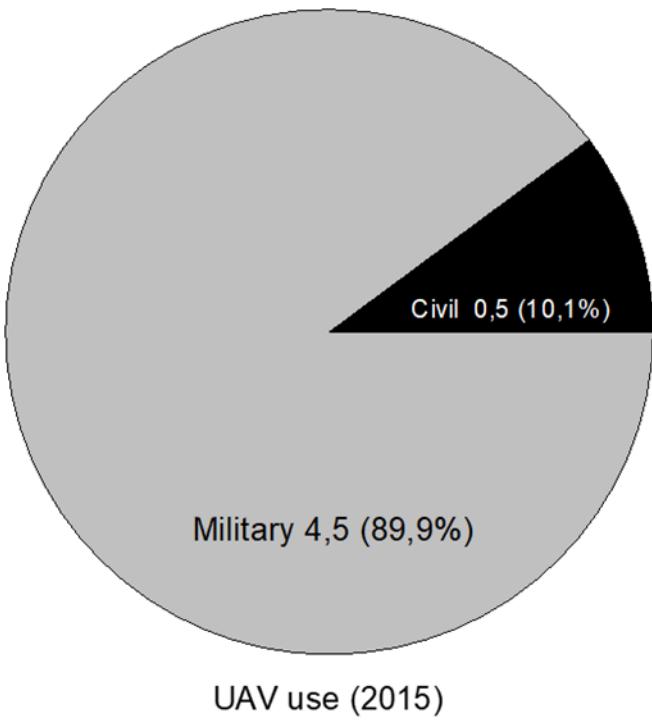
MD4-1000



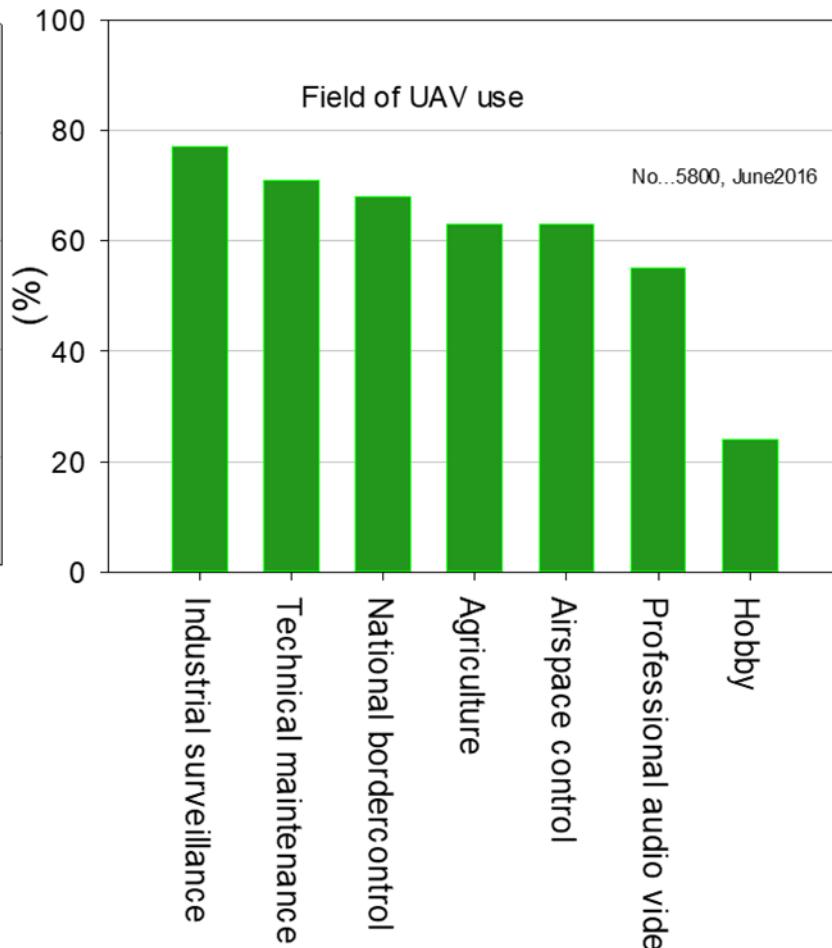
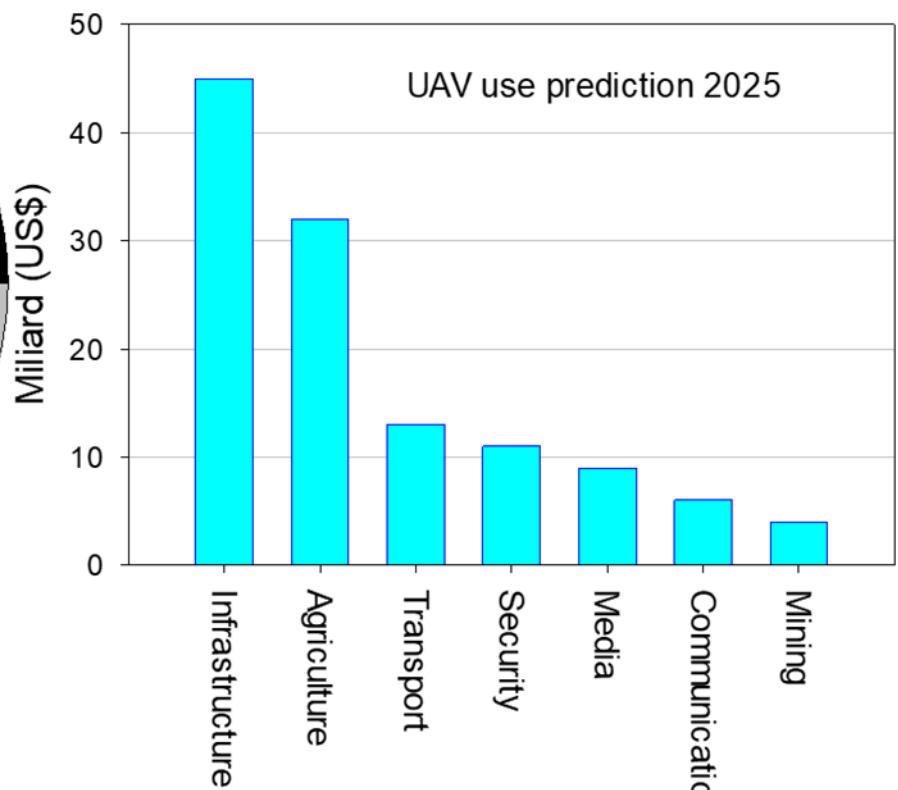
UAV IN FOREST RESEARCH

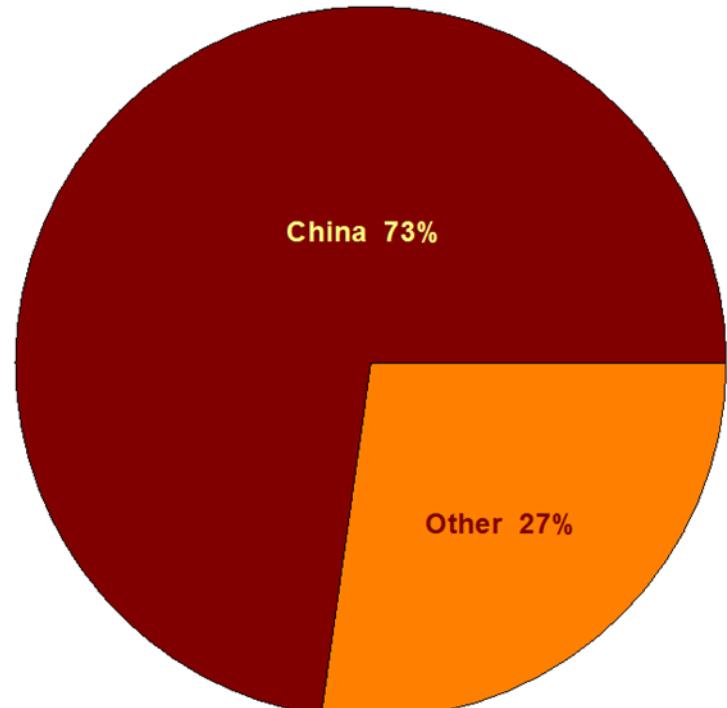
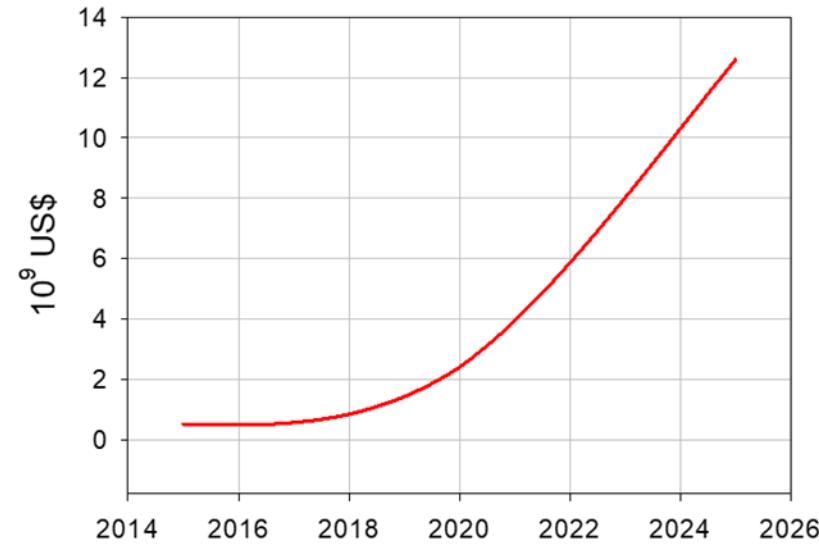
- General features
- Micasense RedEdge

Slovenian Forestry Institute, September 2021



Handelsblatt 2017, 12. Jan





Proportion of UAV origin (2015)

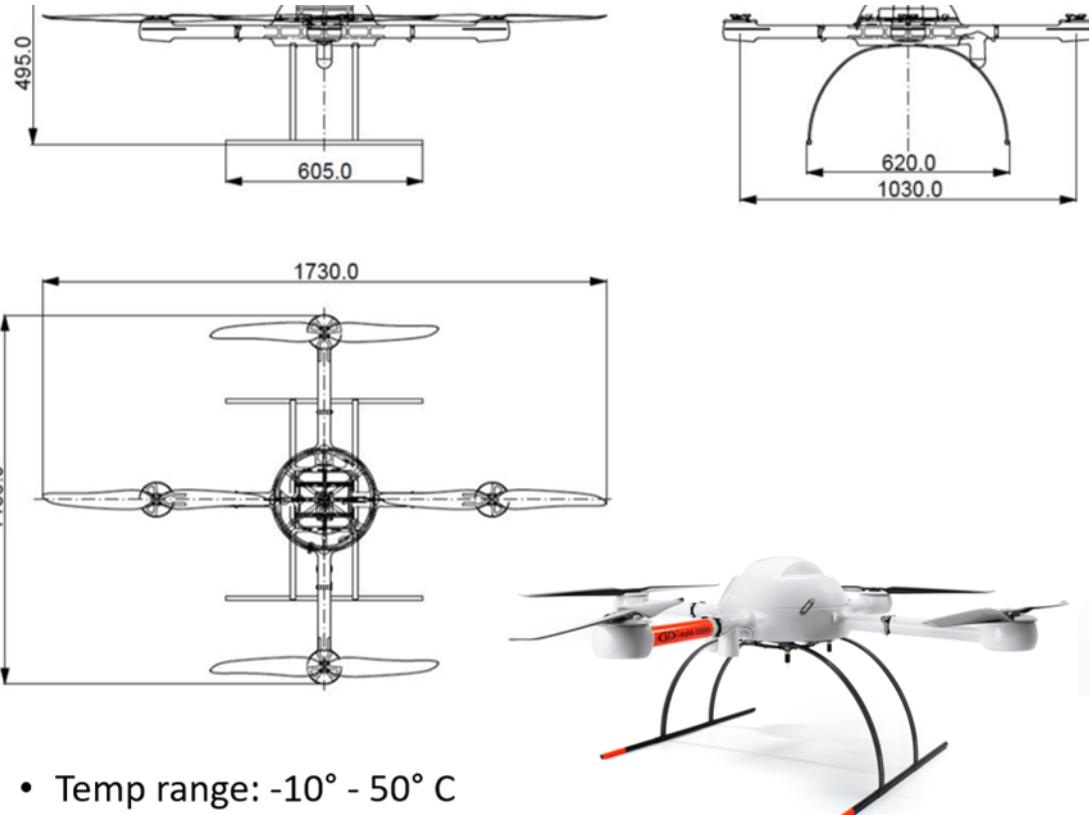
ESSENTIALS

- UAV
- Remote control
- Payload
- Base station
- Batteries



TECH. SPECIFICATION

- UAV mass: 2650 g
- Optimal payload: 800 g
- Max payload: 1200 g
- MTOW: 5000 g
- Battery: 6S2P LiPo 22,2V / 14,6Ah
- Ascending speed: 7.0 m/s
- Max. oper. velocity: 12 m/s
- Radius: 1000m/RC; 30km WP
- Temp range: -10° - 50° C
- Max air humidity: 90% RH
- Max wind speed: 12 m/s
- Optimal tolerable windspeed: 6 m/s
- Plafon: 2000 m ASL
- Max ASL: 4000m ASL (WGS 84)
- Max autonomy: 45 min

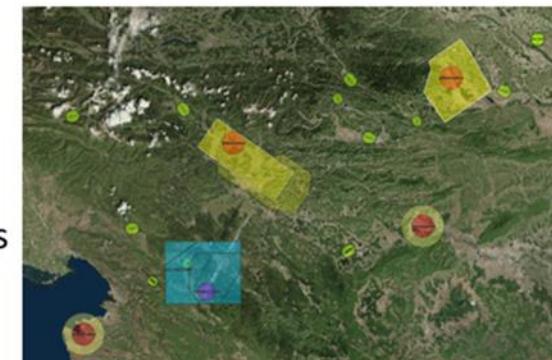


WEATHER RESTRICTIONS (UAV*)

- Frost => compromised rotor airfoil, loss of lift
- T < -10° C ; > 50° C
- Windspeed / gusts or constant conditions > 12 m/s
- Rapid weather changes (pressure changes - barometer)
- Turbulence (vicinity of objects/ obstacles)
- Precipitation IP43 standard :
 - “4” ... airdrop diameter above nad 1mm
 - “3” ... precipitation (60° angle from vertical)

LEGISLATION & AIRSPACE (CAA)

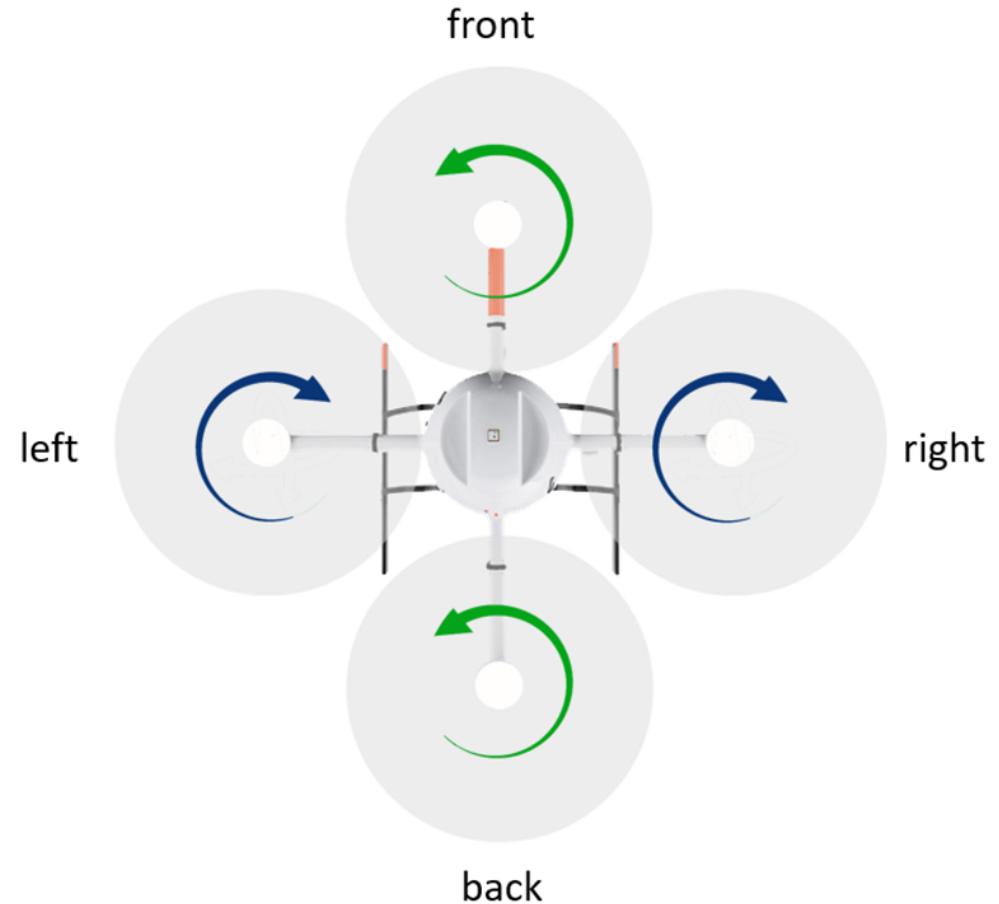
- Registration – several categories: mass/ op. area
- Insurance
- Flight announcement
- 500m from the takeoff, constant visual contact
- Obstacles (terrain, inhabited areas, powerlines...)
- Max 150m above ground
- 50 m (within CTR)
- Restricted: r= 5 km around airports
- Observe NOTAM



<http://www.caa.si/index.php> => UAV

BASICS

- Quadrocopter principle; rotors providing lift
- Torque is equalized
- Control provided by increasing/ decreasing thrust(RPM)
- Pilot controls 3 axes + alternating thrust by remote control



FNC: FLIGHT & NAV. CONTROLLER

- Maintaining UAV inflight stability
- Calculating flight and navigation parameters
- Executing guidance and emergency functions
- Control of UAV subsystems
- Temperature sensitivity
- Ambiental acclimatization (T) 12-15 min.



SENSORS



The Inertial Measurement Unit (IMU):

accelometer

gyroscope (angular velocities, roll & pitch)



Barometer

air pressure and temperature (determination of height)

Sonar

Automatic landing



Magnetometer

magnetic field



GNSS

GPS receiver

3D UAV location, navigation

REMOTE CONTROL (RC)

- Connection with UAV receiver
- In-flight real time telemetry



BASE STATION

- Telemetry display UAV
- Task planning UAV
- Task update UAV
- Data recording (optional)



BATTERY

LiPo cells.

Proper handling & care

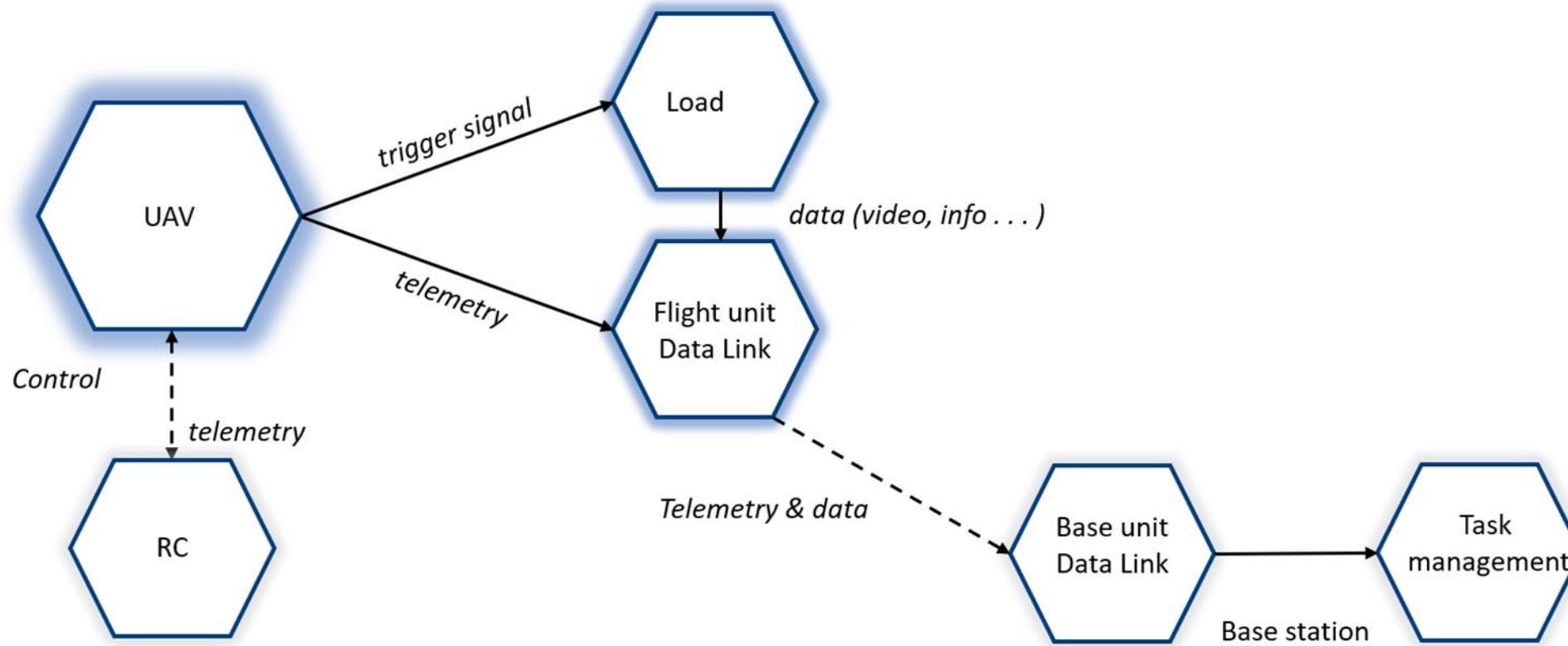
High power/ weight ratio

Lifetime: several 1000 charging cycles



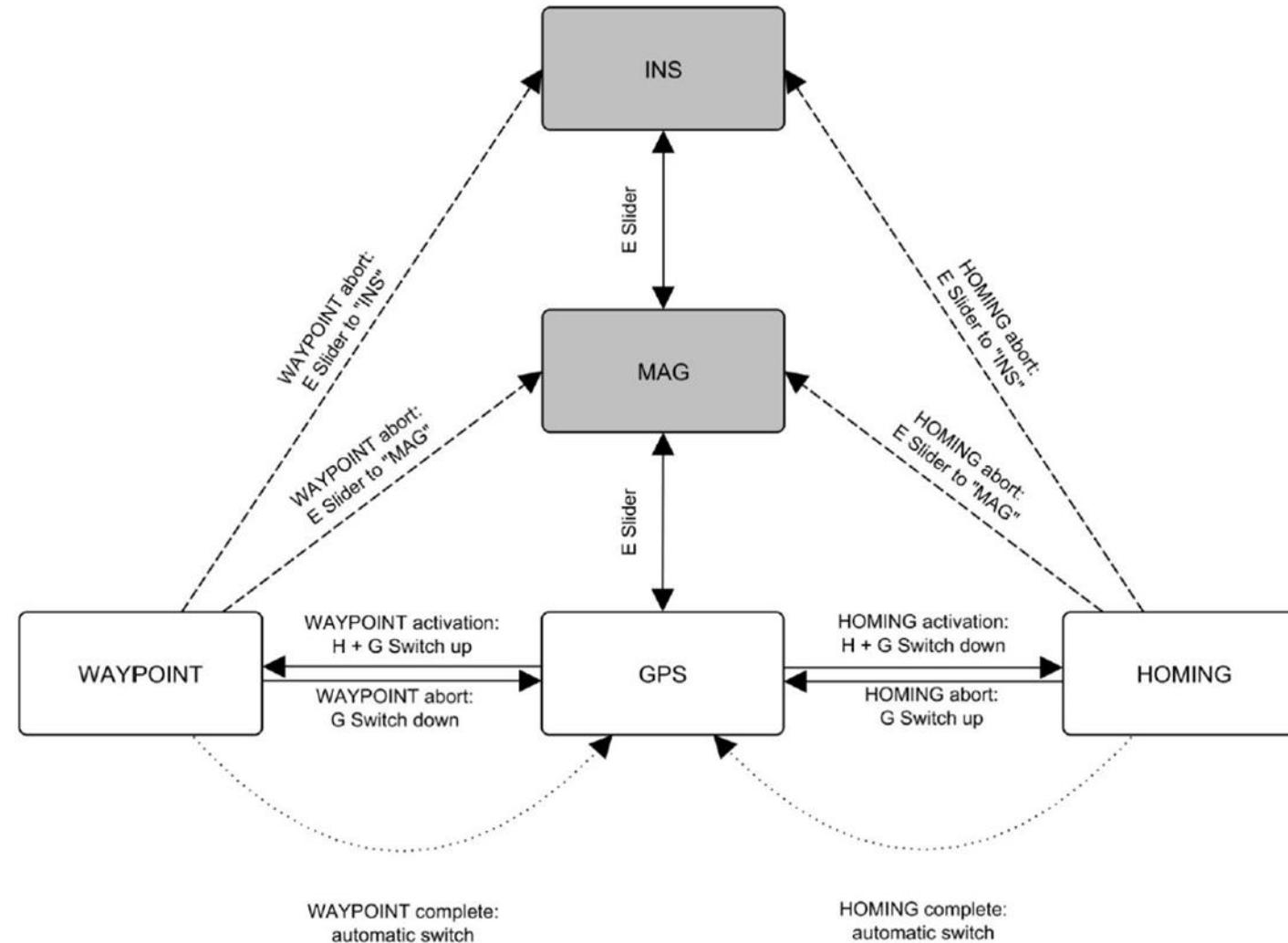
Max voltage	25.2 V
Min. voltage	22.4 V
Critical ₁	22.2 V (homing)
Critical ₂	21.7 V (auto landing)
Cell No	12
Temperature range	10° C - 40° C
Mass	1900 g
Charging time:	45 - 90 min

FUNCTION SCHEME



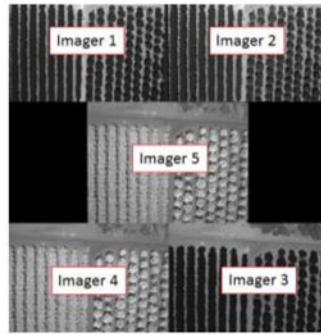
WAYS OF CONTROL

- GPS
- MAG
- INS
- WAYPOINT
- HOMING



MULTISPECTRAL SENSING

- Vigor and health of crops/ vegetation
- Micasense RedEdge™ 3
- Capture of five discrete spectral bands
- Global shutter: more images per time unit
 - higher resolution
 - clear images in spite of short exposition times



- UAV
- Micasense RedEdge™ camera
- UAV housing with:
 - Light sensor (DLS)
 - GPS receiver
- SD memory card
- MicaSense calibration pane (CRP)

Spectral bands:

1. blue (465 – 485nm) $\Delta = 20$ nm
2. green (540 – 580nm) $\Delta = 20$ nm
3. red (658 – 678nm) $\Delta = 10$ nm
4. red edge (707 – 727nm) $\Delta = 10$ nm
5. Near IR (800 – 880nm) $\Delta = 40$ nm

Speed: 1 exposure/s

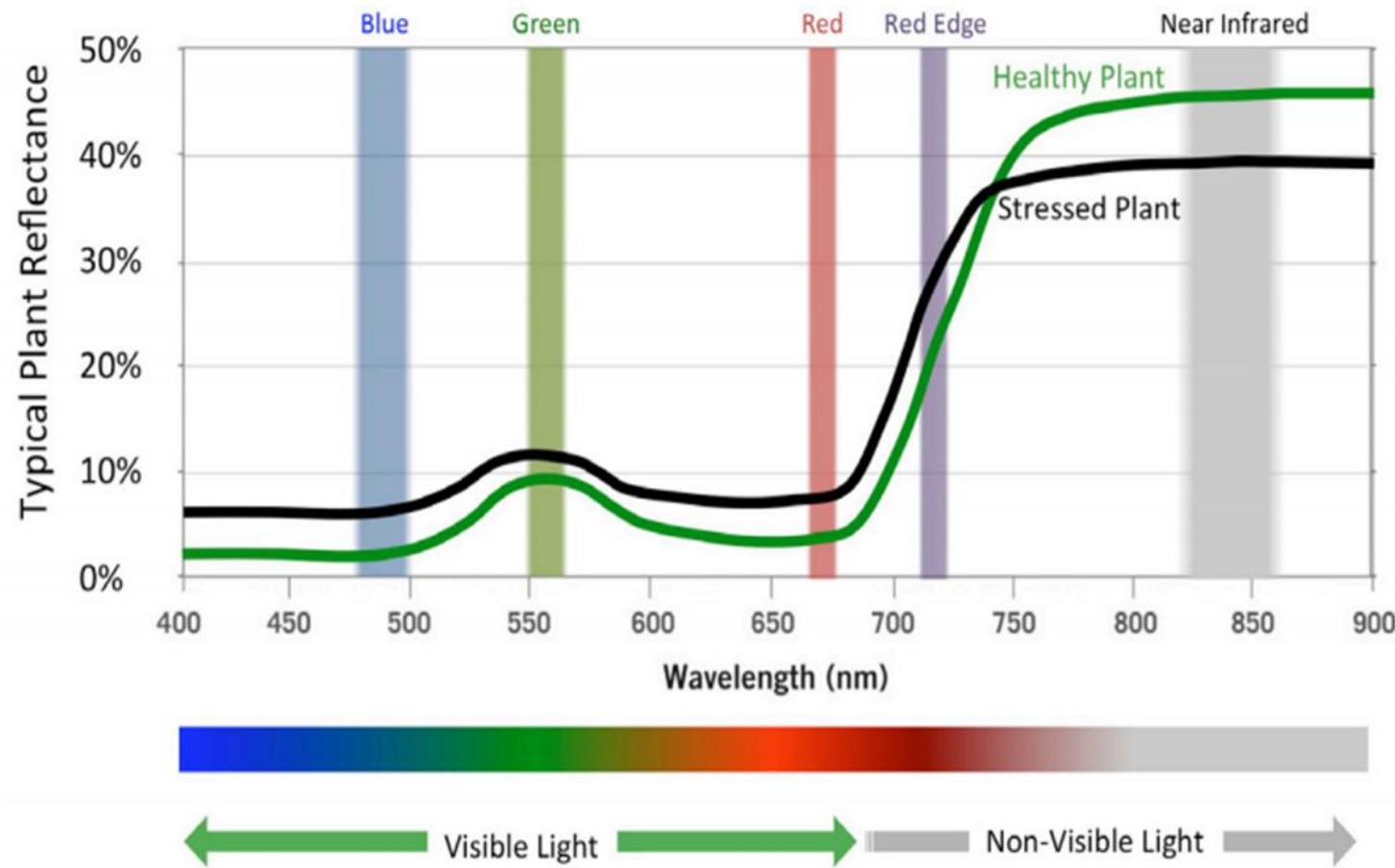
Functioning UAV, 5.0 V DC, 4 W nominal

mass: 150 g camera

50 g gimbal

60 g TCQM + GPS + DLS

Dimensions: 121 x 66 x 46 mm



POSITIONING



MICASENSE REEDGE GSD

SENSOR RESOLUTION 1.2 MEGAPIXELS

ALT m.	GSD cm/pixel
30	2.1
60	4.1
90	6.1
120	8.2



GSD... Ground sampling distance

UAV COVER (TCQM)

- Integrated GPS camera antenna
- Ambient light sensor



TCQM with GPS and DLS modules

RECORDING



PLANNING

Aplication md Cockpit / tablet

Definition of:

- takeoff
- starting / ending task point
- polygon
- optimisation / obstacles
- Recording parameter setting
- UAV parameter setting
- UAV task upload

RECORDING

UAV assembly
UAV activation

GPS coverage check
Telemetry check
Camera activation
Reflectance panel recording

Takeoff
UAV positioning, visual contact
Task execution
Task ending

Landing
UAV deactivation

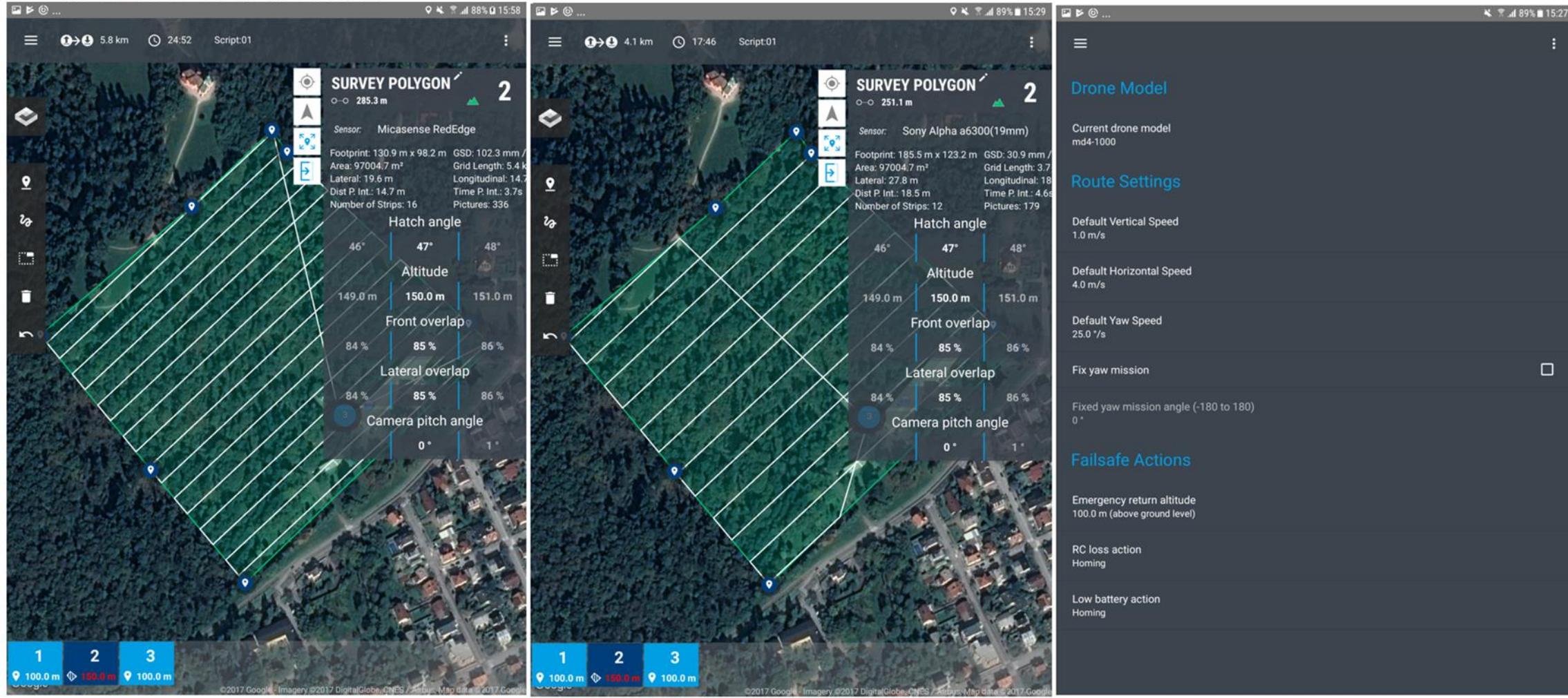
TRANSFER

Data transfer
SD card => PC
Check

ANALYSIS

Agisoft pro

TASK PLANNING



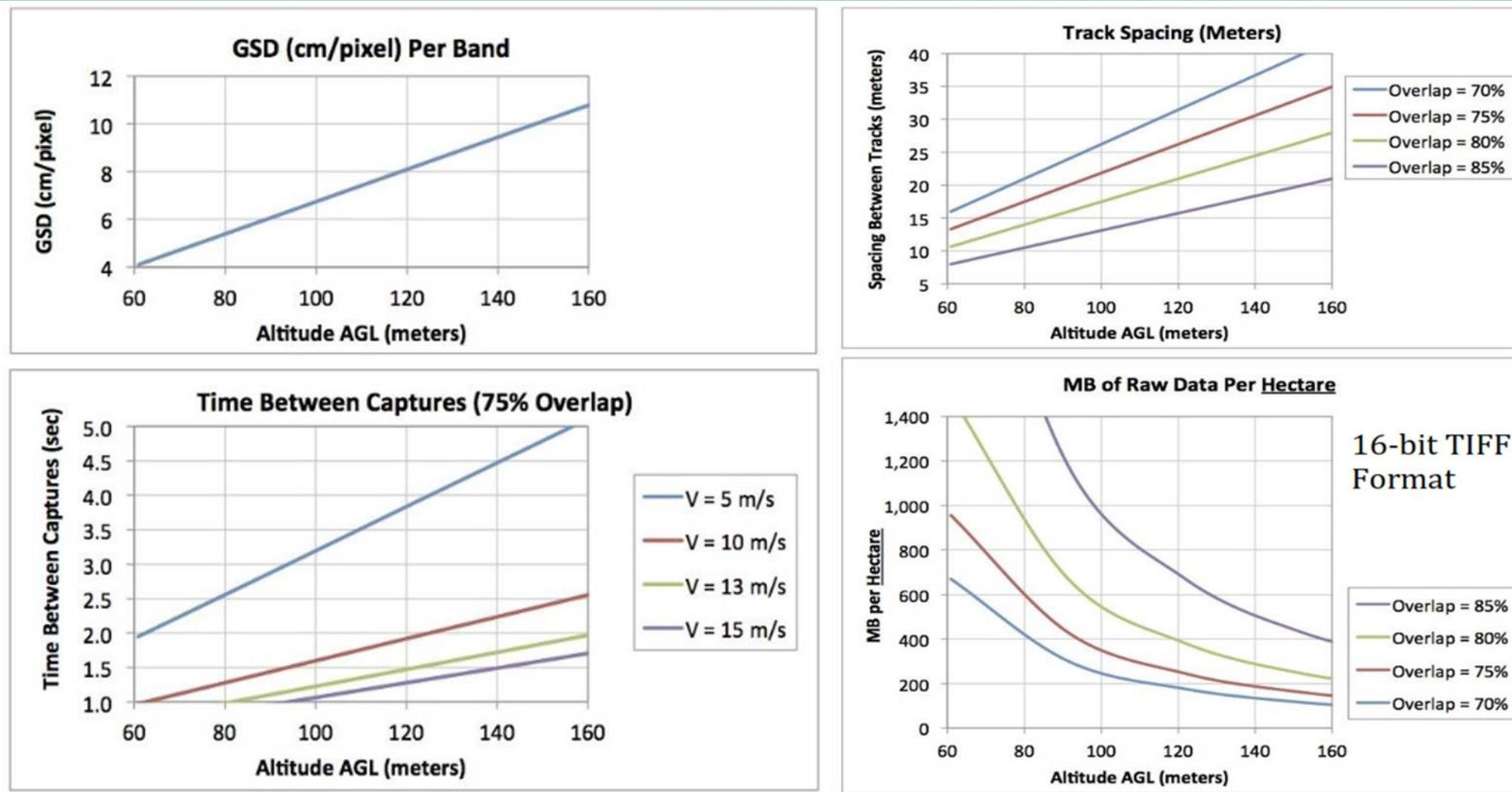
Battery - duration

Terrain - highest polygon point
image quality

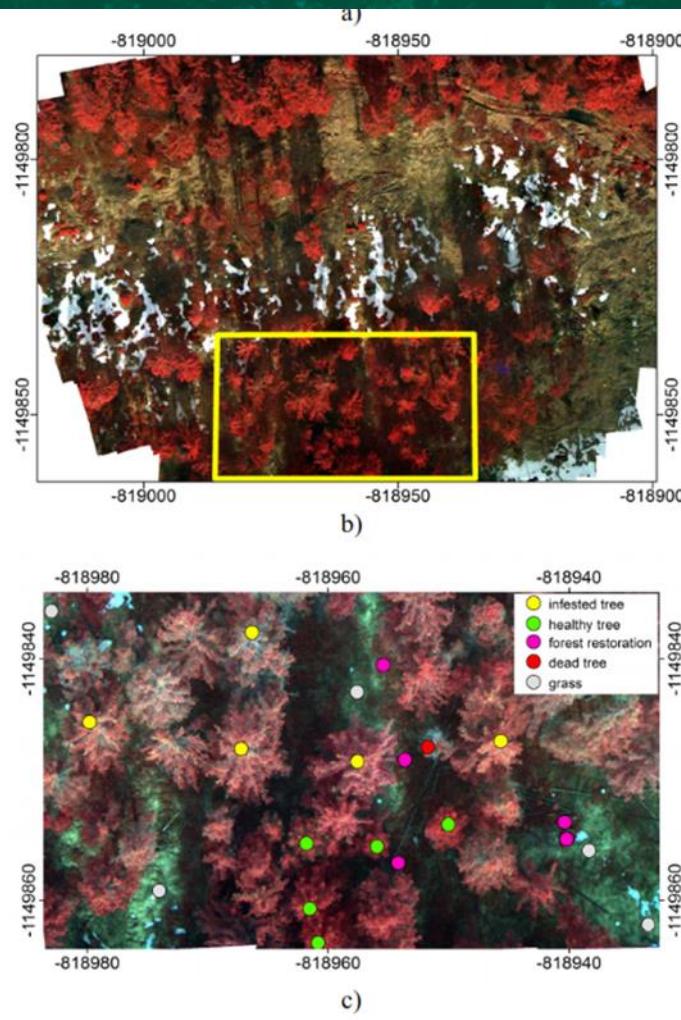
=> recording area

=> recording speed

=> overlapping %



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Minarik & Langhammer, 2016

Index	Formula	Reference
Greenness Index	$\frac{green}{red}$	Le Maire et al. (2004)
Simple ratio (SR) 800/550	$\frac{NIR}{green}$	Le Maire et al. (2004)
Simple ratio 800/650 Pigment specific SR B1	$\frac{NIR}{red}$	Blackburn (1998)
Datt 2	$\frac{NIR}{red_edge}$	Datt (1999)
NDVI	$\frac{NIR - red}{NIR + red}$	Tucker (1979)
Green NDVI	$\frac{NIR - green}{NIR + green}$	Gitelson and Merzlyak (1997)
Red-edge index (NDRE)	$\frac{NIR - (red_edge)}{NIR + (red_edge)}$	Barnes et al. (2000)
Red-edge Green NDVI	$\frac{(red_edge) - green}{(red_edge) + green}$	Buschmann and Nagel (1993)
Red-edge NDVI	$\frac{(red_edge) - red}{(red_edge) + red}$	Ortiz et al. (2013)
Anthocyanin reflectance index 2 (ARI2)	$NIR \left[\left(\frac{1}{green} \right) - \left(\frac{1}{red_edge} \right) \right]$	Gitelson et al. (2002)

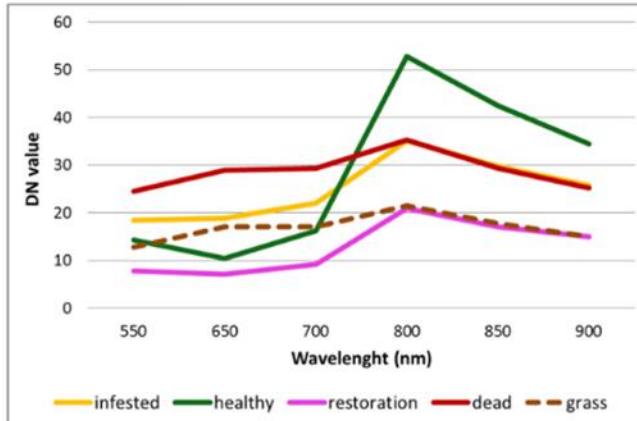
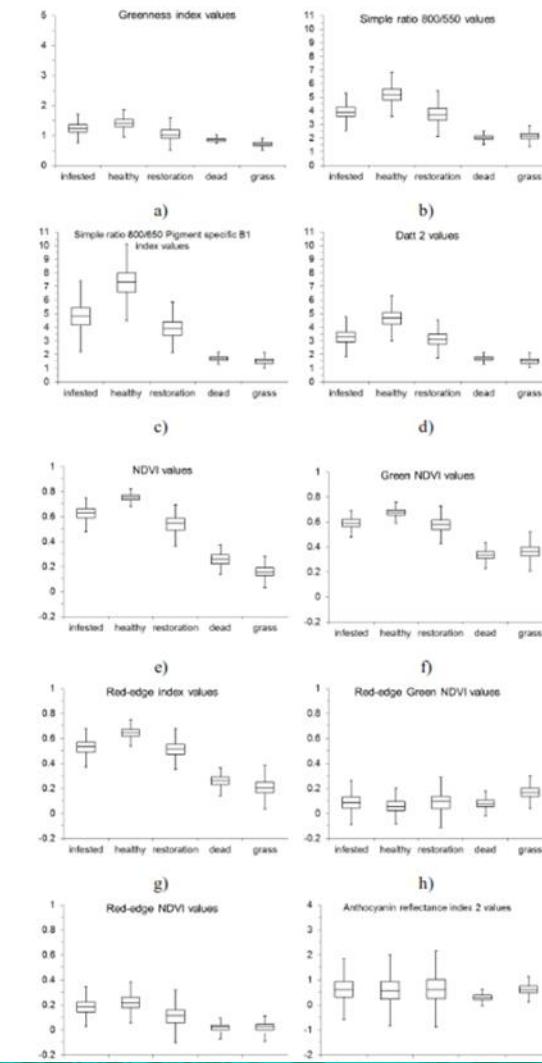
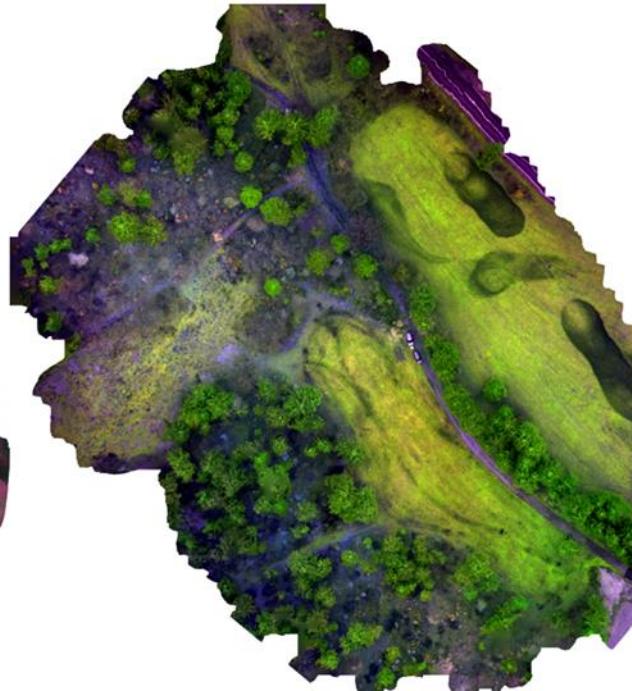
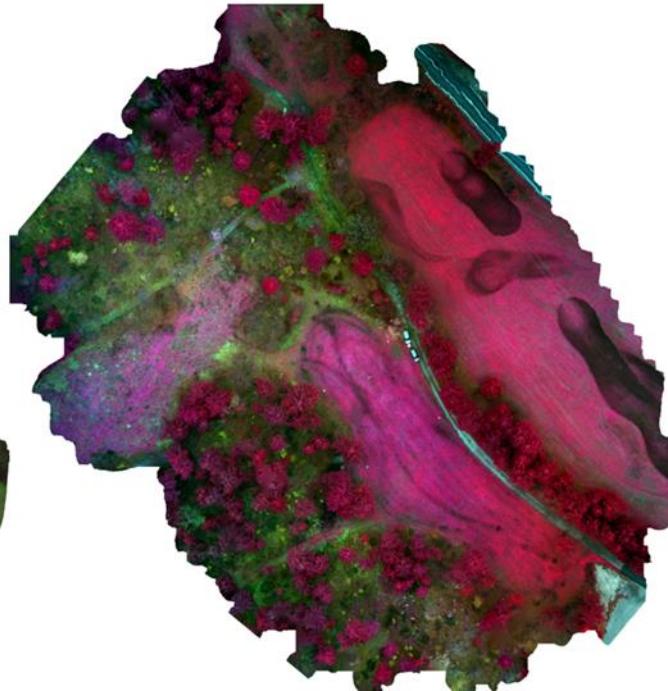
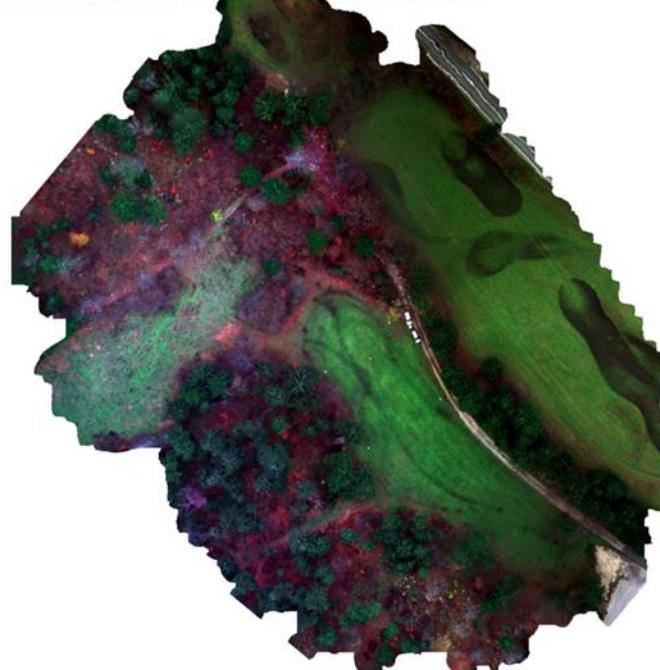
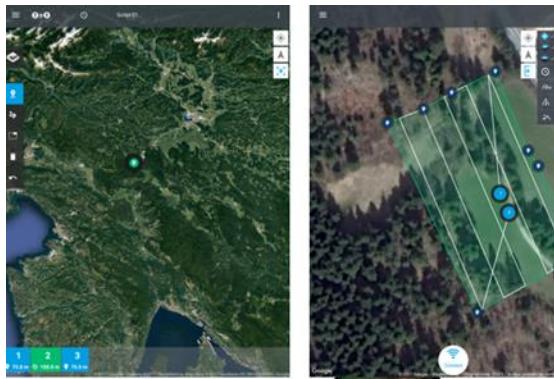


Figure 4. Average DN values of the established categories: infested trees, healthy trees, forest restoration, dead trees, and grass in the 550-900 nm spectral region.

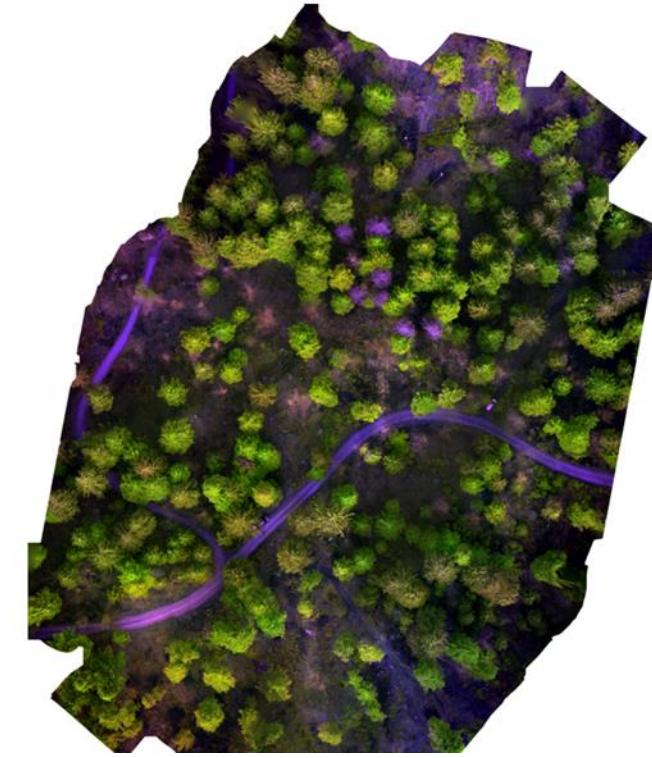
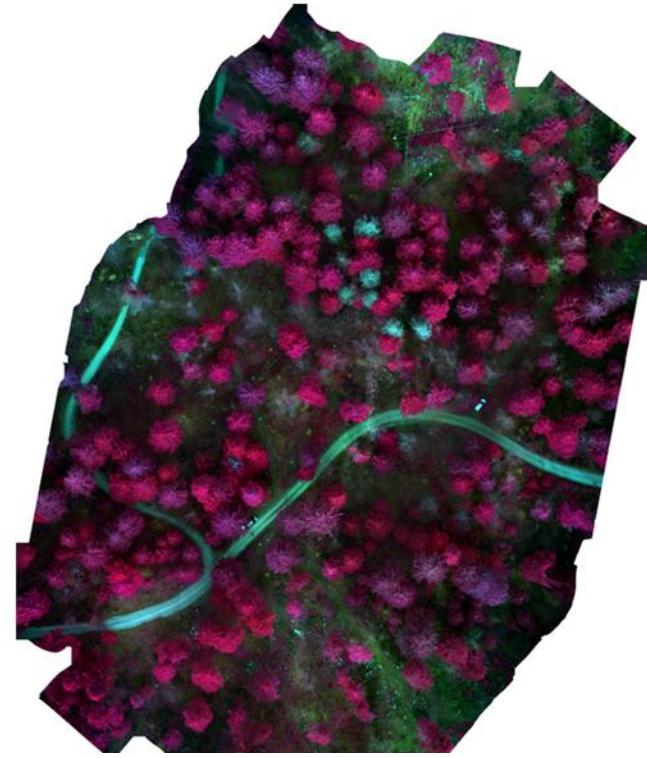
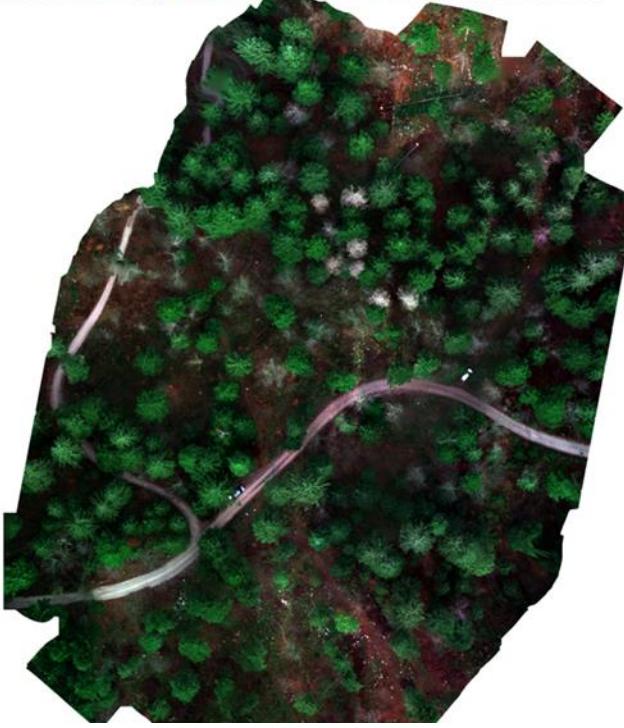
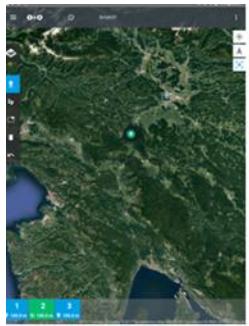


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JGS: 301001: task 2A/3



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